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PROBABILISTIC CELLULAR
AUTOMATA WITH MEMORY TWO:
INVARIANT LAWS AND
MULTIDIRECTIONAL
REVERSIBILITY

AUTOMATES CELLULAIRES PROBABILISTES
À MÉMOIRE DEUX: LOIS INVARIANTES
ET RÉVERSIBILITÉ
MULTIDIRECTIONNELLE

ABSTRACT. — Let us consider the family of one-dimensional probabilistic cellular automata (PCA) with memory two having the following property: the dynamics is such that the value of a given cell at time $t + 1$ is drawn according to a distribution which is a function of the states of its two nearest neighbours at time t , and of its own state at time $t - 1$. We give conditions for which the invariant measure has a product form or a Markovian form, and prove an ergodicity result holding in that context. The stationary space-time diagrams of these PCA present different forms of reversibility. We describe and study extensively this phenomenon, which provides families of Gibbs random fields on the square lattice having nice geometric and combinatorial properties. Such PCA naturally arise in the study of different models coming

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from statistical physics. We review from a PCA approach some results on the 8-vertex model and on the enumeration of directed animals, and we also show that our methods allow to find new results for an extension of the classical TASEP model. As another original result, we describe some families of PCA for which the invariant measure can be explicitly computed, although it does not have a simple product or Markovian form.

RÉSUMÉ. — Considérons la famille d'automates cellulaires probabilistes (ACP) de dimension un avec mémoire deux ayant la propriété suivante : la dynamique est telle que la valeur d'une cellule au temps $t + 1$ est tirée aléatoirement selon une distribution qui est une fonction de l'état de ses deux voisins les plus proches au temps t , et de son propre état au temps $t - 1$. Nous donnons des conditions pour lesquelles la loi invariante d'un tel ACP est une mesure de forme produit ou une mesure markovienne, et prouvons un résultat d'ergodicité s'appliquant dans ce contexte. Les diagrammes espace-temps de ces ACP possèdent différentes formes de réversibilité. Nous décrivons et étudions ce phénomène, qui fournit des familles de champs aléatoires de Gibbs sur la grille carrée ayant des propriétés géométriques et combinatoires remarquables. De tels ACP apparaissent de manière naturelle dans l'étude de différents modèles de physique statistique. En utilisant le point de vue des ACP, nous retrouvons des résultats portant sur le modèle à 8 sommets et sur l'énumération des animaux dirigés, et nous montrons aussi que nos méthodes permettent de trouver de nouveaux résultats sur une extension du modèle classique de TASEP. Un autre résultat original de ce travail est la description de familles d'ACP pour lesquels la loi invariante est explicite, mais n'est ni une mesure de forme produit, ni une mesure markovienne.

1. Introduction

Probabilistic cellular automata (PCA) are a class of random discrete dynamical systems. They can be seen both as the synchronous counterparts of finite-range interacting particle systems, and as a generalization of deterministic cellular automata: time is discrete and at each time step, all the cells are updated independently in a random fashion, according to a distribution depending only on the states of a finite number of their neighbours.

In this article, we focus on a family of one-dimensional probabilistic cellular automata with *memory two* (or *order two*): the value of a given cell at time $t + 1$ is drawn according to a distribution which is a function of the states of its two nearest neighbours at time t , and of its own state at time $t - 1$. The space-time diagrams describing the evolution of the states can thus be represented on a two-dimensional grid.

We study the invariant measures of these PCA with memory two. In particular, we give necessary and sufficient conditions for which the invariant measure has a product form or a Markovian form, and we prove an ergodicity result holding in that context. We also show that when the parameters of the PCA satisfy some conditions, the stationary space-time diagram presents some multidirectional (quasi-)reversibility property: the random field has the same distribution as if we had iterated a PCA with memory two in another direction (the same PCA in the reversible case, or another PCA in the quasi-reversible case). This can be seen has a probabilistic extension of the notion of *expansivity* for deterministic CA. For expansive CA, one can indeed reconstruct the whole space-time diagram from the knowledge of only one column. In the context of PCA with memory two, the criteria of quasi-reversibility

that we obtain are reminiscent of the notion of *permutivity* for deterministic CA. Stationary space-time diagrams of PCA are known to be Gibbs random fields [GKLM89, LMS90]. The family of PCA that we will describe thus provide examples of Gibbs fields with i.i.d. lines in many directions and nice combinatorial and geometric properties.

The first theoretical results on PCA and their invariant measures go back to the seventies [BGM69, KV80, Vas78], and were then gathered in a survey which is still today a reference book [TVS⁺90]. In particular, it contains a detailed study of binary PCA of memory one with only two neighbours, including a presentation of the necessary and sufficient conditions that the four parameters defining the PCA must satisfy in order to have an invariant measure with a product form or a Markovian form. Some extensions and alternative proofs were proposed by Mairesse and Marcovici in a later article [MM14b], together with a study of some properties of the random fields given by stationary space-time diagrams of PCA having a product form invariant measure (see also the survey on PCA of the same authors [MM14a]). The novelty was to highlight that these space-time diagrams are i.i.d. along many directions, and present a directional reversibility: they can also be seen as being obtained by iterating some PCA in another direction. Soon after, Casse and Marckert have proposed an in-depth study of the Markovian case [Cas16, CM15]. Motivated by the study of the 8-vertex model, Casse was then led to introduce a class of one-dimensional PCA with memory two, called *triangular PCA* [Cas18].

In the present article, we propose a comprehensive study of PCA with memory two having an invariant measure with a product form, and we show that their stationary space-time diagrams share some specificities. We first extend the notion of reversibility and quasi-reversibility to take into account other symmetries than the time reversal and, in a second time, we characterize PCA with an invariant product measure that are reversible or quasi-reversible. Even if most one-dimensional positive-rates PCA are usually expected to be ergodic, the ergodicity of PCA is known to be a difficult problem, algorithmically undecidable [BMM13, TVS⁺90]. In Section 3, after characterizing positive-rates PCA having a product invariant measure, we prove that these PCA are ergodic (Theorem 3.3). A novelty of our work is also to display some PCA for which the invariant measure has neither a product form nor a Markovian one, but for which the finite-dimensional marginals can be exactly computed (Corollaries 4.10 and 5.7). In Section 5, we study PCA having Markov invariant measures. Section 6 is then devoted to the presentation of some applications of our models and results to statistical physics (8-vertex model, enumeration of directed animals, TASEP). In particular, we introduce an extension of the TASEP model, in which the probability for a particle to move depends on the distance of the previous particle and of its speed. It can also be seen as a traffic flow model, more realistic than the classical TASEP model. Finally, we give on one si

When describing the family of PCA presenting some given directional reversibility or quasi-reversibility property, for each family of PCA involved, we give the conditions that the parameters of the PCA must satisfy in order to present that behaviour, and we provide the dimension of the corresponding submanifold of the parameter space, see Table 2.1. Our purpose is to show that despite their specificity, these PCA build

up rich classes, and we set out the detail of the computations of the dimensions in the last section.

2. Definitions and presentation of the results

2.1. Introductory example

In this paragraph, we give a first introduction to PCA with memory two, using an example motivated by the study of the 8-vertex model [Cas18]. We present some properties of the stationary space-time diagram of this PCA: although it is a non-trivial random field, it is made of lines of i.i.d. random variables, and it is reversible. In the rest of the article, we will study exhaustively the families of PCA having an analogous behaviour. We will also come back to the 8-vertex model in Section 6.

Let us set $Z_e^2 = \{(i, t) \in Z^2 : i + t \equiv 0 \pmod{2}\}$, and introduce the notations: $Z_t = 2Z$ if $t \in 2Z$, and $Z_t = 2Z + 1$ if $t \in 2Z + 1$, so that the grid Z_e^2 can be seen as the union on $t \in Z$ of the points $\{(i, t) : i \in Z_t\}$, that will contain the information on the state of the system at time t . Note that one can scroll the positions corresponding to two consecutive steps of time along an horizontal zigzag line: $\dots (i, t), (i + 1, t + 1), (i + 2, t), (i + 3, t + 1) \dots$. This will explain the terminology introduced later.

We now define a PCA dynamics on the *alphabet* $S = \{0, 1\}$, which, through a recoding, can be shown to be closely related to the 8-vertex model (see Section 6.1 for details). The configuration η_t at a given time $t \in Z$ is an element of S^{Z_t} , and the evolution is as follows. Let us denote by $\mathcal{B}(q)$ the Bernoulli measure $q\delta_1 + (1 - q)\delta_0$. Given the configurations η_t and η_{t-1} at times t and $t - 1$, the configuration η_{t+1} at time $t + 1$ is obtained by updating each site $i \in Z_{t+1}$ simultaneously and independently, according to the distribution $T(\eta_t(i - 1), \eta_{t-1}(i), \eta_t(i + 1); \cdot)$, where

$$\begin{aligned} T(0, 0, 1; \cdot) &= T(1, 0, 0; \cdot) = \mathcal{B}(q), \\ T(0, 1, 1; \cdot) &= T(1, 1, 0; \cdot) = \mathcal{B}(1 - q) \\ T(0, 1, 0; \cdot) &= T(1, 1, 1; \cdot) = \mathcal{B}(r), \\ T(1, 0, 1; \cdot) &= T(0, 0, 0; \cdot) = \mathcal{B}(1 - r). \end{aligned}$$

As a special case, for $q = r$, we have $T(a, b, c; \cdot) = q\delta_{a+b+c \pmod{2}} + (1 - q)\delta_{a+b+c+1 \pmod{2}}$, so that the new state is equal to $a + b + c \pmod{2}$ with probability q , and to $a + b + c + 1 \pmod{2}$ with probability $1 - q$. Figure 2.1 shows how η_{t+1} is computed from η_t and η_{t-1} , illustrating the progress of the Markov chain.

Let us assume that initially, (η_0, η_1) is distributed according to the uniform product measure $\lambda = \mathcal{B}(1/2)^{Z_0} \otimes \mathcal{B}(1/2)^{Z_1}$. Then, we can show that for any $t \in \mathbb{N}$, (η_t, η_{t+1}) is also distributed according to λ . We will say that the PCA has an invariant *Horizontal Zigzag Product Measure*. By stationarity, we can then extend the space-time diagram to a random field with values in $S^{Z_e^2}$. The study of the space-time diagram shows that it has some peculiar properties, which we will precise in the next sections. In particular, it is quasi-reversible: if we reverse the direction of time, the random field corresponds to the stationary space-time diagram of another

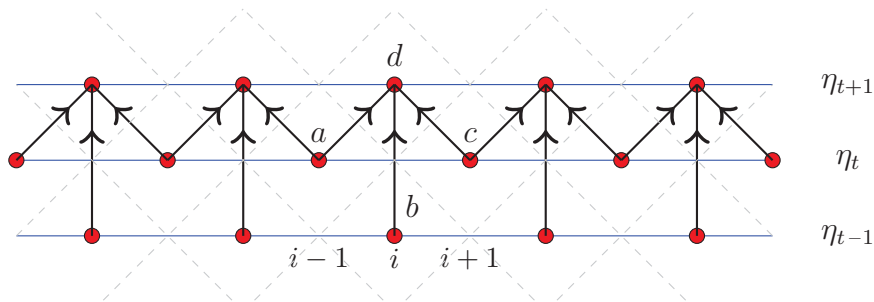


Figure 2.1. Illustration of the way η_{t+1} is obtained from η_t and η_{t-1} , using the transition kernel T . The value $\eta_{t+1}(i)$ is equal to d with probability $T(a, b, c; d)$, and conditionally on η_t and η_{t-1} , the values $(\eta_{t+1}(i))_{i \in \mathbb{Z}_{t+1}}$ are independent.

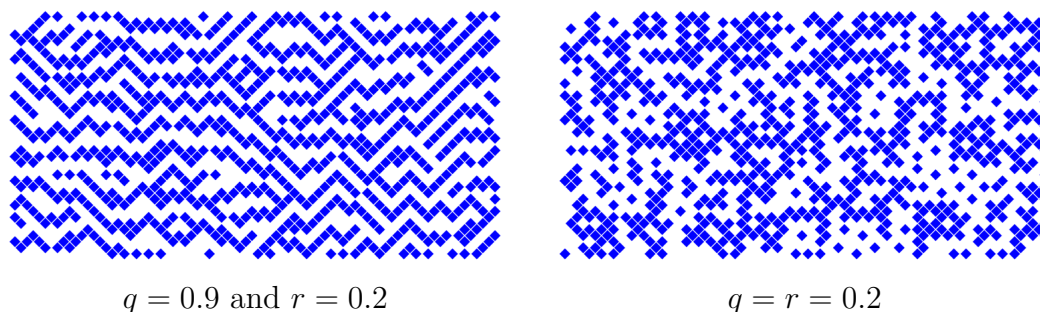


Figure 2.2. Examples of portions of stationary space-time diagrams of the 8-vertex PCA, for different values of the parameters. Cells in state 1 are represented in blue, and cells in state 0 are white.

PCA. Furthermore, the PCA is ergodic: whatever the distribution of (η_0, η_1) , the distribution of (η_t, η_{t+1}) converges weakly to λ (meaning that for any $n \in \mathbb{N}$, the restriction of (η_t, η_{t+1}) to the cells of abscissa ranging between $-n$ and n converges to a uniform product measure). For $q = r$, the stationary space-time diagram presents even more symmetries and directional reversibilities: it has the same distribution as if we had iterated the PCA in any other of the four cardinal directions. In addition, any straight line drawn along the space-time diagram is made of i.i.d. random variables, see Figure 2.2 for an illustration.

We will show that this PCA belongs to a more general class of PCA that are all ergodic and for which the stationary space-time diagram share specific properties (independence, directional reversibility).

2.2. PCA with memory two and their invariant measures

In this article, we only consider PCA with memory two for which the value of a given cell at time $t + 1$ is drawn according to a distribution which is a function of the states of its two nearest neighbours at time t , and of its own state at time $t - 1$. We thus introduce the following definition of transition kernel and of PCA with memory two.

DEFINITION 2.1. — Let S be a finite set, called the alphabet. A transition kernel is a function T that maps any $(a, b, c) \in S^3$ to a probability distribution on S . We denote by $T(a, b, c; \cdot)$ the distribution on S which is the image of the triplet $(a, b, c) \in S^3$, so that: $\forall d \in S, T(a, b, c; d) \in [0, 1]$ and $\sum_d S T(a, b, c; d) = 1$.

A probabilistic cellular automaton (PCA) with memory two of transition kernel T is a Markov chain of order two $(\eta_t)_{t>0}$ such that η_t has values in S^{Z^t} , and conditionally on η_t and η_{t-1} , for any $i \in Z_{t+1}$, $\eta_{t+1}(i)$ is distributed according to $T(\eta_t(i-1), \eta_{t-1}(i), \eta_t(i+1); \cdot)$, independently for different $i \in Z_{t+1}$.

By definition, if $(\eta_t(i-1), \eta_{t-1}(i), \eta_t(i+1)) = (a, b, c)$, then $\eta_{t+1}(i)$ is equal to $d \in S$ with probability $T(a, b, c; d)$, see Figure 2.1 for an illustration. We say that a PCA has *positive rates* if its transition kernel T is such that $\forall a, b, c, d \in S, T(a, b, c; d) > 0$. One can consider a PCA of order 2 on S as a PCA of order 1 on S^2 , but the resulting PCA then does not have positive rates, which leads to significant difficulties. We thus introduce specific tools for the study of PCA of order 2.

Let μ be a distribution on $S^{Z_{t-1}} \times S^{Z_t}$, and let us introduce the two basis vectors $u = (-1, 1)$ and $v = (1, 1)$ of Z_e^2 . We denote by $\sigma_v(\mu)$ the distribution on $S^{Z_t} \times S^{Z_{t+1}}$ which is the image of μ by the mapping:

$$\sigma_v : ((x_k)_{k \in Z_{t-1}}, (y_l)_{l \in Z_t}) \rightarrow ((x_{k-1})_{k \in Z_t}, (y_{l-1})_{l \in Z_{t+1}}).$$

When considering the distribution μ as living on two consecutive horizontal lines of the lattice Z_e^2 , corresponding to times $t-1$ and t , the distribution $\sigma_v(\mu)$ thus corresponds to shifting μ by a vector $v = (1, 1)$. Similarly, we denote by $\sigma_{v-u}(\mu)$ the distribution on $S^{Z_{t-1}} \times S^{Z_t}$ which is the image of μ by the application: $\sigma_{v-u} : ((x_k)_{k \in Z_{t-1}}, (y_l)_{l \in Z_t}) \rightarrow ((x_{k-2})_{k \in Z_{t-1}}, (y_{l-2})_{l \in Z_t})$.

For our specific context of PCA with memory two, we introduce the following definitions.

DEFINITION 2.2. — Let μ be a probability distribution on $S^{Z_0} \times S^{Z_1}$.

- The distribution μ is said to be *shift-invariant* if $\sigma_{v-u}(\mu) = \mu$.
- The distribution μ on $S^{Z_0} \times S^{Z_1}$ is an *invariant distribution of a PCA with memory two* if the PCA dynamics is such that: $(\eta_0, \eta_1) \sim \mu \implies (\eta_1, \eta_2) \sim \sigma_v(\mu)$.

By a standard compactness argument, one can prove that any PCA has at least one invariant distribution which is shift-invariant. In this article, we will focus on such invariant distributions. Note that if μ is both a shift-invariant measure and an invariant distribution of a PCA, then we also have $(\eta_0, \eta_1) \sim \mu \implies (\eta_1, \eta_2) \sim \sigma_u(\mu)$.

DEFINITION 2.3. — Let p be a distribution on S . The *p-HZPM* (for Horizontal Zigzag Product Measure) on $S^{Z_{t-1}} \times S^{Z_t}$ is the distribution $\pi_p = p^{Z_{t-1}} \otimes p^{Z_t}$.

Observe that we do not specify t in the notation, since there will be no possible confusion. By Definition 2.2, π_p is invariant for a PCA if:

$$(\eta_{t-1}, \eta_t) \sim \pi_p \implies (\eta_t, \eta_{t+1}) \sim \pi_p.$$

2.3. Stationary space-time diagrams and directional (quasi-)reversibility

Let A be a PCA and μ one of its invariant measures. Let $G_k = (\eta_t(i) : t \in \{-k, \dots, k\}, i \in Z_t)$ be a space-time diagram of A , started at time $t = -k$ under its invariant measure μ , until time $t = k$. Then $(G_k)_{k>0}$ induces a sequence of compatible measures on Z_e^2 and, by Kolmogorov's extension theorem, defines a unique measure on Z_e^2 , that we denote by $\mathcal{L}(A, \mu)$.

DEFINITION 2.4. — *Let A be a PCA and μ one of its invariant distributions which is shift-invariant. A random field $(\eta_t(i) : t \in Z, i \in Z_t)$ which is distributed according to $\mathcal{L}(A, \mu)$ is called a stationary space-time diagram of A taken under μ .*

We will use the notation $G(A, \mu)$ to represent a stationary space-time diagram of A taken under μ , that is, a random field with distribution $\mathcal{L}(A, \mu)$.

We denote by D_4 the dihedral group of order 8, that is, the group of symmetries of the square. We denote by r the rotation of angle $\pi/2$ and by h the horizontal reflection. We denote the vertical reflection by $v = r^2 \circ h$, and the identity by id . For a subset E of D_4 , we denote by $\langle E \rangle$ the subgroup of D_4 generated by the elements of E .

DEFINITION 2.5. — *Let A be a positive-rates PCA, and let μ be an invariant measure of A which is shift-invariant. For $g \in D_4$, we say that (A, μ) is g -quasi-reversible, if there exists a PCA A_g and a measure μ_g such that the associated stationary space time-diagrams satisfy*

$$G(A, \mu) \stackrel{(d)}{=} g^{-1} \circ G(A_g, \mu_g).$$

In this case, the pair (A_g, μ_g) is the g -reverse of (A, μ) . If, moreover, $(A_g, \mu_g) = (A, \mu)$, then (A, μ) is said to be g -reversible.

For a subset E of D_4 , we say that A is E -quasi-reversible (resp. E -reversible) if it is g -quasi-reversible (resp. g -reversible) for any $g \in E$.

Classical definitions of quasi-reversibility and reversibility of PCA correspond to time-reversal, that are, h -quasi-reversibility and h -reversibility. Geometrically, the stationary space-time diagram (A, μ) is g -quasi-reversible if after the action of the isometry g , the random field has the same distribution as if we had iterated another PCA A_g (or the same PCA A , in the reversible case). In particular, if (A, μ) is r -quasi-reversible (resp. r^2, r^3), it means that even if the space-time diagram is originally defined by an iteration of the PCA A towards the North, it can also be described as the stationary space-time diagram of another PCA directed to the East (resp. to the South, to the West).

The stationary space-time diagram of a PCA (see Definition 2.4) is a random field indexed by Z_e^2 . For a point $x = (i, t) \in Z_e^2$, we will also use the notation $\eta(x) = \eta(i, t) = \eta_t(i)$, and for a family $L \subset Z_e^2$, we define $\eta(L) = (\eta(x))_{x \in L}$.

The following Lemma 2.6 proves that the space-time diagram of a positive-rate PCA characterizes its dynamics. Precisely, if two positive-rates PCA A and A have the same space-time diagram (in law) taken under their respective invariant measures μ and μ , then $A = A$ and $\mu = \mu$.

LEMMA 2.6. — *Let (A, μ) and (A, μ) be two positive-rates PCA with one of their invariant measure. Then, $\mathcal{L}(A, \mu) = \mathcal{L}(A, \mu) \implies (A, \mu) = (A, \mu)$.*

Proof. — Let $G = G(A, \mu) = (\eta_t(i) : t \in \mathbb{Z}, i \in \mathbb{Z}_t)$ and $G = G(A, \mu) = (\eta_t(i) : t \in \mathbb{Z}, i \in \mathbb{Z}_t)$ be two space-time diagrams of law $\mathcal{L}(A, \mu)$ and $\mathcal{L}(A, \mu)$. By definition, $G|_{t=0,1} \sim \mu$ and $G|_{t=0,1} \sim \mu$. Since $G \stackrel{(d)}{=} G$, we obtain $\mu = \mu$.

Let us denote $\mu(a, b, c) = \mathbb{P}(\eta_1(-1) = a, \eta_0(0) = b, \eta_1(1) = c)$. As a consequence of the fact that A has positive rates, we have $\forall (a, b, c) \in S^3, \mu(a, b, c) > 0$. Thus, for any $a, b, c, d \in S$, we have

$$\mathbb{P}(\eta_1(-1) = a, \eta_0(0) = b, \eta_1(1) = c, \eta_2(0) = d) = \mu(a, b, c)T(a, b, c; d) > 0.$$

The same relation holds for A and as $G \stackrel{(d)}{=} G$, we obtain $\mu(a, b, c)T(a, b, c; d) = \mu(a, b, c)T(a, b, c; d)$. Since $\mu = \mu$, we deduce that $T(a, b, c; d) = T(a, b, c; d)$ for any $a, b, c, d \in S$. Hence, $A = A$.

By Lemma 2.6, if a PCA is g -quasi-reversible (see Definition 2.5), its g -reverse is thus unique. Let us now enumerate some easy results on quasi-reversible PCA and reversible PCA. Although the following proposition is quite straightforward, we are not aware of any reference formalizing the notion of directional reversibility and the properties below.

PROPOSITION 2.7. — *Let A be a positive-rates PCA and let μ be one of its invariant measures.*

- (1) (A, μ) is id-reversible.
- (2) (A, μ) is v -quasi-reversible and the v -reverse PCA is defined by the transition kernel $T_v(c, b, a; d) = T(a, b, c; d)$.
- (3) For any $g \in D_4$, if (A, μ) is g -quasi-reversible, then its g -reverse (A_g, μ_g) is g^{-1} -quasi-reversible and (A, μ) is the g^{-1} -reverse of (A_g, μ_g) .
- (4) If (A, μ) is g -quasi-reversible and (A_g, μ_g) is its g -reverse and if (A_g, μ_g) is g -quasi-reversible and $(A_{g g}, \mu_{g g})$ is its g -reverse, then (A, μ) is $g g$ -quasi-reversible and $(A_{g g}, \mu_{g g})$ is its $g g$ -reverse.
- (5) For any subset E of D_4 , if (A, μ) is E -reversible, then (A, μ) is $\langle E \rangle$ -reversible.

Remark 2.8. — Since $\langle r, v \rangle = D_4$, a consequence of the last point of Proposition 2.7 is that if (A, μ) is r and v -reversible, then it is D_4 -reversible.

Table 2.1 presents a summary of the results that will be proven in the next sections, concerning PCA having a p -HZPM invariant distribution and their stationary space-time diagrams. For each possible (quasi-)reversibility behaviour, we give the conditions that the parameters of the PCA must satisfy (see Section 4 for details), and provide the number of degrees of freedom left by these equations, that is, the dimension of the corresponding submanifold of the parameter space (see Section 9). In a similar fashion, Table 2.2 synthesized the main results about PCA having a Markovian invariant measure (see Section 5).

Table 2.1. Summary of the characterization of (quasi-)reversible PCA having a p -HZPM invariant distribution. We denote by n the cardinal of the alphabet S .

Conditions on the parameters	Property of the PCA	Dim. of the submanifold (nb. of deg. of freedom)
$\boxed{\text{Cond. 1. — } \forall a, c, d \in S, p(d) = \sum_b p(b)T(a, b, c; d)}$	p -HZPM invariant $\{r^2, h\}$ -quasi-reversible $T_{r^2}(c, d, a; b) = \frac{p(b)}{p(d)}T(a, b, c; d)$ $T_h(a, d, c; b) = \frac{p(b)}{p(d)}T(a, b, c; d)$	$n^2(n - 1)^2$
Cond. 1 + $\boxed{\text{Cond. 2. — } \forall a, b, d \in S, p(d) = \sum_c p(c)T(a, b, c; d)}$	r -quasi-reversible $T_r(d, a, b; c) = \frac{p(c)}{p(d)}T(a, b, c; d)$	$n(n - 1)^3$
Cond. 1 + $\boxed{\text{Cond. 3. — } \forall b, c, d \in S, p(d) = \sum_a p(a)T(a, b, c; d)}$	r^{-1} -quasi-reversible $T_{r^{-1}}(b, c, d; a) = \frac{p(a)}{p(d)}T(a, b, c; d)$	$n(n - 1)^3$
Cond. 1 + Cond. 2 + Cond. 3	D_4 -quasi-reversible	$(n - 1)^4$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, T(a, b, c; d) = T(c, b, a; d)}$	v -reversible	$\frac{(n - 1)^2 n (n + 1)}{2}$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, p(b)T(a, b, c; d) = p(d)T(c, d, a; b)}$	r^2 -reversible	$\frac{(n - 1)^2 n (n + 1)}{2}$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, p(b)T(a, b, c; d) = p(d)T(a, d, c; b)}$	h -reversible	$\frac{n^3(n - 1)}{2}$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, T(a, b, c; d) = T(c, b, a; d) \text{ and } p(b)T(a, b, c; d) = p(d)T(c, d, a; b)}$	$\langle r^2, v \rangle$ -reversible	$\frac{(n - 1)n^2(n + 1)}{4}$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, p(a)T(a, b, c; d) = p(d)T(b, c, d; a)}$	$\langle r \rangle$ -reversible	$\frac{n(n - 1)(n^2 - 3n + 4)}{4}$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, p(a)T(a, b, c; d) = p(d)T(d, c, b; a)}$	$\langle r \circ v \rangle$ -reversible	$\frac{(n - 1)^2(n^2 - 2n + 2)}{2}$
Cond. 1 + $\boxed{\forall a, b, c, d \in S, p(a)T(a, b, c; d) = p(d)T(b, c, d; a) \text{ and } T(a, b, c; d) = T(c, b, a; d)}$	D_4 -reversible	$\frac{n(n - 1)(n^2 - n + 2)}{8}$

3. Invariant product measures and ergodicity

In this section, we lay the groundwork for the study of PCA with memory two having an invariant measure with a product form. First, Theorem 3.1 gives the necessary and sufficient condition for a PCA to have a p -HZPM invariant distribution

Table 2.2. Summary of the characterization of (quasi-)reversible PCA having a (F, B) -HZMC invariant distribution.

Conditions on the parameters	Property of the PCA
<div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 5px auto;"> <i>Cond. 4.</i> — $\forall a, c, d \in S,$ $F(a; d)B(d; c) = \sum_b {}_S B(a; b)F(b; c)T(a, b, c; d)$ </div>	(F, B) -HZMC invariant $\{r^2, h\}$ -quasi-reversible $T_{r^2}(c, d, a; b) = \frac{B(a; b)F(b; c)}{F(a; d)B(d; c)}T(a, b, c; d)$ $T_h(a, d, c; b) = \frac{B(a; b)F(b; c)}{F(a; d)B(d; c)}T(a, b, c; d)$
<p style="text-align: center;">Cond. 4 +</p> <div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 5px auto;"> <i>Cond. 5.</i> — $\forall a, c, d \in S,$ $F(a; d) = \sum_c {}_S F(b; c)T(a, b, c; d)$ </div>	r -quasi-reversible $T_r(d, a, b; c) = \frac{F(b; c)}{F(a; d)}T(a, b, c; d)$
<p style="text-align: center;">Cond. 4 +</p> <div style="border: 1px solid black; padding: 5px; width: fit-content; margin: 5px auto;"> <i>Cond. 6.</i> — $\forall b, c, d \in S,$ $\frac{\rho(d)}{\rho(c)}B(d; c) = \sum_a {}_S \frac{\rho(a)}{\rho(b)}B(a; b)T(a, b, c; d)$ </div>	r^{-1} -quasi-reversible $T_{r^{-1}}(b, c, d; a) = \frac{\rho(a)\rho(c)B(a; b)}{\rho(b)\rho(d)B(d; c)}T(a, b, c; d)$

(Cond. 1). This condition will be extensively used in the continuation of the article. We then prove that any PCA satisfying this condition is ergodic, meaning that whatever the initial distribution for times $t = 0$ and $t = 1$, when iterating the dynamics, the PCA converges to the product measure of parameter p . Finally, we show that the stationary space-time diagrams of PCA having a p -HZPM invariant distribution share the following property: not only all the horizontal zigzag lines are distributed according to the product measure of parameter p , but also more general zigzag lines (in the sense of Definition 3.4).

3.1. Conditions for having an invariant HZPM

To start with, next Theorem 3.1 gives a characterization of PCA with memory two having a p -HZPM invariant distribution.

THEOREM 3.1. — *Let A be a positive-rates PCA with transition kernel T , and let p be a probability vector on S . The p -HZPM distribution π_p is invariant for A if and only if:*

Cond 1. — for any $a, c, d \in S$, $p(d) = \sum_b {}_S p(b)T(a, b, c; d)$.

Note that since A has positive rates, if π_p is invariant for A , then the vector p has to be positive. For a positive probability vector p on S , we define $\mathcal{T}_S(p)$ as the set of positive-rates PCA for which the measure π_p is invariant. We denote by \mathcal{T}_S the set of all positive-rates PCA with set of symbols S having an invariant p -HZPM, for some positive probability vector p on S .

As an immediate consequence of Theorem 3.1, one obtains the following result.

COROLLARY 3.2. — *Let A be a positive-rates PCA with transition kernel T . Then, $A \in \mathcal{T}_S$ if and only if for any $a, c \in S$, the left eigenspace $E_{a,c}$ of matrices $(T(a, b, c; d))_{b, d \in S}$ related to the eigenvalue 1 is the same. In that case, the invariant*

HZPM is unique: it is the measure π_p defined by the unique vector p such that $E_{a,c} = \text{Vect}(p)$ for all $a, c \in S$ and $\sum_b p(b) = 1$.

Proof of Theorem 3.1. — Let p be a positive vector such that π_p is invariant by A and assume that $(\eta_{t-1}, \eta_t) \sim \pi_p$. Then, on the one hand, since π_p is invariant by A , we have

$$\mathbb{P}(\eta_t(i-1) = a, \eta_{t+1}(i) = d, \eta_t(i+1) = c) = p(a)p(c)p(d).$$

And on the other hand, by definition of the PCA,

$$\mathbb{P}(\eta_t(i-1) = a, \eta_{t+1}(i) = d, \eta_t(i+1) = c) = \sum_{b \in S} p(a)p(b)p(c)T(a, b, c; d).$$

Cond. 1 follows.

Conversely, assume that Cond. 1 is satisfied, and that $(\eta_{t-1}, \eta_t) \sim \pi_p$. For some given choice of $n \in \mathbb{Z}_t$, let us denote: $X_i = \eta_{t-1}(n+1+2i)$, $Y_i = \eta_t(n+2i)$, $Z_i = \eta_{t+1}(n+1+2i)$, for $i \in \mathbb{Z}$, see Figure 3.1 for an illustration. Then, for any $k > 1$, we have

$$\begin{aligned} & \mathbb{P}((Y_i)_{0 \leq i \leq k} = (y_i)_{0 \leq i \leq k}, (Z_i)_{0 \leq i \leq k-1} = (z_i)_{0 \leq i \leq k-1}) \\ &= \sum_{(x_i)_{0 \leq i \leq k-1}} \mathbb{P}((X_i)_{0 \leq i \leq k-1} = (x_i)_{0 \leq i \leq k-1}, (Y_i)_{0 \leq i \leq k} = (y_i)_{0 \leq i \leq k}) \prod_{i=0}^{k-1} T(y_i, x_i, y_{i+1}; z_i) \\ &= \sum_{(x_i)_{0 \leq i \leq k-1}} \prod_{i=0}^{k-1} p(x_i) \prod_{i=0}^k p(y_i) \prod_{i=0}^{k-1} T(y_i, x_i, y_{i+1}; z_i) \\ &= \prod_{i=0}^k p(y_i) \prod_{i=0}^{k-1} \sum_{x_i \in S} p(x_i) T(y_i, x_i, y_{i+1}; z_i) \\ &= \prod_{i=0}^k p(y_i) \prod_{i=0}^{k-1} p(z_i) \text{ by Cond. 1, thus, } \pi_p \text{ is invariant by } A. \end{aligned}$$

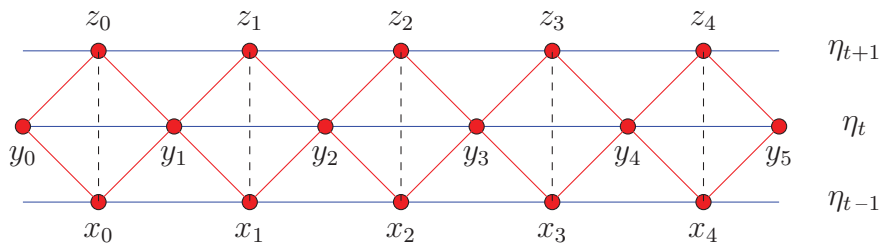


Figure 3.1. Illustration of the proof of Theorem 3.1.

As a consequence of Corollary 3.2, $A \in \mathcal{T}_S$ if and only if $A \in \mathcal{T}_S(p)$ for the unique p given by the corollary.

3.2. Ergodicity

THEOREM 3.3. — *If $A \in \mathcal{T}_S(p)$, then, A is ergodic. Precisely, for any distribution of (η_0, η_1) , the distribution of (η_t, η_{t+1}) converges weakly to π_p .*

Proof. — The proof we propose is inspired from [Vas78], see also [TVS⁺90] and [Mar16]. Let us fix some boundary conditions $(\ell, r) \in S^2$. Then, for any $k > 0$, the transition kernel T induces a Markov chain on S^{2k+1} , such that the probability of a transition from the sequence $(a_0, b_0, a_1, b_1, \dots, b_{k-1}, a_k) \in S^{2k+1}$ to a sequence $(a_0, b_0, a_1, b_1, \dots, b_{k-1}, a_k) \in S^{2k+1}$ is given by:

$$\begin{aligned} & P_k^{(\ell, r)}\left((a_0, b_0, a_1, b_1, \dots, b_{k-1}, a_k), (a_0, b_0, a_1, b_1, \dots, b_{k-1}, a_k)\right) \\ &= T(\ell, a_0, b_0; a_0)T(a_0, b_0, a_1; b_0)T(b_0, a_1, b_1; a_1) \cdots T(b_{k-1}, a_k, r; a_k) \\ &= T(\ell, a_0, b_0; a_0)T(b_{k-1}, a_k, r; a_k) \prod_{i=1}^{k-1} T(b_{i-1}, a_i, b_{i+1}; a_i) \prod_{i=0}^{k-1} T(a_i, b_i, a_{i+1}; b_i). \end{aligned}$$

We refer to Figure 3.2 for an illustration. Let us observe that the restriction $\pi_p^k = p^{2k+1}$ of the p -HZPM is left invariant by this Markov chain. This is an easy consequence of Cond. 1. For any $(\ell, r) \in S^2$, the transition kernel $P^{(\ell, r)}$ is positive. Therefore, there exists $\theta_{(\ell, r)} < 1$ such that for any probability distributions ν, ν' on S^{2k+1} , we have

$$\left\| P_k^{(\ell, r)} \nu - P_k^{(\ell, r)} \nu' \right\|_1 \leq \theta_k^{(\ell, r)} \|\nu - \nu'\|_1,$$

the above inequality being true in particular for $\theta_k^{(\ell, r)} = 1 - \varepsilon_k^{(\ell, r)}$, where:

$$\varepsilon_k^{(\ell, r)} = \min\{P_k^{(\ell, r)}(x, y) : x, y \in S^{2k+1}\}.$$

Let us set $\theta_k = \max\{\theta_k^{(\ell, r)} : (\ell, r) \in S^2\}$. It follows that for any sequence $(\ell_t, r_t)_{t>0}$ of elements of S^2 , we have

$$\left\| P_k^{(\ell_{t-1}, r_{t-1})} \cdots P_k^{(\ell_1, r_1)} P_k^{(\ell_0, r_0)} \nu - P_k^{(\ell_{t-1}, r_{t-1})} \cdots P_k^{(\ell_1, r_1)} P_k^{(\ell_0, r_0)} \nu' \right\|_1 \leq \theta^t \|\nu - \nu'\|_1.$$

In particular, for $\nu = \pi_p^k$, we obtain that for any distribution ν on S^{2k+1} and any sequence $(\ell_t, r_t)_{t>0}$ of elements of S^2 , we have

$$\left\| P_k^{(\ell_{t-1}, r_{t-1})} \cdots P_k^{(\ell_1, r_1)} P_k^{(\ell_0, r_0)} \nu - \pi_p^k \right\|_1 \leq 2\theta^t.$$

Let now μ be a distribution on $S^{\mathbb{Z}_0 \times \mathbb{Z}_1}$, and let $k > 0$. When iterating A , the distribution μ induces a random sequence of symbols $\ell_t = \eta_{2t+1}(-2k + 1)$ and $r_t = \eta_{2t+1}(2k + 1)$. Let us denote by ν_t the distribution of the sequence $(\eta_{2t}(-2k), \eta_{2t+1}(-2k + 1), \eta_{2t}(-2k + 2), \dots, \eta_{2t}(2k - 2), \eta_{2t+1}(2k - 1), \eta_{2t}(2k))$, and let $\pi_p^{2k} = p^{4k+1}$. We have

$$\forall t > 0, \|\nu_t - \pi_p^{2k}\|_1 \leq \max_{(\ell_0, r_0) \dots (\ell_{t-1}, r_{t-1}) \in S^2} \left\| P_{2k}^{(\ell_{t-1}, r_{t-1})} \cdots P_{2k}^{(\ell_1, r_1)} P_{2k}^{(\ell_0, r_0)} \nu_0 - \pi_p^{2k} \right\|_1 \leq 2\theta^t.$$

This concludes the proof.

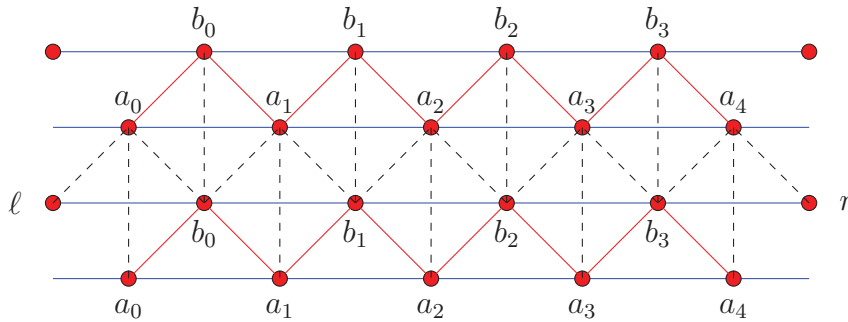


Figure 3.2. Illustration of the proof of Theorem 3.3.

3.3. First properties of the space-time diagram

Let us now focus on the space-time diagram $G(A, \pi_p)$ of a PCA $A \in \mathcal{T}_S(p)$, taken under its unique invariant measure π_p . By definition, any horizontal line of that space-time diagram is i.i.d. The following proposition extends this result to other types of lines.

DEFINITION 3.4. — A zigzag polyline is a sequence $(i, t_i)_{m_1 \leq i \leq m_2} \in Z_e^2$ such that for any $i \in \{m_1, \dots, m_2\}$, $(t_{i+1} - t_i) \in \{-1, 1\}$.

PROPOSITION 3.5. — Let $A \in \mathcal{T}_S(p)$ be a PCA of stationary space-time diagram $G(A, \pi_p) = (\eta_t(i) : t \in Z, i \in Z_t)$. For any zigzag polyline $(i, t_i)_{m_1 \leq i \leq m_2}$, we have $(\eta_{t_i}(i) : i \in \{m_1, \dots, m_2\}) \sim \mathcal{B}(p)^{(m_2 - m_1 + 1)}$.

Observe that Proposition 3.5 implies that (bi-)infinite zigzag polylines are also made of i.i.d. random variables with distribution p .

Proof. — The proof is done by induction on $T = \max(t_i) - \min(t_i)$. If $T = 1$, then the zigzag polyline is an horizontal zigzag, and since $A \in \mathcal{T}_S(p)$, the result is true.

Now, suppose that the result is true for any zigzag polyline such that $\max(t_i) - \min(t_i) = T$, and consider a zigzag polyline $(i, t_i)_{m_1 \leq i \leq m_2}$ such that $\max(t_i) - \min(t_i) = T + 1$. Then, there exists t such that $\min(t_i) = t$ and $\max(t_i) = t + T + 1$. Let $M = \{i \in \{m_1, \dots, m_2\} : t_i = t + T + 1\}$. For any $i \in M$, we have $t_{i \pm 1} = t + T$ (we assume that $m_1, m_2 \notin M$, even if it means extending the line). So, by induction, we have $(\eta(i, t_i - 2) \mathbb{1}_{i \in M}) : i \in \{m_1, \dots, m_2\} \sim \mathcal{B}(p)^{(m_2 - m_1 + 1)}$. For any $(a_i)_{m_1 \leq i \leq m_2} \in S^{m_2 - m_1 + 1}$, we have

$$\begin{aligned} & \mathbb{P}(\eta(x_i, t_i) = a_i : m_1 \leq i \leq m_2) \\ &= \sum_{(b_i : i \in M)} \mathbb{P}(\{\eta(i, t_i) = a_i : i \notin M\}, \{\eta(i, t_i - 2) = b_i : i \in M\}) \prod_{i \in M} T(a_{i-1}, b_i, a_{i+1}; a_i) \\ &= \sum_{(b_i : i \in M)} \prod_{i \notin M} p(a_i) \prod_{i \in M} p(b_i) T(a_{i-1}, b_i, a_{i+1}; a_i) \\ &= \prod_{i \notin M} p(a_i) \prod_{i \in M} \sum_{b_i \in S} p(b_i) T(a_{i-1}, b_i, a_{i+1}; a_i) = \prod_{i=m_1}^{m_2} p(a_i). \end{aligned}$$

4. Directional (quasi-)reversibility of PCA having an invariant product measure

We now explore the directional reversibility and quasi-reversibility properties of PCA having an invariant p -HZPM. First, for any transformation g of the dihedral group D_4 , we give the necessary and sufficient condition under which the PCA is g -quasi-reversible or g -reversible, thus proving the results that were announced in Table 2.1. We then present some further properties of the stationary space-time diagrams that hold in this context, beyond Proposition 3.5. Finally, these results will allow us to exhibit a family of PCA having an invariant measure that can be computed explicitly, although it does not have a product form or a Markovian one.

4.1. (Quasi-)reversible PCA with invariant p -HZPM

In this section, we characterize PCA of $\mathcal{T}_S(p)$ that are g -quasi-reversible, for each possible $g \in D_4$. Let $A \in \mathcal{T}_S(p)$, and $g \in D_4$. From the transition kernel T of A , we define a map $T_g : S^3 \times S \rightarrow \mathbb{R}_+$ by:

$$\forall a, b, c, d \in S, \quad T_g(g(a, b, c); g(d)) = \frac{p(g(d))}{p(d)} T(a, b, c; d),$$

where in the above expression, we use some abuse of notation when denoting by $g(a, b, c)$ and $g(d)$ the images of the vertices by the permutation induced by the transformation $g \in D_4$ (see Figure 2.1). For example, in the case where $g = r$, we have $g(a, b, c) = (d, a, b)$, $g(d) = c$, and the expression above stands for:

$$\forall a, b, c, d \in S, \quad T_r(d, a, b; c) = \frac{p(c)}{p(d)} T(a, b, c; d).$$

The expressions of T_{r^2} , T_h , and $T_{r^{-1}}$ can be found in Table 2.1.

Observe that T_g is not necessarily a transition kernel. For example, T_r is a transition kernel if and only if:

$$\forall a, b, d \in S, \quad \sum_c \frac{p(c)}{p(d)} T(a, b, c; d) = 1,$$

which is equivalent to Cond. 2, see again Table 2.1. Analogously, $T_{r^{-1}}$ is a transition kernel if and only if Cond. 3 is satisfied. And it appears that as soon as a PCA belongs to $\mathcal{T}_S(p)$, T_{r^2} and T_h are transition kernels, since Cond. 1 is satisfied.

THEOREM 4.1. — *A PCA $A \in \mathcal{T}_S(p)$ of transition kernel T is g -quasi-reversible if and only if T_g is a transition kernel. In that case, T_g is the transition kernel of the g -reverse A_g of A .*

Before proving Theorem 4.1, let us present two corollaries that derive from it. First, the next result is a direct consequence of Theorem 4.1.

COROLLARY 4.2. — *Any PCA $A \in \mathcal{T}_S(p)$ is r^2 -quasi-reversible and h -quasi-reversible.*

For any stationary Markov chain, we can define a time-reversed chain, which still has the Markov property. But in general, the time-reversed chain of a stationary PCA is no more a PCA. Indeed, nothing ensures that for the time-reversed process, the states of different cells are independently distributed, conditionally on the states of their neighbours at the previous time step. So, it is restrictive to ask that the time reversal of the stationary Markov chain associated to a PCA of transition kernel T is still distributed according to some transition kernel T . Here, Corollary 4.2 shows that any PCA in $\mathcal{T}_S(p)$ is r^2 -quasi-reversible, which means that the time-reversed chain of a PCA of $\mathcal{T}_S(p)$ is still a PCA with memory two, which furthermore belongs to $\mathcal{T}_S(p)$, since it preserves the measure π_p .

We also have the following characterization of reversible PCA.

COROLLARY 4.3. — *Let $A \in \mathcal{T}_S(p)$ and $g \in D_4$. The PCA A is g -reversible iff $T_g = T$.*

Proof of Corollary 4.3. — By Theorem 4.1, A is g -quasi-reversible iff T_g is a transition kernel. It is furthermore reversible if $T_g = T$. Since T is obviously a transition kernel, A is g -reversible iff $T_g = T$.

As a direct consequence, we obtain easily all the conditions for reversibility that are given in Table 2.1.

Let us now prove Theorem 4.1. We begin the proof with the case $g = r^2$. The cases $g = \text{id}$ and $g = v$ are obvious by Proposition 2.7, and the case $g = h$ will directly follow from the case $g = r^2$.

Proof of Theorem 4.1, case $g = r^2$. — If $A \in \mathcal{T}_S(p)$, its transition kernel T satisfies Cond. 1, and thus, T_{r^2} is a transition kernel. It only remains to prove that A is indeed r^2 -quasi-reversible, and that T_{r^2} is the transition kernel of the r^2 -reverse of A .

For some given choice of $n \in Z_t$, let us denote again: $X_i = \eta_{t-1}(n + 1 + 2i)$, $Y_i = \eta_t(n + 2i)$, $Z_i = \eta_{t+1}(n + 1 + 2i)$, for $i \in Z$, see Figure 3.1.

The following computation proves the result wanted.

$$\begin{aligned} & P\left((X_i)_{0 \leq i \leq k} = (x_i)_{0 \leq i \leq k} \mid (Y_i)_{0 \leq i \leq k+1} = (y_i)_{0 \leq i \leq k+1}, (Z_i)_{0 \leq i \leq k} = (z_i)_{0 \leq i \leq k}\right) \\ &= \frac{P\left((X_i)_{0 \leq i \leq k} = (x_i)_{0 \leq i \leq k}, (Y_i)_{0 \leq i \leq k+1} = (y_i)_{0 \leq i \leq k+1}, (Z_i)_{0 \leq i \leq k} = (z_i)_{0 \leq i \leq k}\right)}{P\left((Y_i)_{0 \leq i \leq k+1} = (y_i)_{0 \leq i \leq k+1}, (Z_i)_{0 \leq i \leq k} = (z_i)_{0 \leq i \leq k}\right)} \\ &= \frac{p(y_0) \prod_{i=0}^k p(x_i)p(y_{i+1})T(y_i, x_i, y_{i+1}; z_i)}{p(y_0) \prod_{i=0}^k p(z_i)p(y_{i+1})} \\ &= \prod_{i=0}^k \frac{p(x_i)}{p(z_i)} T(y_i, x_i, y_{i+1}; z_i) \\ &= \prod_{i=0}^k T_{r^2}(y_{i+1}, z_i, y_i; x_i). \end{aligned}$$

Now, we will characterize PCA in $\mathcal{T}_S(p)$ that are r -quasi-reversible.

We give now the proof of Theorem 4.1 in the case $g = r$. The case $g = r^{-1}$ is similar and the cases $g = r \circ v, g = r^{-1} \circ v$ then follow.

Proof of Theorem 4.1, case $g = r$. — Let us first prove that if A is r -quasi-reversible, then Cond. 2 is satisfied and the transition kernel \tilde{T} of the r -reverse A_r of A is equal to T_r . Let us recall the notations $u = (-1, 1)$ and $v = (1, 1)$. Since $A \in \mathcal{T}_S(p)$, for any $x \in Z_e^2$ and $a, b, c, d \in S$, we have

$$P(\eta(x + u) = a, \eta(x) = b, \eta(x + v) = c, \eta(x + u + v) = d) = p(a)p(b)p(c)T(a, b, c; d).$$

Hence, the transition kernel \tilde{T} of A_r satisfies:

$$\begin{aligned} \tilde{T}(d, a, b; c) &= P(\eta(x + v) = c | \eta(x + u) = a, \eta(x) = b, \eta(x + u + v) = d) \\ (4.1) \quad &= \frac{p(a)p(b)p(c)T(a, b, c; d)}{\sum_c {}_S p(a)p(b)p(c)T(a, b, c; d)} \\ &= \frac{p(c)T(a, b, c; d)}{\sum_c {}_S p(c)T(a, b, c; d)}. \end{aligned}$$

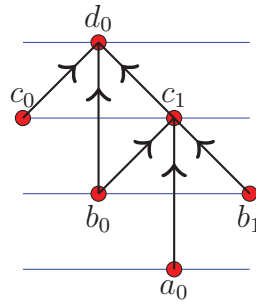


Figure 4.1. The pattern L .

For some $x \in Z_e^2$, let us introduce the pattern $L = (x, x + u, x + v, x + 2u, x + u + v, x + 2u + v)$, see Figure 4.1. For $a_0, b_0, b_1, c_0, c_1, d_0 \in S$, we are interested in the quantity:

$$Q(a_0, b_0, b_1, c_0, c_1, d_0) = P(\eta(L) = (a_0, b_0, b_1, c_0, c_1, d_0)).$$

On the one hand, using the fact that we have a portion of the space-time diagram $G(A, \pi_p)$, Proposition 3.5 implies that:

$$P(\eta(x + 2u) = c_0, \eta(x + u) = b_0, \eta(x) = a_0, \eta(x + v) = b_1) = p(c_0)p(b_0)p(a_0)p(b_1).$$

We thus obtain

$$Q(a_0, b_0, b_1, c_0, c_1, d_0) = p(c_0)p(b_0)p(a_0)p(b_1)T(b_0, a_0, b_1; c_1)T(c_0, b_0, c_1; d_0).$$

On the other hand, using the fact that A is r -quasi-reversible, we have

$$Q(a_0, b_0, b_1, c_0, c_1, d_0) = \sum_{b_1, c_1} {}_S Q(a_0, b_0, b_1, c_0, c_1, d_0) \tilde{T}(d_0, c_0, b_0; c_1) \tilde{T}(c_1, b_0, a_0; b_1).$$

It follows that:

$$\begin{aligned}
 (4.2) \quad 1 &= \sum_{b_1, c_1} \frac{Q(a_0, b_0, b_1, c_0, c_1, d_0)}{Q(a_0, b_0, b_1, c_0, c_1, d_0)} \tilde{T}(d_0, c_0, b_0; c_1) \tilde{T}(c_1, b_0, a_0; b_1) \\
 &= \sum_{b_1, c_1} \frac{p(b_1)T(b_0, a_0, b_1; c_1)T(c_0, b_0, c_1; d_0)}{p(b_1)T(b_0, a_0, b_1; c_1)T(c_0, b_0, c_1; d_0)} \tilde{T}(d_0, c_0, b_0; c_1) \tilde{T}(c_1, b_0, a_0; b_1)
 \end{aligned}$$

By (4.1), we have

$$\begin{aligned}
 \tilde{T}(d_0, c_0, b_0; c_1) &= \frac{p(c_1)T(c_0, b_0, c_1; d_0)}{\sum_c p(c)T(c_0, b_0, c; d_0)}, \\
 \tilde{T}(c_1, b_0, a_0; b_1) &= \frac{p(b_1)T(b_0, a_0, b_1; c_1)}{\sum_b p(b)T(b_0, a_0, b; c_1)}.
 \end{aligned}$$

After replacing in (4.2), we obtain:

$$\begin{aligned}
 &\left(\sum_b p(b)T(b_0, a_0, b; c_1) \right) \left(\sum_c p(c)T(c_0, b_0, c; d_0) \right) \\
 &= p(c_1) \sum_{b_1, c_1} p(b_1)T(b_0, a_0, b_1; c_1)T(c_0, b_0, c_1; d_0).
 \end{aligned}$$

Summing over $d_0 \in S$ on both sides and simplifying gives: $\sum_b p(b)T(b_0, a_0, b; c_1) = p(c_1)$. Hence, Cond. 2 is necessary, and $\tilde{T} = T_r$.

Let us now assume that T_r is a transition kernel, meaning that Cond. 2 holds.

For some $x \in Z_e^2$, and $m \in \mathbb{N}$ let us define the pattern $M = (x + i u + j v)_{0 \leq i, j \leq m}$. Using Proposition 3.5, for any $(a_{i,j})_{0 \leq i, j \leq m} \in S^{\{0,1,\dots,m\}^2}$, we have

$$P(\eta(M) = (a_{i,j})_{0 \leq i, j \leq m}) = \prod_{i=0}^m p(a_{i,0}) \prod_{j=1}^m p(a_{0,j}) \prod_{i=1}^m \prod_{j=1}^m T(a_{i,j-1}, a_{i-1,j-1}, a_{i-1,j}; a_{i,j}).$$

This computation is represented on Figure 4.3(a). The points for which $p(a_{i,j})$ appears in the product are marked by black dots, while the black vertical arrows represent the values that are computed through the transition kernel T . Now, by definition of T_r , we have

$$(4.3) \quad \forall a, b, c, d \in S, \quad p(c)T(a, b, c; d) = p(d)T_r(d, a, b; c).$$

It means that in the product above, we can perform flips as represented in Figure 4.2, where an arrow to the right now represents a computation made with the transition kernel T_r . We say that such a use of (4.3) is a flip of (c, d) . By flipping successively the cells from right to left and bottom to top: first $(a_{0,m}, a_{1,m})$, then $(a_{0,m-1}, a_{1,m-1})$, $(a_{1,m}, a_{2,m})$, and $(a_{0,m-2}, a_{1,m-2})$, $(a_{1,m-1}, a_{2,m-1})$, $(a_{2,m}, a_{3,m})$ etc., we finally obtain (see Figure 4.3 for an illustration):

$$\begin{aligned}
 (4.4) \quad P(\eta(M) = (a_{i,j})_{0 \leq i, j \leq m}) \\
 = \prod_{i=0}^m p(a_{i,0}) \prod_{j=1}^m p(a_{m,j}) \prod_{i=0}^{m-1} \prod_{j=1}^m T_r(a_{i+1,j}, a_{i+1,j-1}, a_{i,j-1}; a_{i,j}).
 \end{aligned}$$



Figure 4.2. Elementary flip illustrating the relation $p(c)T(a, b, c; d) = p(d)T_r(d, a, b; c)$.

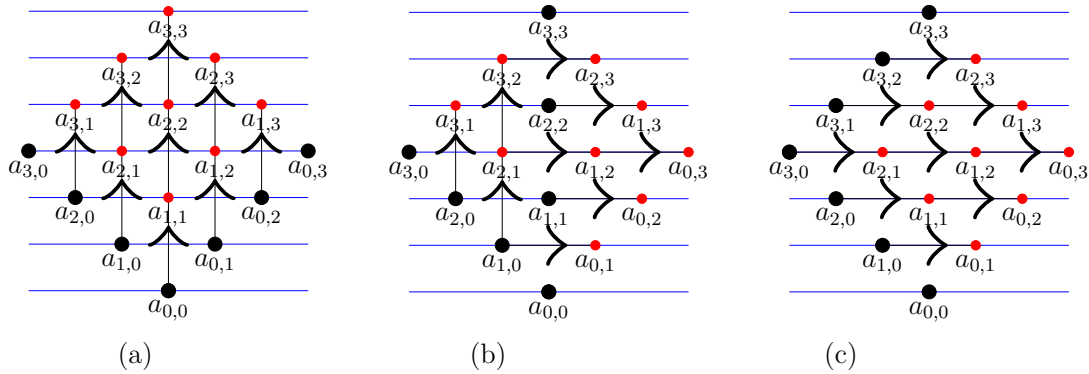


Figure 4.3. From T to T_r using flips.

Let us define the vertical lines: $V_{-1} = (x + (m - i)u + (m - i - 1)v)_{0 \leq i \leq m-1}$, $V_0 = (x + (m - i)u + (m - i)v)_{0 \leq i \leq m}$, $V_1 = (x + (m - i - 1)u + (m - i)v)_{0 \leq i \leq m-1}$. From (4.4), we deduce that:

$$\begin{aligned} \mathbb{P}(\eta(V_1) = (a_{m,m-1}, \dots, a_{1,0}) \mid \eta(V_0) = (a_{m,m}, \dots, a_{0,0}), \eta(V_{-1}) = (a_{m,m-1}, \dots, a_{1,0})) \\ = \prod_{i=0}^{m-1} T_r(a_{m-i,m}, a_{m-i,m-i-1}, a_{m-i-1,m-i-1}; a_{m-i-1,m-i}) \end{aligned}$$

Since this is true for any $x \in \mathbb{Z}_e^2$ and any $m \in \mathbb{N}$, it follows that the rotation of $G(A, \pi_p)$, the space-time diagram of A , by the rotation r is a space-time diagram of A_r , whose transition kernel is T_r , under one of its invariant measure that we denote by μ (observe that we do not specify the dependence on A in that last notation, although the measure depends on A). Furthermore, we can express explicitly the finite-dimensional marginals of μ . For any $m \in \mathbb{N}$, we have

$$\begin{aligned} \mu((a_{i+1,i})_{0 \leq i \leq m-1}, (a_{i,i})_{0 \leq i \leq m}) \\ = \mathbb{P}(\eta(V_0) = (a_{m,m}, \dots, a_{0,0}), \eta(V_1) = (a_{m,m-1}, \dots, a_{1,0})) \\ (4.5) \quad = \sum_{(a_{i,j} : i, i+1=j)} \prod_{i=0}^m p(a_{i,0}) \prod_{j=1}^m p(a_{0,j}) \prod_{1 \leq i, j \leq m} T(a_{i,j-1}, a_{i-1,j-1}, a_{i-1,j}; a_{i,j}) \end{aligned}$$

$$(4.6) \quad = \sum_{(a_{i,j} : j < i)} \prod_{i=0}^m p(a_{i,0}) \prod_{j=1}^m p(a_{m,j}) \prod_{1 \leq j \leq i \leq m} T_r(a_{i+1,j}, a_{i+1,j-1}, a_{i,j-1}; a_{i,j})$$

Note that in Theorem 4.1 (case $g = r$), the reverse PCA is not necessarily an element of $\mathcal{T}_S(p)$. In the space-time diagram $G(A, \pi_p)$, the points $x, x + u, x + 2u, \dots, x + mu, x + mu + v, \dots, x + mu + mv$ consist in independent random variables with distribution p . But if we now consider only the three points $x, x + v, x + u + v$, they have no reason to be independent, so that μ can be different from π_p . Proposition 4.4 below specifies the cases for which the reverse PCA A_r is an element of $\mathcal{T}_S(p)$, meaning that $\mu = \pi_p$.

PROPOSITION 4.4. — *Let $A \in \mathcal{T}_S(p)$. The following properties are equivalent:*

- (1) A is $\{r, r^{-1}\}$ -quasi-reversible,
- (2) A is r -quasi-reversible and $A_r \in \mathcal{T}_S(p)$,
- (3) A is r^{-1} -quasi-reversible and $A_{r^{-1}} \in \mathcal{T}_S(p)$,
- (4) Cond. 2 and Cond. 3 hold,
- (5) A is D_4 -quasi-reversible.

Proof.

(1) \Rightarrow (2). — If A is r -quasi-reversible, then the transition kernel T_r of its r -reverse A_r satisfies:

$$\sum_a p(a) T_r(d, a, b; c) = \sum_a p(a) \frac{p(c)}{p(d)} T(a, b, c; d) = p(c),$$

using Cond. 3, since A is r^{-1} -quasi-reversible. Thus, Cond. 1 holds for T_r and, by Theorem 3.1, $A_r \in \mathcal{T}_S(p)$.

(1) \Leftrightarrow (2). — Since $A_r \in \mathcal{T}_S(p)$, by Corollary 4.2, A_r is r^2 -quasi-reversible. Then, by the property (4) of Proposition 2.7, A is $r^3 = r^{-1}$ -quasi-reversible.

(1) \Leftrightarrow (3). — Same proof as (1) \Leftrightarrow (2).

(1) \Leftrightarrow (4). — It is a consequence of Theorem 4.1.

(1) \Leftrightarrow (5). — It is a consequence of the points (2) and (4) of Proposition 2.7, together with Corollary 4.2.

4.2. Independence properties of the space-time diagram

THEOREM 4.5. — *Let us consider a PCA $A \in \mathcal{T}_S(p)$ and its stationary space-time diagram $G = (A, \pi_p)$. Then for any $|a| \not\equiv 1$, the points of G indexed by the discrete line $L_{a,b} = \{(x, y) \in \mathbb{Z}_e^2 : y = ax + b\}$ consist in i.i.d. random variables.*

Proof. — This is a consequence of Proposition 3.5. We can assume without loss of generality that $b = 0$ and that $0 < a \not\equiv 1$, and we assume that the discrete line is non-empty. Let $(x, y) \in \mathbb{Z}_e^2$ be the first point with positive coordinates belonging to the integer line, so that we have in particular $0 < y \not\equiv x$. Let us define the sequence $(t_i)_Z$ by $t_{i+kx} = i + ky$ for $i \in \{0, \dots, y - 1\}$ and $t_{i+kx} = y + \frac{(-1)^{i-y-1}}{2} + ky$ for $i \in \{y, \dots, x - 1\}$, and any $k \in \mathbb{Z}$. This sequence satisfies the conditions of Proposition 3.5, so that $(\eta_{t_i}(i) : i \in \mathbb{Z}) \sim p^{\mathbb{Z}}$. Since $L_{a,b} \subset \{(i, t_i) : i \in \mathbb{Z}\}$, the result follows.

THEOREM 4.6. — *Let us consider a PCA $A \in \mathcal{T}_S(p)$ satisfying Cond. 2 or Cond. 3. Then, for any line of its stationary space-time diagram $G = (A, \pi_p)$, nodes on that line are i.i.d.*

Proof. — We prove the result for a PCA $A \in \mathcal{T}_S(p)$ satisfying Cond. 2. In that case, A is r -quasi-reversible. Now, take any line L in G .

Let us now consider an equation of the form $y = ax + b$ with $|a| > 1$, or $x = c$. We can assume without loss of generality that $b = 0$. Let $(x, y) \in \mathbb{Z}_e^2$ be the first point with a positive coordinates belonging to the integer line, so that we have in particular $0 < |x| < y$. Then we can perform flips, similarly as the ones done in the proof of the Theorem 4.1, case $g = r$ (see Figure 4.3), to obtain that, for any m , the points $m\mathbf{u}, (m - 1)\mathbf{u}, \dots, \mathbf{u}, (0, 0), (x, y), (2x, 2y), \dots, (kx, ky)$ (with $k = \lfloor m/(x + y) \rfloor$) are i.i.d. In particular, $(0, 0), (x, y), (2x, 2y), \dots, (kx, ky)$ are i.i.d.

PCA with strong independence

Let us recall the notations $\mathbf{u} = (-1, 1)$, $\mathbf{v} = (1, 1)$.

DEFINITION 4.7. — *Let $G = (A, \mu)$ be a stationary space-time diagram of a PCA A under one of its invariant measure μ . We say that G is top (resp. bottom, left, right) i.i.d. if, for any $x \in \mathbb{Z}_e^2$, $\{\eta(x), \eta(x - \mathbf{u}), \eta(x - \mathbf{v})\}$ (resp. $\{\eta(x), \eta(x + \mathbf{u}), \eta(x + \mathbf{v})\}$, $\{\eta(x), \eta(x - \mathbf{u}), \eta(x + \mathbf{v})\}$ $\{\eta(x), \eta(x + \mathbf{u}), \eta(x - \mathbf{v})\}$) are i.i.d. A PCA is said to be 3-to-3 i.i.d. if it is top, bottom, left and right i.i.d.*

PROPOSITION 4.8. — *$G = (A, \mu)$ is both top and bottom i.i.d. if and only if $A \in \mathcal{T}_S$ and μ is its invariant HZPM.*

Proof. — Let $G = (A, \mu)$ be a top and bottom i.i.d. PCA. We denote by p the one-dimensional marginal of μ . Then, we have, for any $a, b, c, d \in S$,

$$\begin{aligned} \mathbb{P}(\eta(x) = d, \eta(x - \mathbf{u}) = a, \eta(x - \mathbf{v}) = c) &= p(a)p(d)p(c) \text{ (top i.i.d.)} \\ &= \sum_{b \in S} p(a)p(b)p(c)T(a, b, c; d) \text{ (bottom i.i.d.).} \end{aligned}$$

Hence, Cond. 1 holds and, by Theorem 3.1, $A \in \mathcal{T}_S(p)$, and $\mu = \pi_p$. The reverse statement is trivial.

PROPOSITION 4.9. — *$G = (A, \mu)$ is 3-to-3 i.i.d. if and only if A is a D_4 -quasi-reversible PCA of \mathcal{T}_S and μ is its invariant HZPM.*

Proof. — Let (A, μ) be a 3-to-3 i.i.d. PCA, then $A \in \mathcal{T}_S$ because A is both top and bottom i.i.d. Moreover,

$$\begin{aligned} p(a)p(b)p(d) &= \sum_{c \in S} p(a)p(b)p(c)T(a, b, c; d) \\ \text{and } p(c)p(b)p(d) &= \sum_{a \in S} p(a)p(b)p(c)T(a, b, c; d), \end{aligned}$$

using the fact that A is top and left (resp. right) i.i.d. But these are respectively Cond. 2 and Cond. 3 and, so, by Theorem 4.4, A is D_4 -quasi-reversible. The reverse statement is trivial.

Note that $G = (A, \mu)$ is top, bottom, and left (resp. right) i.i.d. if and only if A is a r -quasi-reversible PCA (resp. r^{-1} -quasi-reversible PCA) of \mathcal{T}_S and μ is its invariant HZPM.

Connection with previous results for PCA with memory one

In the special case when the PCA has memory one, meaning that the transition probabilities $T(a, b, c; d)$ do not depend on $b \in S$, Cond. 1 reduces to: $\forall a, c, d \in S, p(d) = T(a, \cdot, c; d)$. So, the only PCA having an invariant HZPM are trivial ones (no time dependence at all). In that context, it is in fact more relevant to study PCA having simply an invariant horizontal product measure, as done in [MM14b]. Observe that when there is no dependence on $b \in S$, Cond. 2 et Cond. 3 become

$$\forall a, d \in S, \sum_{c \in S} p(c)T(a, \cdot, c; d) = p(d) \text{ and } \forall c, d \in S, \sum_{a \in S} p(a)T(a, \cdot, c; d) = p(d).$$

We recover the two sufficient conditions for having an horizontal product measure, as described in Theorem 5.6 of [MM14b]. In that article, the space-time diagrams are represented on a regular triangular lattice, which is more adapted to the models that are considered. The authors show that under one or the other of these two conditions, there exists a transversal PCA, so that after an appropriate rotation of the triangular lattice, the stationary space-time diagram can also be described as the one of another PCA. With our terminology, this corresponds to a quasi-reversibility property.

4.3. PCA with an explicit invariant law that is not HZPM

As already mentioned, if a PCA $A \in \mathcal{T}_S(p)$ satisfies Cond. 2 and not Cond. 3 (or the reverse), we get a PCA $C = A_r$ (or $A_{r^{-1}}$) for which we can compute exactly the marginals of an invariant measure μ , see equations (4.5) and (4.6). Using the previous results, we can describe conditions on the transitions of a PCA C for being of the form $C = A_r$, with A having an invariant p -HZMP. We thus obtain next corollary, highlighting a family of PCA having an invariant measure that can be computed explicitly, although it does not have a well-identified form.

COROLLARY 4.10. — *Let C be a PCA with transition kernel U . If there exists a probability distribution p such that Cond. 2 and Cond. 3 hold, then there exists a unique probability distribution μ on $S^{\mathbb{Z}^0} \times S^{\mathbb{Z}^1}$ such that*

- μ is invariant by C ,
- (C, μ) is $\{r^{-1}, r\}$ -quasi-reversible and
 - its r^{-1} -reverse is $(C_{r^{-1}}, \pi_p)$ with $C_{r^{-1}} \in \mathcal{T}_S(p)$, and the transition kernel of $C_{r^{-1}}$ is equal to $U_{r^{-1}}$.
 - its r -reverse is (C_r, π_p) with $C_r \in \mathcal{T}_S(p)$, and the transition kernel of C_r is equal to U_r .
- $\mu|_{\mathbb{Z}^0} = p^{\mathbb{Z}^0}$ and $\mu|_{\mathbb{Z}^1} = p^{\mathbb{Z}^1}$.

Moreover, we have explicit formulas for marginals of μ .

In Section 7, Example 7.7 provides an example of a PCA satisfying only Cond. 2, so that its r -reverse A_r satisfies the conditions of Corollary 4.10 above.

5. Horizontal zigzag Markov chains

After having extensively studied PCA with memory two having an invariant measure with a product form, we now focus on PCA having an invariant measure with a Markovian form, with a similar approach. We characterize such PCA, and among them, those having a quasi-reversibility property, thus justifying the results that were announced in Table 2.2. As in the previous section, our results will also allow us to exhibit a new family of PCA having an invariant measure that can be computed explicitly, although it does not have a simple form.

5.1. Conditions for having an invariant HZMC

In this section, we recall some previous results obtained in [Cas18] about PCA with memory two having an invariant measure which is a Horizontal Zigzag Markov Chain. Our purpose is to keep the present article as self-contained as possible.

First, let us recall what is a (F, B) -HZMC distribution. This is the same notion as (D, U) -HZMC in [Cas18], but to be consistent with the orientation chosen here for the space-time diagrams, we prefer using the notations F for forward in time, and B for backward in time (rather than D for down and U for up). The definition we give below relies on the following Lemma 5.1.

LEMMA 5.1. — *Let S be a finite set, and let $F = (F(a; b) : a, b \in S)$ and $B = (B(b; c) : b, c \in S)$ be two positive transition matrices from S to S . We denote by ρ_B (resp. ρ_F) the invariant probability distribution of B (resp. F), that is, the normalised left-eigenvector of B (resp. F) associated to the eigenvalue 1. If $FB = BF$, then $\rho_B = \rho_F$.*

Proof. — Note that by Perron–Frobenius, B and F have a unique invariant probability distribution, satisfying respectively $\rho_B B = B$ and $\rho_F F = F$. Since $FB = BF$, we have $\rho_B FB = \rho_B BF = \rho_B F$, so that the vector $\rho_B F$ is an invariant probability distribution of B . By uniqueness, we obtain $\rho_B F = \rho_B$. Since the invariant probability distribution of F is also unique, we obtain $\rho_B = \rho_F$.

DEFINITION 5.2. — *Let S be a finite set, and let F and B be two transition matrices from S to S , such that $FB = BF$. We denote by ρ their (common) left-eigenvector associated to the eigenvalue 1. The (F, B) -HZMC (for Horizontal Zigzag Markov Chain) on $S^{\mathbb{Z}^t} \times S^{\mathbb{Z}^{t+1}}$ is the distribution $\zeta_{F,B}$ such that, for any $n \in \mathbb{Z}_t$, for any $a_{-n}, a_{-n+2}, \dots, a_n \in S, b_{-n+1}, b_{n+3}, \dots, b_{n-1} \in S$,*

$$\begin{aligned} \mathbb{P}((\zeta_{F,B}(i, t) = a_i, \zeta_{F,B}(i, t+1) = b_i : -n \triangleleft i \triangleleft n)) \\ = \rho(a_{-n}) \prod_{i=-n+1}^{n-1} F(a_{i-1}; b_i) B(b_i; a_{i+1}). \end{aligned}$$

We give a simple necessary and sufficient condition that depends on both T and (F, B) for a (F, B) -HZMC to be an invariant measure of a PCA with transition kernel T (in order to remove any ambiguity, let us precise that the definition of a transition kernel is exactly the same as in the previous sections).

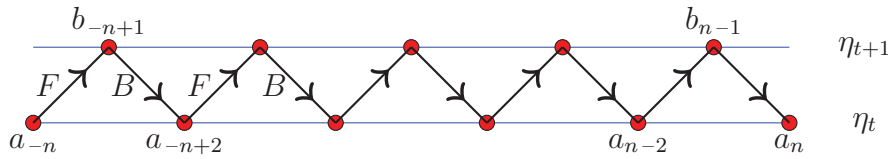


Figure 5.1. Illustration of Definition 5.2.

PROPOSITION 5.3 (Lemma 5.10 of [Cas18]). — Let S be a finite set. Let A be a PCA with positive rates and let F and B be two transition matrices from S to S . The (F, B) -HZMC distribution is an invariant probability distribution of A if and only if:

Cond. 4: for any $a, c, d \in S$, $F(a; d)B(d; c) = \sum_b \in S B(a; b)F(b; c)T(a, b, c; d)$.

We denote by $\mathcal{T}_S(F, B)$ the subset of positive-rates PCA with set of symbols S having an invariant (F, B) -HZMC.

In the context of PCA having an invariant (F, B) -HZMC, Proposition 3.5 can be extended as follows. The proof being similar, we omit it.

PROPOSITION 5.4. — Let $A \in \mathcal{T}_S(F, B)$, of stationary space-time diagram $G(A, \zeta_{F,B}) = (\eta_t(i) : t \in \mathbb{Z}, i \in \mathbb{Z}_t)$. For any zigzag polyline $(i, t_i)_{m \subset i \subset n}$, and any $(a_i)_{m \subset i \subset n} \in S^{n+1}$, we have

$$P(\eta(i, t_i) = a_i : m \subset i \subset n) = \rho(a_0) \prod_{\substack{m \in \{0, \dots, n-1\} \\ t_{i+1} = t_i + 1}} F(a_i; a_{i+1}) \prod_{\substack{m \in \{0, \dots, n-1\} \\ t_{i+1} = t_i - 1}} B(a_i; a_{i+1}).$$

In general, the knowledge of the transition kernel T alone is not sufficient to be able to tell if the PCA A admits or not an invariant (F, B) -HZMC. Until now, the characterization of PCA having an invariant (F, B) -HZMC is known in only two cases: when $|S| = 2$ [Cas18, Theorem 5.3], and when $F = B$ [Cas18, Theorem 5.2]. In the other cases ($F \neq B$ and $|S| > 2$), it is an open problem.

5.2. Quasi-reversible PCA with invariant HZMC

This section is devoted to PCA having an HZMC invariant measure, and that are (quasi-)reversible.

Let $A \in \mathcal{T}_S(F, B)$. For $a, b \in S$, let us define

$$M_u(b; a) = \frac{\rho(a)}{\rho(b)} B(a; b) \text{ and } M_{-v}(b; a) = \frac{\rho(a)}{\rho(b)} F(a; b).$$

We also introduce the notations $M_{-u} = B$ and $M_v = F$ (recall that $u = (-1, 1)$ and $v = (1, 1)$). For $g \in D_4$, we define

$$p_{FB}(g(a, b, c)) = \rho(g(a)) M_{g(-u)}(g(a), g(b)) M_{g(v)}(g(b), g(c)),$$

where $g(-u)$ corresponds to the vector $g(a)g(b)$, and $g(v)$ to $g(b)g(c)$ (note again the small abuse of notation for the images of the vertices by the permutation induced

by g). If g is the identity, we have $p_{FB}(a, b, c) = \rho(a)B(a, b)F(b, c)$. And for example in the case where $g = r$, we have

$$p_{FB}(r(a, b, c)) = p_{FB}(d, a, b) = \rho(d)M_{-v}(d, a)B(a, b) = \rho(a)F(a, b)B(a, b).$$

From the transition kernel T of A , we define a map $T_g : S^3 \times S \rightarrow \mathbb{R}_+$ by:

$$\forall a, b, c, d \in S, \quad T_g(g(a, b, c); g(d)) = \frac{p_{FB}(a, b, c)}{p_{FB}(g(a, b, c))}T(a, b, c; d).$$

For example, in the case where $g = r$, this gives:

$$(5.1) \quad \forall a, b, c, d \in S, \quad T_r(d, a, b; c) = \frac{F(b; c)}{F(a; d)}T(a, b, c; d).$$

The expressions of T_{r^2}, T_h , and $T_{r^{-1}}$ can be found in Table 2.2.

Observe that T_g is not necessarily a transition kernel. For example, T_r is a transition kernel if and only if:

$$\forall a, c, d \in S, \quad \sum_c \frac{F(b; c)}{F(a; d)}T(a, b, c; d) = 1,$$

which is equivalent to Cond. 5, see again Table 2.2. Analogously, $T_{r^{-1}}$ is a transition kernel if and only if Cond. 6 is satisfied. And it appears that as soon as a PCA belongs to $\mathcal{T}_S(F, B)$, T_{r^2} and T_h are transition kernels, since Cond. 4 is satisfied.

THEOREM 5.5. — *A PCA $A \in \mathcal{T}_S(F, B)$ of transition kernel T is g -quasi-reversible if and only if T_g is a transition kernel. In that case, T_g is the transition kernel of the g -reverse A_g of A .*

The next result is a direct consequence of Theorem 5.5.

COROLLARY 5.6. — *Any PCA $A \in \mathcal{T}_S(F, B)$ is r^2 -quasi-reversible and h -quasi-reversible.*

Proof of Theorem 5.5. — The cases $g = \text{id}$ and $g = v$ are obvious by Proposition 2.7, and the cases $g = h$ and $g = r^2$ can be handled exactly as in the proof of Theorem 4.1. We thus focus on the case $g = r$, for which the proof also follows the same idea as in Theorem 4.1. Suppose that A is r -quasi-reversible, and denote by \tilde{T} the transition kernel of A_r . Then, for any $a, b, c, d \in S$, and any $x \in Z_e^2$,

$$(5.2) \quad \begin{aligned} \tilde{T}(d, a, b; c) &= \mathbb{P}(\eta(x + v) = c | \eta(x + u + v) = d, \eta(x + u) = a, \eta(x) = b) \\ &= \frac{\rho(a)B(a; b)F(b; c)T(a, b, c; d)}{\sum_c \rho(a)B(a; b)F(b; c)T(a, b, c; d)} = \frac{F(b; c)T(a, b, c; d)}{\sum_c F(b; c)T(a, b, c; d)}. \end{aligned}$$

For some $x \in Z_e^2$, let us reintroduce the pattern $L = (x, x + u, x + v, x + 2u, x + u + v, x + 2u + v)$, see Figure 4.1. For $a_0, b_0, b_1, c_0, c_1, d_0 \in S$, we are interested in the quantity: $Q(a_0, b_0, b_1, c_0, c_1, d_0) = \mathbb{P}(\eta(L) = (a_0, b_0, b_1, c_0, c_1, d_0))$.

On the one hand, we have

$$\begin{aligned} Q(a_0, b_0, b_1, c_0, c_1, d_0) \\ = \rho(c_0)B(c_0; b_0)B(b_0; a_0)F(a_0; b_1)T(b_0, a_0, b_1; c_1)T(c_0, b_0, c_1; d_0). \end{aligned}$$

On the other hand, we have

$$Q(a_0, b_0, b_1, c_0, c_1, d_0) = \sum_{b_1, c_1 \in S} Q(a_0, b_0, b_1, c_0, c_1, d_0) \tilde{T}(d_0, c_0, b_0; c_1) \tilde{T}(c_1, b_0, a_0; b_1).$$

Using the expressions of $\tilde{T}(d_0, c_0, b_0; c_1)$ and $\tilde{T}(c_1, b_0, a_0; b_1)$ given by (5.2) and simplifying, we get:

$$\begin{aligned} \left(\sum_b F(a_0; b) T(b_0, a_0, b; c_1) \right) \left(\sum_c F(b_0; c) T(c_0, b_0, c; d_0) \right) \\ = F(b_0; c_1) \sum_{b, c \in S} F(a_0; b) T(b_0, a_0, b; c) T(c_0, b_0, c; d_0). \end{aligned}$$

Now summing on $d_0 \in S$, we find, for any $b_0, c_1 \in S$,

$$F(b_0; c_1) = \sum_b F(a_0; b) T(b_0, a_0, b; c_1),$$

so that $\tilde{T} = T_r$.

Conversely, suppose that A is a PCA having an invariant measures (F, B) -HZMC and that Cond. 5 holds. Then, we can perform flips thanks to (5.1) as in Figures 4.2 and 4.3 to obtain the result.

5.3. PCA with an explicit invariant law that is not HZMC

As mentioned in Section 4.3, there exist PCA $A \in \mathcal{T}_S(p)$ that are r -quasi-reversible, and for which the r -reverse A_r does not belong to $\mathcal{T}_S(p)$. In that case, A_r has an invariant measure μ which is not a product measure, and for which we know formulas allowing to compute exactly all the marginals, see equations (4.5) and (4.6). Let us point out that the measure μ cannot be a (F, B) -HZMC. Indeed, consider the stationary space-time diagram $(A, \pi_p) = (\eta(i, t) : (i, t) \in \mathbb{Z}_e^2)$, and assume that μ is a (F, B) -HZMC measure. Then, the marginal of size one of μ is equal to $\rho = p$, and for any $x \in \mathbb{Z}_e^2$, we have $\mathbb{P}(\eta(x + u) = a, \eta(x) = b) = p(a)p(b) = \rho(a)F(a; b)$ and $\mathbb{P}(\eta(x) = b, \eta(x + v) = c) = p(b)p(c) = \rho(c)B(c; b)$. Thus, we obtain $F(a; b) = B(c; b) = p(b)$ for any $a, b, c \in S$, meaning that the (F, B) -HZMC is in fact a p -HZMP, which is not possible since A_r does not belong to $\mathcal{T}_S(p)$.

So, the PCA A_r has an invariant measure that we can compute, and that has neither a product form nor a Markovian one. That was a real surprise of this work. We give an explicit example of such a PCA in Section 7, see Example 7.7.

Similarly, if a PCA A with a (F, B) -invariant HZMC is r -quasi-reversible, and is such that its r -reverse A_r does not have an invariant HZMC, then we can compute exactly the invariant measure of A_r , although it does not have a well-known form. This provides an analogous of Corollary 4.10, in the Markovian case. Precisely, next Corollary 5.7 gives conditions on the transitions of a PCA C for being of the form $C = A_r$, with A having a (F, B) -invariant HZMC. To the best knowledge of the authors, this is the first time that we can compute from the transition kernel an invariant law that is not Markovian.

COROLLARY 5.7. — *Let C be a PCA of positive transition kernel U . If there exist two positive transition matrices F and B from S to S such that $FB = BF$, and such that the two following conditions hold:*

Cond. 7. — *for any $a, b, c \in S$, $F(b; c) = \sum_d {}_S F(a; d)U(d, a, b; c)$;*

Cond. 8. — *for any $a, c, d \in S$, $B(d; c) = \sum_b {}_S B(a; b)U(d, a, b; c)$;*

then there exists a probability measure μ on S such that

- μ is invariant by C ,
- (C, μ) is $\{r, r^{-1}\}$ -quasi-reversible and
 - its r^{-1} -reverse is $(C_{r^{-1}}, \zeta_{F,B})$, with $C_{r^{-1}} \in \mathcal{T}_S(F, B)$, and the transition kernel of $C_{r^{-1}}$ is given by $T(a, b, c; d) = \frac{F(a;d)}{F(b;c)}U(d, a, b; c)$.
 - its r -reverse is $(C_r, \zeta_{M_u, M_{-v}})$, with $C_r \in \mathcal{T}_S(M_u, M_{-v})$, and the transition kernel of C_r is given by $T_{r^2}(c, d, a; b) = \frac{B(a;b)}{B(d;c)}U(d, a, b; c)$.

Moreover, we have explicit formulas for marginals of μ .

Note that in the above Theorem 5.5, the transition kernel T , which is the transition kernel of $C_{r^{-1}}$, corresponds to the transition kernel of the PCA A (having a (F, B) -invariant HZMC) such that $C = A_r$. The transition kernels T of $C_{r^{-1}}$ and T_{r^2} of C_r can be written as being equal respectively to $U_{r^{-1}}$ and U_r , but with (F, B) replaced by (B, M_{-v}) when applying the formulas given in Table 2.2.

Remark 5.8. — In Cond. 7 (resp. Cond. 8), by putting $a = b$ (resp. $a = d$), we find that for any $a \in S$, the vector $(F(a; d) : d \in S)$ (resp. $(B(a; b) : b \in S)$) is the left eigenvector of $(U(d, a, a; c))_{d,c \in S}$ (resp. $(U(a, a, b; c))_{b,c \in S}$) associated to the eigenvalue 1. In particular, this allows to determine F and B , knowing only U . This is in contrast with Proposition 5.3, where in general, the knowledge of T does not allow to find F and B .

Proof. — Let us define

$$T(a, b, c; d) = \frac{F(a; d)}{F(b; c)}U(d, a, b; c).$$

Then, as Cond. 7 and Cond. 8 hold, we can check that T is a transition kernel and satisfies Cond. 4, so $\zeta_{F,B}$ is an invariant measure of the PCA whose transition kernel is T . Moreover,

$$\sum_{c \in S} F(b; c)T(a, b, c; d) = \sum_{c \in S} F(a; d)U(d, a, b; c) = F(a; d).$$

That is Cond. 5, and we conclude by application of Theorem 5.5 (case $g = r$). Finally, multidimensional laws of μ are deduced from the space-time diagram (C, μ) . Indeed, after action of the rotation r^{-1} , it has the same distribution as $(C_{r^{-1}}, \zeta_{F,B})$ whose transition kernel is T . So, we can compute all the finite-dimensional marginals of the space-time diagram, and in particular the multidimensional laws of μ .

6. Applications to statistical physics

In many models of statistical physics (6 and 8-vertex models, enumeration of directed animals, TASEP model, First Passage Percolation / Last Passage Percolation,

Eden growth model, Box-Ball Systems...), one can find a PCA of order 1 or 2 that provides an alternative description of the system. In most cases, the original models are integrable only on a submanifold of their parameter space, and this corresponds to choices of parameters for which the corresponding PCA has a simple invariant measure, with a product or a Markovian structure.

In Section 6.1 and 6.2, we show that using this PCA approach, results of previous sections provide new proofs of known results about the 8-vertex model and about the enumeration of directed animals, after associating suitable PCA with these two models. This gives a simpler alternative to transfer-matrix methods, that does not require tedious computations.

The PCA approach also often suggests relevant ways to extend the initial models of statistical physics. Let us indeed assume that when studying the PCA involved, it appears that the family of parameters for which they have a closed-form invariant measure belong to a larger submanifold, defined with more parameters. Then, one can try to backtrack this observation to the original model, by the introduction of new parameters preserving the physical meaning of the model, with a larger domain of parameters on which the model is integrable. This is what we illustrate in Section 6.3, where we define a new TASEP model with variable speed that extends the classical parallel TASEP. The results of previous sections (Theorem 3.1 and Proposition 5.3) do not apply directly because the PCA does not have positive rates. Nevertheless, our techniques can still be used to compute some invariant measures of this new model.

6.1. The 8-vertex model

For some $k \in 2\mathbb{Z}$, we consider the graph G_k whose set of vertices is $V_k = \mathbb{Z}_e^2 \cap [-k, k]^2$, the restriction of the even lattice to a finite box, and whose set of edges is $E_k = \{(x, x + u) : x, x + u \in V_k\} \cup \{(x, x + v) : x, x + v \in V_k\}$. We define the boundary of V_k by $\partial V_k = \{(x_1, x_2) \in V_k : \max(|x_1|, |x_2|) = k\}$.

For each edge of G_k , we choose an orientation. This defines an orientation O of G_k , and we denote by O_k the set of orientations of G_k . For a given orientation $O \in O_k$, and an edge $e \in E_k$, we denote:

$$o(e) = \begin{cases} 0 & \text{if the edge } e \text{ is oriented from top to bottom in } O \text{ (}\searrow \text{ or } \swarrow\text{),} \\ 1 & \text{if the edge } e \text{ is oriented from bottom to top in } O \text{ (}\swarrow \text{ or } \searrow\text{).} \end{cases}$$

Hence, an orientation $O \in O_k$ can be seen as an element $(o(e))_{e \in E_k}$ of $\{0, 1\}^{E_k}$.

Around each vertex $x \in V_k \setminus \partial V_k$, there are 4 oriented edges, giving a total of 16 possible local configurations, defining the *type* of the vertex x . In the 8-vertex model case, we consider only the orientations O such that around each vertex $x \in V_k \setminus \partial V_k$, there is an even number (0, 2 or 4) of incoming edges, so that only 8 local configurations remain, see Figure 6.1. To each local configuration i among these 8 local configurations, we associate a local weight $w_i > 0$. This allows to define a global weight W on the set \tilde{O}_k of admissible orientations, by:

$$W(O) = \prod_{x \in V_k \setminus \partial V_k} w_{\text{type}(x)}, \quad \text{for } O \in \tilde{O}_k.$$

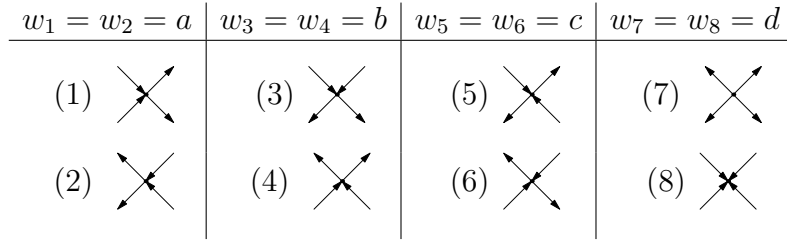


Figure 6.1. The 8 possible local configurations around any vertex.

Thanks to these weights, we finally define a probability distribution P_W on \tilde{O}_k , by:

$$P_W(O) = \frac{W(O)}{Z_k}, \quad \text{with} \quad Z_k = \sum_{O \in \tilde{O}_k} W(O).$$

In the following, we assume that the parameters satisfy $w_1 = w_2 = a$, $w_3 = w_4 = b$, $w_5 = w_6 = c$ and $w_7 = w_8 = d$, which corresponds to the most studied 8-vertex model. We furthermore assume that $a + c = b + d$. Let us briefly comment on this condition. Among 6 and 8-vertex models, a different case that has attracted much attention is the case when $a = b$, which corresponds to the *XXZ model* [DCGH⁺18]. But from a physical point of view, this condition is quite restrictive, since it amounts to assuming that the oxygen atoms are arranged on a square lattice. We can relax this condition by assuming that the oxygen atoms are arranged on a diamond-shaped lattice, and within this framework, an interesting specific case for some ranges of temperature and pressure consists in assuming that $a + c = b + d$. As we will see, from a mathematical point of view, this choice of parameters has also the advantage of allowing simple explicit computations. For more information on the 8-vertex model, we refer the interested reader to [Bax82, Cas16, DCGH⁺18, Mel18], and references therein. In [BCG16], the authors study the 6-vertex model under an analogous condition, using *transfer matrices*. Understanding the links between these two techniques would be a very interesting subject, but the authors of the present article are not yet sufficiently familiar with these techniques to achieve this.

Following Baxter [Bax82, Section 10.2], let us define a “two-to-one” map \mathcal{C}_8 between 2-colorings of faces of G_k and admissible orientations of the 8-vertex model on G_k . Let F_k be the set of faces of G_k , that is, the set of quadruples $(x, x + u, x + u + v, x + v) \in (\mathbb{Z}_e^2)^4$ for which at least 3 of the 4 vertices belong to G_k . Let $C \in \{0, 1\}^{F_k}$ be a 2-coloring of faces of G_k , and take any edge $e \in E_k$. We denote by f_e and f_e the two adjacent faces of e . The map consists in setting:

$$o(e) = \begin{cases} 1 & \text{if } C(f_e) = C(f_e), \\ 0 & \text{otherwise (i.e. if } C(f_e) \neq C(f_e)). \end{cases}$$

It is a “two-to-one” map because from an admissible orientation O , we obtain two 2-colorings in $\mathcal{C}_8^{-1}(O) = \{C_0, C_1\}$. These two colorings satisfy $C_0(f) = 1 - C_1(f)$ for any $f \in F_k$, see Figure 6.2.

Let us set $q = a/(a + c)$ and $r = b/(b + d)$, and consider the PCA A_8 defined in Section 2.1. We denote \mathcal{F}_k the law of its space-time diagram $G(A_8, \pi_p)$ under its invariant measure π_p restricted to G_k .

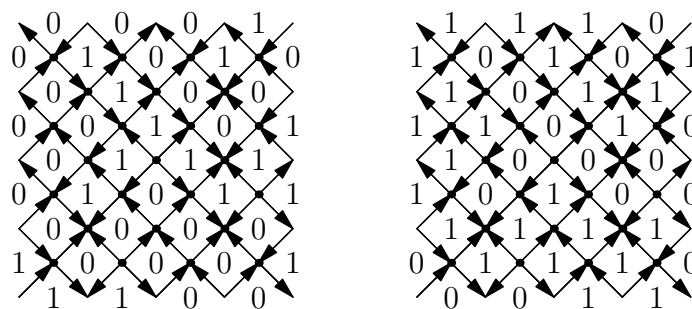


Figure 6.2. An orientation O and its two possible 2-colorings.

PROPOSITION 6.1 (Lemma 5.4 and Proposition 1.3 of [Cas18]). — If $C \sim \mathcal{F}_k$, then $\mathcal{C}_8(C) \sim P_W$.

This proposition is the first application of PCA with memory two in the literature. One can check that the PCA A_8 satisfies Cond. 1 with $p(0) = p(1) = 1/2$. Theorem 3.3 implies that this PCA is ergodic. When $n \rightarrow \infty$, the center of the square has the same behaviour whatever the boundary conditions are [Cas18, Proposition 1.6].

Note that in what precedes, we have assumed that the weights satisfy the relation $a + c = b + d$. If we now assume that they rather satisfy $a + d = b + c$, we can design a PCA that, when iterated from left to right (or equivalently, from right to left), generates configurations distributed according to the required distribution P_W . When $a = b$ and $c = d$, so that both relations are satisfied, we obtain $q = r$, and the dynamics is D_4 -reversible.

6.2. Enumeration of directed animals

In this section, we give a new proof about a known result (Lemma 6.3) about enumerations of directed animals. Our new proof is based on the fact that, to any PCA with memory 2 with an HZMC invariant law, one can associate a PCA with memory 1 with the same invariant law.

A directed animal on the square lattice (resp. on the triangular lattice) is a set $A \subset \mathbb{Z}_e^2$ such that $(0, 0) \in A$ and, for any $z \in A$ there exists a directed path $w = ((0, 0) = x_0, x_1, \dots, x_{m-1}, x_m = z)$ such that, for any $1 \leq k \leq m$,

$$x_k - x_{k-1} \in \{u, v\} \text{ (resp. } \{u, v, u + v\}),$$

see Figure 6.2 for an illustration on the triangular lattice. Let us denote by \mathcal{A}_S (resp. \mathcal{A}_T) the set of directed animals on the square (resp. triangular) lattice.

The *area* of an animal A is the cardinal of A and the *perimeter* of an animal A is the cardinal of $P(A) = \{x : x \notin A, \{x\} \cup A \text{ is a directed animal}\}$. Let us introduce the generating functions of directed animals enumerated according to their area, on the square lattice and on the triangular lattice:

$$G_S(z) = \sum_{A \in \mathcal{A}_S} z^{|A|} \qquad G_T(z) = \sum_{A \in \mathcal{A}_T} z^{|A|}.$$

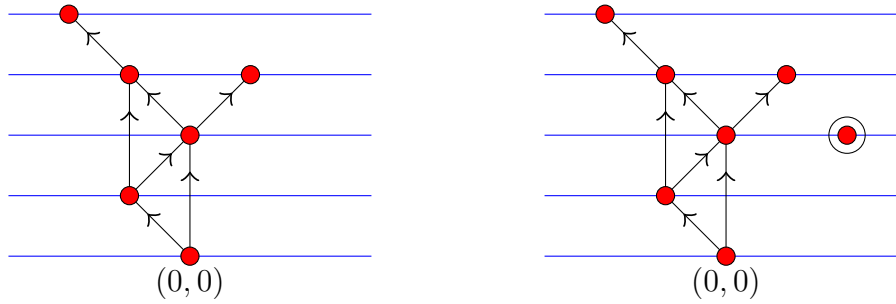


Figure 6.3. The set on the left is a directed animal on the triangular lattice, while the set on the right is not.

The computation of these series was done by Dhar in 1982 via the study of hard-particles model [Dha82]. Here, we will present this work using PCA, see also [MM14a] for details. Let us introduce the binary state PCA B_S with memory one, and the binary state PCA B_T with memory two, defined respectively by the following transition kernels:

$$T_S(a, b; 1) = \begin{cases} p_S & \text{if } a = b = 0, \\ 0 & \text{else.} \end{cases} \quad T_T(a, b, c; 1) = \begin{cases} p_T & \text{if } a = b = c = 0, \\ 0 & \text{otherwise.} \end{cases}$$

The following Theorem 6.2 connects the generating functions G_S and G_T with these PCA.

THEOREM 6.2 ([Dha82, BM98, LBM07]). — *For any $p_S, p_T \in (0, 1)$, let $(\eta_S(i, t) : (i, t) \in \mathbb{Z}_e^2)$ and $(\eta_T(i, t) : (i, t) \in \mathbb{Z}_e^2)$ be respectively the space-time diagram of B_S and B_T under their invariant probability measures. Then,*

$$\mathbb{P}(\eta(0, 0) = 1) = -G_S(-p_S) \quad \mathbb{P}(\eta(0, 0) = 1) = -G_T(-p_T).$$

In the case of directed animal on the square lattice, it is well known that B_S has a simple (F, B) -HZMC invariant measure, that can be computed explicitly, see [BM98, CM15, Dha82, LBM07]. Note also that the ergodicity of B_S , for any choice of $p_S \in (0, 1)$, was proven in [HMM19]. Using Proposition 5.3, one obtain that if $p_S = \frac{p_T}{1+p_T}$, then Cond. 4 holds, so that the same (F, B) -HZMC is also an invariant measure of B_T . We thus obtain the following Lemma 6.3 (although B_S and B_T do not have positive rates, we can easily extend our sufficient conditions to them).

LEMMA 6.3. — *We have the following:*

$$(6.1) \quad G_T \left(\frac{z}{1+z} \right) = G_S(z).$$

This allows to obtain the expression of the area generating function of directed animals on the triangular lattice from the one on the square lattice. We give below the two expressions of G_S and G_T .

THEOREM 6.4 ([BM98, Dha82]). — *The area generating function of directed animals on the square lattice and on the triangular lattice are respectively given by:*

$$G_S(z) = \frac{1}{2} \left(\left(1 - \frac{4z}{1+z} \right)^{-1/2} - 1 \right) \quad \text{and} \quad G_T(z) = \frac{1}{2} \left((1 - 4z)^{-1/2} - 1 \right).$$

The same questions can be asked for the enumeration according to area and perimeter, but in this case we have no explicit description of the invariant measures of the PCA involved. For more references on the question, see [LBM07, MM14a].

6.3. Parallel TASEP of order two

The TASEP (Totally ASymmetric Exclusion Process) describes the evolution of some particles that go from the left to the right on a line without overtaking. There are various kinds of TASEP models, with discrete or continuous time and space, and one or more types of particles. We refer the interested readers to the following articles [BC15, BF05, GG01] for the description of some models with discrete time and space. Here, we present a new (to the best knowledge of the authors) generalization of TASEP called TASEP of order two on real line and discrete time.

The TASEP presented here models the behaviour of an infinite number of particles (indexed by Z) on the real line, that move to the right, and that do not bypass and do not overlap. For $i, t \in Z$, we denote by $x_i(t) \in \mathbb{R}$ the position of particle i at time t . Time is discrete, and at time t , each particle $i \in Z$ moves with a random speed $v_i(t)$, independently of the others. The random speed $v_i(t)$ depends on the distance $x_{i+1}(t) - x_i(t)$ between the particle i and the particle $i + 1$ in front of it, and of the speed $v_{i+1}(t - 1) = x_{i+1}(t) - x_{i+1}(t - 1)$ of the particle $i + 1$ at time $t - 1$. Formally, the evolution of $(x_i(t))_{i \in Z}$ is defined by:

$$\forall i \in Z, \quad x_i(t + 1) = x_i(t) + v_i(t),$$

where $v_i(t)$ is random and distributed following $\mu_{(x_{i+1}(t) - x_i(t), v_{i+1}(t-1))}$, a probability distribution on \mathbb{R}^+ , and $(v_i(t))_{i \in Z}$ are independent, knowing $(x_i(t))_{i \in Z}$ and $(x_i(t - 1))_{i \in Z}$.

It is known that TASEP with discrete time can be represented by PCA [Cas16, MM14a]. We adopt the approach presented in [Cas16] to show that the TASEP of order two can be represented by a PCA with memory two: take $\eta(i, t) = x_i(t)$, then $(\eta(i, t) : i \in Z, t \in \mathbb{N})$ is the space-time diagram of a PCA with memory two whose transition kernel T is, for any $a \in \mathbb{R}, x, y, v \in \mathbb{R}^+$,

$$T(a, a + x, a + x + y; a + v) = \mu_{(x+y,y)}(v).$$

Now, we will focus as an example on the simplest case where $v \in \{0, 1\}$ a.s. and particles move on the integer line (for any $i \in Z, t \in \mathbb{N}, x_i(t) \in Z$). The constraints we have on T are the following:

- $T(a, a + 1, a + 1; a) = 1$ for any $a \in Z$ (and $T(a, b, b + i; c)$ can take any value if $i \neq 0, 1$ or $b \notin a$),
- $T(a, a + k, a + k + i; c) = 0$ for any $a, k > 0, i \in \{0, 1\}$ and $c \notin \{a, a + 1\}$,
- $T(a, a + k, a + k + i; a) = T(b, b + k, b + k + i; b)$ for any $k > 1, i \in \{0, 1\}, a, b \in Z$.

The first two points mean that the next position has to be empty for a particle to move, and that a particle can only move of one unit forward. The last point is an hypothesis of translation invariance. Hence, the PCA can be described by the

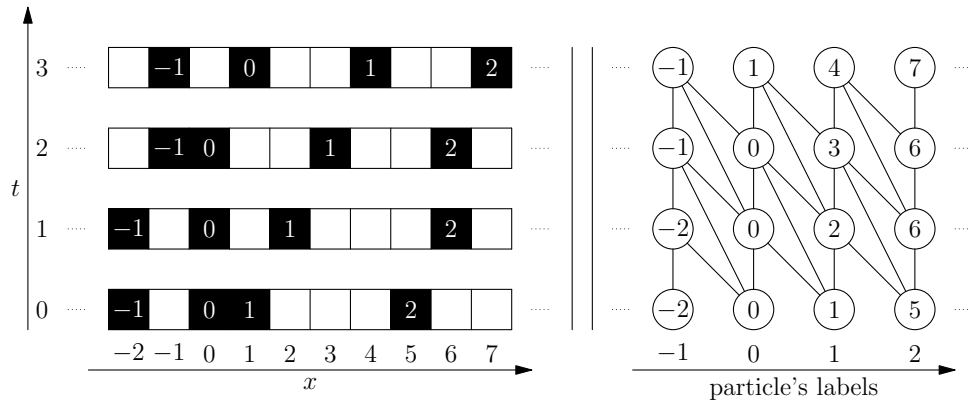


Figure 6.4. On the left, the classical representation of a TASEP: a white square is an empty square; a black square is a square that contains a particle, the white number is the label of this particle. On the right, the PCA that represents this TASEP; each column represents the trajectory of a particle.

transitions $(T(0, k, k; 0))_{k>2}$ and $(T(0, k, k + 1; 0))_{k>1}$. Although this PCA is not with positive rates and does not admit an invariant measure, it has some interesting properties that permit to find invariant measures for the parallel TASEP.

The model above is reminiscent of q -TASEP models as defined in [BC15]. In particular, the discrete time *Bernoulli q -TASEP* can be interpreted as a TASEP of order two with a time change. In contrast to our model, the number of particles is assumed to be finite, and at each time step, the positions of the particles are updated successively from right to left: each particle can move by one unit, with a probability that depends both on the length of the gap with the foregoing particle and on the fact that the jump of the foregoing particle did occur or not. The *Poisson q -TASEP* is a continuous time TASEP, but it also shares the property that the rate at which particles jump forward is modulated by the distance to the next particle, which is also the case of the discrete time *geometric q -TASEP*. In this last model, particles can move by several units in one time step. It follows that the geometric q -TASEP is tightly related to TAZRP models, and as we may detail in a future work, the PCA approach can be extended to these models.

The first result of this section is about the fact that there exists a family of (F, B) -HZMC that is stable by this PCA. First, let us define a (q, p) -HZMC for any probability q and p on \mathbb{Z} : a (q, p) -HZMC is a (F, B) -HZMC such that, for any $a, k \in \mathbb{Z}$, $F(a; a + k) = q(k)$ and $B(a; a + k) = p(k)$.

LEMMA 6.5. — For any transition kernel T , if there exist p a probability on \mathbb{N} and q on $\{0, 1\}$ such that, for any $k > 1$,

$$(6.2) \quad p(k)q(1)T(0, k, k + 1; 0) + p(k + 1)q(0)T(0, k + 1, k + 1; 0) = p(k + 1)q(0)$$

then if we start under the law such that (η_0, η_1) is a (q, p) -HZMC with $\eta_0(0) = 0$ a.s., then any double line (η_t, η_{t+1}) is also distributed as a (q, p) -HZMC but the starting

point is now $\eta_t(0)$ with

$$P(\eta_t(0) = k) = \binom{t}{k} q(1)^k q(0)^{t-k}.$$

Note that (6.2) also implies

$$(6.3) \quad p(k)q(1)T(0, k, k + 1; 1) + p(k + 1)q(0)T(0, k + 1, k + 1; 1) = p(k)q(1),$$

both equations being equivalent to:

$$(6.4) \quad p(k)q(1)T(0, k, k + 1; 0) = p(k + 1)q(0)T(0, k + 1, k + 1; 1).$$

These two conditions (6.2) and (6.3) are similar to Cond. 4 of Proposition 5.3.

Proof. — The proof is done by induction on $t \in \mathbb{N}$. For $t = 0$, we assume that (η_0, η_1) is a (q, p) -HZMC with $\eta_0(0) = 0$ a.s. Now, let us suppose that (η_t, η_{t+1}) is a (q, p) -HZMC with $P(\eta_t(0) = k) = \binom{t}{k} q(1)^k q(0)^{t-k}$. Then, by conditioning on the possible values $(a_i)_{0 \leq i \leq k+1}$ for $(\eta_t(i))_{0 \leq i \leq k+1}$, we obtain that the finite dimensional laws of (η_{t+1}, η_{t+2}) are given by:

$$\begin{aligned} & P((\eta_{t+1}(i) = b_i)_{0 \leq i \leq k}, (\eta_{t+2}(i) = c_i)_{0 \leq i \leq k-1}) \\ &= \sum_{a_0, \dots, a_{k+1}} \binom{t}{a_0} q(1)^{a_0} q(0)^{t-a_0} q(b_0 - a_0) \prod_{i=0}^{k-1} p(a_{i+1} - b_i) q(b_{i+1} - a_{i+1}) T(b_i, a_{i+1}, b_{i+1}; c_i) \\ &= \left(\sum_{a_0} \binom{t}{a_0} q(1)^{a_0} q(0)^{t-a_0} q(b_0 - a_0) \right) \\ & \quad \left(\prod_{i=0}^{k-1} \sum_{a_{i+1}} p(a_{i+1} - b_i) q(b_{i+1} - a_{i+1}) T(b_i, a_{i+1}, b_{i+1}; c_i) \right). \end{aligned}$$

Since the only non-zero terms correspond to $a_i \in \{b_i, b_i - 1\}$, the left parenthesis is equal to:

$$\sum_{a_0 \in \{b_0, b_0 - 1\}} \binom{t}{a_0} q(1)^{a_0} q(0)^{t-a_0} q(b_0 - a_0) = \binom{t + 1}{b_0} q(1)^{b_0} q(0)^{t+1-b_0},$$

and the right one to:

$$\begin{aligned} & \prod_{i=0}^{k-1} \sum_{a_{i+1} \in \{b_{i+1}, b_{i+1} - 1\}} p(a_{i+1} - b_i) q(b_{i+1} - a_{i+1}) T(b_i, a_{i+1}, b_{i+1}; c_i) \\ &= \prod_{i=0}^{k-1} \sum_{a_{i+1} \in \{b_{i+1}, b_{i+1} - 1\}} p(a_{i+1} - b_i) q(b_{i+1} - a_{i+1}) T(0, a_{i+1} - b_i, b_{i+1} - b_i; c_i - b_i) \\ &= \prod_{i=0}^{k-1} p(b_{i+1} - c_i) q(c_i - b_i), \quad \text{using (6.2) and (6.3)}. \end{aligned}$$

We can remark that q is the speed law of a particle under the stationary regime and p the distance law between two successive particles (to be precise the left one at current time t and the right one at previous time $t - 1$).

THEOREM 6.6. — For any T , for any distribution q on $\{0, 1\}$ such that

$$(6.5) \quad Z = \sum_{k=0}^{\infty} \left(\frac{q(1)}{q(0)} \right)^k \prod_{m=1}^k \frac{T(0, m, m+1; 0)}{T(0, m+1, m+1; 1)} < \infty,$$

there exists a unique distribution p on \mathbb{N} such that (6.2) hold.

Moreover, this distribution p is, for any $k > 1$,

$$(6.6) \quad p(k) = \frac{\left(\frac{q(1)}{q(0)} \right)^{k-1} \prod_{m=1}^{k-1} \frac{T(0, m, m+1; 0)}{T(0, m+1, m+1; 1)}}{Z}.$$

Proof. — Let q be a probability measure on $\{0, 1\}$. By (6.4), we have

$$(6.7) \quad \forall k > 1, \quad p(k+1) = p(k) \frac{T(0, k, k+1; 0)}{T(0, k+1, k+1; 1)} \frac{q(1)}{q(0)}.$$

By induction, we obtain

$$\forall k > 1, \quad p(k+1) = \left(\frac{q(1)}{q(0)} \right)^k \prod_{m=1}^k \frac{T(0, m, m+1; 0)}{T(0, m+1, m+1; 1)} p(1)$$

As $\sum_{k \in \mathbb{N}} p(k) = 1$, we need (6.5). In that case, (6.6) follows.

In the classical case of parallel TASEP (presented in [MM14a, Sections 2.3 & 4.3], [Cas16, Section 3.3]), we have

$$(6.8) \quad T(0, k, k+1; 1) = T(0, k+1, k+1; 1) = p.$$

With Theorem 6.6, we recover the invariant measures of the classical parallel TASEP and can express the one of the generalized TASEP as a renewal process.

COROLLARY 6.7. — For any distribution q on $\{0, 1\}$ such that (6.5) holds and p (given by (6.6), with $p(0) = 0$) has a finite mean, the TASEP of order 2 has an invariant measure on $\{0, 1\}^{\mathbb{Z}} \times \{0, 1\}^{\mathbb{Z}}$ such that on the same line, the distance between two consecutive 1s are i.i.d. and distributed according to γ with, for any $k > 1$, $\gamma(k) = q(0)p(k) + q(1)p(k-1)$.

This example goes beyond our previous framework for many reasons. First, the PCA does not have positive rates. Second, studying the invariant measures of this PCA is not interesting because they only correspond to states where nobody moves. That is why we have focused here on families of distributions that are stable by the PCA rather than on only one invariant distribution. And by studying carefully the eigenvectors on the good subspaces, we are able to solve the algebraic issues. This provides some interesting results on a PCA with an infinite alphabet, involving a family of (F, B) -HZMC laws (with $F \neq B$), whereas our main explicit results on PCA involve general (F, B) -HZMC measures but on an alphabet of size 2, or PCA with a general alphabet but with an invariant (F, F) -HZMC (see the end of Section 5.1 and Section 8).

7. The binary case

In this section, we specify the conditions obtained in Section 4 to the case of a binary symbol set $S = \{0, 1\}$.

PROPOSITION 7.1. — For a binary symbol set $S = \{0, 1\}$,

- (1) Cond. 1 is equivalent to
 Cond. 9. — $\forall a, c \in S, p(0)T(a, 0, c; 1) = p(1)T(a, 1, c; 0)$.
- (2) Cond. 2 is equivalent to
 Cond. 10. — $\forall a, b \in S, p(0)T(a, b, 0; 1) = p(1)T(a, b, 1; 0)$.
- (3) Cond. 3 is equivalent to
 Cond. 11. — $\forall b, c \in S, p(0)T(0, b, c; 1) = p(1)T(1, b, c; 0)$.

Proof. — In the binary case, Cond. 1 reduces to:

$$\forall a, c \in S, p(1) = p(0)T(a, 0, c; 1) + p(1)T(a, 1, c; 1),$$

which is itself equivalent to Cond. 9. The proof is analogous for Cond. 10 and Cond. 11.

Let p be a probability measure on $S = \{0, 1\}$. If we specify some results of Table 2.1 to the case $|S| = 2$, we obtain

$$\begin{aligned} \dim(\mathcal{T}_S(p)) &= \dim(\{A \in \mathcal{T}_S(p) : A \text{ is } h\text{-reversible}\}) = 4, \\ \dim(\{A \in \mathcal{T}_S(p) : A \text{ is } v\text{-reversible}\}) &= \dim(\{A \in \mathcal{T}_S(p) : A \text{ is } r^2\text{-reversible}\}) = 3, \\ \dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-quasi-reversible}\}) & \\ &= \dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-reversible}\}) = 1. \end{aligned}$$

In this section, we describe more precisely these different sets, which give an alternative proof of the value of their dimension, in the binary case. First, the next result shows that in the binary case, the sets above having the same dimension are equal.

PROPOSITION 7.2. — Let p be any positive probability on $S = \{0, 1\}$, and let $A \in \mathcal{T}_S(p)$. Then, we have the following properties.

- (1) A is h -reversible.
- (2) A is v -reversible iff A is r^2 -reversible.
- (3) A is D_4 -quasi-reversible iff A is D_4 -reversible.

Proof.

(1). — Since A is in $\mathcal{T}_S(p)$, A is h -quasi-reversible, and the transition kernel T_h of its h -reverse satisfies, for any $a, b, c, d \in S$,

$$T_h(a, d, c; b) = \frac{p(b)}{p(d)}T(a, b, c; d).$$

For $b = d$, this gives $T_h(a, b, c; d) = T(a, b, c; d)$, and for $b \neq d$, Cond. 9 provides the result.

(2). — It is a corollary of 1. Indeed, if A is in $\mathcal{T}_S(p)$ and v -reversible, then it is h and v -reversible, and so also $r^2 = v \circ h$ -reversible. And conversely, if it is r^2 -reversible, then it is $v = r^2 \circ h$ -reversible.

(3). — This will be a consequence of Proposition 7.5.

As a consequence of Proposition 7.1, we obtain the following descriptions of binary PCA having an invariant HZPM.

PROPOSITION 7.3. — *Let A be a PCA with transition kernel T (with positive rates). Then A has an invariant HZPM iff*

Cond. 12. — *there exists $k \in]0, \infty[$ such that for any $a, c \in S$,*

$$\frac{T(a, 1, c; 0)}{T(a, 0, c; 1)} = k.$$

More explicitly, this is equivalent to the following condition.

Cond. 13. — *there exists $k \in]0, \infty[$ and*

$$\begin{cases} q_{0,0}, q_{0,1}, q_{1,0}, q_{1,1} \in (0, 1) & \text{if } k \in (0, 1] \\ q_{0,0}, q_{0,1}, q_{1,0}, q_{1,1} \in (1 - k^{-1}, 1) & \text{if } k \in [1, \infty) \end{cases}$$

such that, for any $a, c \in S$,

$$\begin{aligned} T(a, 0, c; 0) &= q_{a,c}, \\ T(a, 1, c; 0) &= k(1 - q_{a,c}) = k - kq_{a,c}. \end{aligned}$$

In that case, the p -HZPM invariant is $(p(0), p(1))$ where

$$p(1) = 1 - p(0) = \frac{1}{1+k}.$$

Proof. — The PCA A has an invariant HZPM iff there exists a probability p on S such that Cond. 9 is satisfied, which can easily be shown to be equivalent to the above conditions.

PROPOSITION 7.4. — *Let p be a positive probability on S , and let $k = p(0)/p(1)$. Then, A is a r -quasi-reversible PCA of $\mathcal{T}_S(p)$ iff*

Cond. 14. — *There exist*

$$\begin{cases} q_0, q_1 \in (0, 1) & \text{if } k \in (0, 1] \\ q_0, q_1 \in (1 - k^{-1}, 1 - k^{-1} + k^{-2}) & \text{if } k \in [1, \infty) \end{cases}$$

such that, for any $a \in S$:

$$\begin{aligned} T(a, 0, 0; 0) &= q_a, \\ T(a, 0, 1; 0) &= T(a, 1, 0; 0) = k(1 - q_c) = k - kq_a \\ T(a, 1, 1; 0) &= k(1 - k(1 - q_c)) = k - k^2 + k^2q_a. \end{aligned}$$

Similarly, A is a r^{-1} -quasi-reversible PCA of $\mathcal{T}_S(p)$ iff

Cond. 15. — *There exist*

$$\begin{cases} q_0, q_1 \in (0, 1) & \text{if } k \in (0, 1] \\ q_0, q_1 \in (1 - k^{-1}, 1 - k^{-1} + k^{-2}) & \text{if } k \in [1, \infty) \end{cases}$$

such that, for any $c \in S$:

$$\begin{aligned} T(0, 0, c; 0) &= q_c, \\ T(0, 1, c; 0) &= T(1, 0, c; 0) = k(1 - q_c) = k - kq_c \\ T(1, 1, c; 0) &= k(1 - k(1 - q_c)) = k - k^2 + k^2q_c. \end{aligned}$$

Proof. — We prove the first statement. Let A be a r -quasi-reversible PCA in $\mathcal{T}_S(p)$. Then T satisfies Cond. 9 and 10, meaning that for any $a, b, c \in S$,

$$\frac{T(a, 1, c; 0)}{T(a, 0, c; 1)} = \frac{T(a, b, 1; 0)}{T(a, b, 0; 1)} = k = \frac{p(0)}{p(1)}.$$

Taking $b = c = 0$, we find, for any $a \in S$,

$$T(a, 1, 0; 0) = T(a, 0, 1; 0) = kT(a, 0, 0; 1)$$

and taking $b = c = 1$, we find that for any $a \in S$,

$$T(a, 0, 1; 1) = T(a, 1, 0; 1) = k^{-1}T(a, 1, 1; 0).$$

Hence, for any $a \in S$, we obtain

$$T(a, 1, 1; 0) = k(1 - T(a, 0, 1; 0)) = k(1 - k(1 - T(a, 0, 0; 0))).$$

Then, every $T(a, b, c; d)$ can be express in terms of $T(0, 0, 0; 0) = q_0$, $T(0, 0, 1; 0) = q_1$ and k , which gives Cond. 14, and the range of q_0, q_1 is deduced from the fact that, for any $a, b, c, d \in S$, $T(a, b, c; d) \in (0, 1)$.

Conversely, let A be such that Cond. 14 holds. Then Cond. 9 and 10 hold, so $A \in \mathcal{T}_S(p)$ and A is r -quasi-reversible.

PROPOSITION 7.5. — *Let p be a positive probability on S , and let $k = p(0)/p(1)$. Then, A is a $\{r, r^{-1}\}$ -quasi-reversible PCA of $\mathcal{T}_S(p)$ iff*

Cond. 16. — There exists

$$\begin{cases} q_0 \in (0, 1) & \text{if } k \in (0, 1] \\ q_0 \in (1 - k^{-1} + k^{-2} - k^{-3}, 1 - k^{-1} + k^{-2}) & \text{if } k \in [1, \infty) \end{cases}$$

such that

$$\begin{aligned} T(0, 0, 0; 0) &= q_0, \\ T(0, 0, 1; 0) &= T(0, 1, 0; 0) = T(1, 0, 0; 0) = k(1 - q_0) = k - kq_0 \\ T(0, 1, 1; 0) &= T(1, 1, 0; 0) = T(1, 0, 1; 0) = k(1 - k(1 - q_0)) = k - k^2 + k^2q_0 \\ T(1, 1, 1; 0) &= k(1 - k(1 - k(1 - q_0))) = k - k^2 + k^3 - k^3q_0. \end{aligned}$$

Moreover, in that case, A is D_4 -reversible.

Proof. — The PCA A is a $\{r, r^{-1}\}$ -quasi-reversible PCA of $\mathcal{T}_S(p)$ iff Cond. 9, 10 and 11 are satisfied, which can easily be shown to be equivalent to the above condition. Now, we prove the D_4 -reversibility of A . First, A is symmetric, so A is v -reversible. Second, it is easy to check that $T_r = T$, so that A is r and v -reversible. By (5) of Proposition 2.7, A is D_4 -reversible.

Example 7.6. — Let us consider the special case when p is the uniform distribution on S , meaning that $p(0) = p(1) = 1/2$. Then, $k = 1$, and the family of PCA above corresponds to:

$$\forall a, b, c, d \in S, \quad T(a, b, c; d) = \begin{cases} q_0 & \text{if } d = a + b + c \pmod 2 \\ 1 - q_0 & \text{otherwise.} \end{cases}$$

In the deterministic case ($q_0 = 1$), we get a linear CA. Such CA have been intensively studied. Here, in the probabilistic setting, the PCA we obtain can be seen as noisy versions of that linear CA (with a probability $1 - q_0$ of doing an error, independently for different cells). This is a special case of the 8-vertex PCA, with $p = r$.

Example 7.7. — Let us consider the probability distribution on S given by $p(0) = 1/3$ and $p(1) = 2/3$, so that $k = 2$. When specifying Cond. 14 to $q_0 = 3/4$ and $q_1 = 4/5$, we obtain

$$\begin{aligned} T(0, 0, 0; 0) &= 3/4, & T(1, 0, 0; 0) &= 4/5, \\ T(0, 0, 1; 0) &= T(0, 1, 0; 0) = 1/8, & T(1, 0, 1; 0) &= T(1, 1, 0; 0) = 1/10, \\ T(0, 1, 1; 0) &= 7/16, & T(1, 1, 1; 0) &= 9/20. \end{aligned}$$

The PCA A of transition kernel T is r -quasi-reversible, but one can check that it does not satisfy Cond. 11, so that it is not r^{-1} -quasi-reversible. So, T_r does not belong to $\mathcal{T}_S(p)$, and following the argument developed in Section 5.3, T_r does not have an invariant HZMC either. Nevertheless, one can exactly compute the marginals of its invariant measure μ , see (4.5) and (4.6). The transitions of T_r are the following ones:

$$\begin{aligned} T_r(0, 0, 0; 0) &= 3/4, & T_r(1, 0, 0; 0) &= 1/8, \\ T_r(0, 0, 1; 0) &= 1/8, & T_r(1, 0, 1; 0) &= 7/16, \\ T_r(0, 1, 0; 0) &= 4/5, & T_r(1, 1, 0; 0) &= 1/10, \\ T_r(0, 1, 1; 0) &= 1/10, & T_r(1, 1, 1; 0) &= 9/20. \end{aligned}$$

8. Extension to general alphabet

We now present some extensions of our methods and results to general sets of symbols. First of all, we extend the definition of PCA to any Polish space S , as it has been done in [Cas16] for PCA with memory one. The transition kernel T of a PCA with memory two must now satisfy

- for any Borel set $D \in \mathcal{B}(S)$, the map

$$\begin{aligned} T_D : \quad S^3 &\longrightarrow \mathbb{R} \\ (a, b, c) &\longmapsto T(a, b, c; D) \end{aligned}$$

is $\mathcal{B}(S^3)$ -measurable;

- for any $a, b, c \in S$, the map

$$\begin{aligned} T_{a,b,c} : \quad \mathcal{B}(S) &\longrightarrow \mathbb{R} \\ D &\longmapsto T(a, b, c; D) \end{aligned}$$

is a probability measure on S .

For any σ -finite measure μ on S , the transition kernel T is said to be μ -positive if, for μ^3 -almost every $(a, b, c) \in S^3$, $T(a, b, c; \cdot)$ is absolutely continuous with respect to μ and μ is absolutely continuous with respect to $T(a, b, c; \cdot)$. In that case, thanks to Radon–Nikodym theorem, we can define the density of T with respect to μ , that is a μ^4 -measurable positive function where, for μ^3 -almost every $(a, b, c) \in S^3$,

$$t(a, b, c; d) = \frac{dT(a, b, c; \cdot)}{d\mu}(d)$$

where $\frac{dT(a, b, c; \cdot)}{d\mu}$ is the Radon–Nikodym derivative of $T(a, b, c; \cdot)$ with respect to μ .

THEOREM 8.1. — *Let μ be any σ -finite measure on a Polish space S . Let A be a PCA with a μ -positive transition kernel T on S . Then, A has an invariant μ -positive HZPM iff Cond. 17. — there exists a μ -measurable positive function p on S such that, for μ^3 -almost every $(a, c, d) \in S^3$,*

$$p(d) = \int_E p(b)t(a, b, c; d)d\mu(b)$$

and $\mu(p) = \int_E p(b)d\mu(b) < \infty,$

where t is the μ -density of T .

Then, the P -HZPM is invariant by A where $p(\cdot)/\mu(p)$ is the μ -density of P .

Proof. — The proof follows the same idea as that of Theorem 3.1, except that we are now on a Polish space S . Let A be a μ -positive triangular PCA with alphabet S .

Suppose that A has an invariant μ -positive P -HZPM and that (η_t, η_{t+1}) follows a P -HZPM distribution. Then, for any $\tilde{A}, \tilde{B}, \tilde{C}, \tilde{D} \in \mathcal{B}(S)$,

$$\begin{aligned} &P\left(\eta_t(i-1) \in \tilde{A}, \eta_{t+1}(i) \in \tilde{D}, \eta_t(i+1) \in \tilde{C}\right) \\ &= \int_{\tilde{A} \times \tilde{C} \times \tilde{D}} p(a)p(c)p(d)d\mu^3(a, c, d) \quad \text{on the one hand,} \\ &= \int_{\tilde{A} \times \tilde{C} \times \tilde{D}} \left(\int_S p(a)p(b)p(c)t(a, b, c; d)d\mu(b)\right) d\mu^3(a, c, d) \quad \text{on the other hand.} \end{aligned}$$

Hence, for μ -almost $a, c, d \in S$,

$$p(a)p(c) \int_S p(b)t(a, b, c; d)d\mu(b) = p(a)p(d)p(c)$$

and so, as $p(a), p(c) > 0$ for μ -almost $a, c \in S$, Cond. 17 holds.

Conversely, assume that Cond. 17 is satisfied, and that (η_{t-1}, η_t) follows a μ -positive P -HZPM distribution. For some given choice of $n \in \mathbb{Z}_t$, let us denote: $X_i = \eta_{t-1}(n+1+2i), Y_i = \eta_t(n+2i), Z_i = \eta_{t+1}(n+1+2i)$, for $i \in \mathbb{Z}$, see Figure 3.1 for an illustration.

Then, for any $k > 1$, for any μ -measurable Borel sets $B_0, B_1, \dots, B_k, C_0, \dots, C_{k-1}$,

$$\begin{aligned} & \mathbb{P}((Y_i)_{0 \leq i \leq k} \in B_0 \times \dots \times B_k, (Z_i)_{0 \leq i \leq k-1} \in C_0 \times \dots \times C_{k-1}) \\ &= \int_{C_0 \times \dots \times C_{k-1}} \int_{B_0 \times \dots \times B_k} \left(\prod_{i=0}^{k-1} \int_S t(y_i, x_i, y_{i+1}; z_i) p(x_i) d\mu(x_i) \right) \\ & \qquad \qquad \qquad p(y_0) \dots p(y_k) d\mu(y_0, \dots, y_k) d\mu(z_0, \dots, z_{k-1}) \\ &= \int_{C_0 \times \dots \times C_{k-1}} \int_{B_0 \times \dots \times B_k} \left(\prod_{i=0}^{k-1} p(z_i) \right) p(y_0) \dots p(y_k) d\mu(y_0, \dots, y_k) d\mu(z_0, \dots, z_{k-1}) \end{aligned}$$

thus, the P -HZPM distribution is invariant by A .

Now, the problem is reduced to finding eigenfunction associated to the eigenvalue 1 of some integral operator. If this problem is solved by Gauss elimination in the case of a finite space, this is more complicated in the general case. Indeed, such a function does not always exist, but, when it is the case, the solution is unique (up to a multiplicative constant), see the following lemma.

LEMMA 8.2 ([Dur10, Theorem 6.8.7]). — *Let \mathcal{A} be an integral operator of kernel m :*

$$\mathcal{A} : f \rightarrow \left(\mathcal{A}(f) : y \rightarrow \int_S f(x) m(x; y) d\mu(x) \right).$$

If m is the μ -density of a μ -positive t. k. M from S to S , then \mathcal{A} possesses at most one positive eigenfunction in $L^1(\mu)$ (up to a multiplicative constant).

Moreover, the previous results concerning the characterization of reversible and quasi-reversible PCA extend to PCA with general alphabet. The difference is that we are considering μ -positive PCA and that Cond. 2 and 3 are respectively replaced by the two following Conditions (18) and (19).

Cond. 18. — for μ^3 -almost every $(a, b, d) \in S^3$, $\int_S p(c) t(a, b, c; d) d\mu(c) = p(d)$

Cond. 19. — for μ^3 -almost every $(b, c, d) \in S^3$, $\int_S p(a) t(a, b, c; d) d\mu(a) = p(d)$.

Following the same idea as in [Cas16], many results on PCA with invariant (F, B) -HZMC can also be generalized to PCA on general alphabets.

9. Dimensions of the manifolds

In this section, we give the dimensions of $\mathcal{T}_S(p)$ and of its subsets of (quasi-)reversible PCA, as functions of the cardinal n of the alphabet S (see Table 2.1). But first, we need some results about dimensions of sets of matrices.

9.1. Preliminaries: dimensions of sets of matrices with a given eigenvector

Let S be a finite set of size n , and let u, v be two positive probabilities on S . We denote by $\mathcal{M}_S(u, v)$ the set of positive matrices $M = (m_{ij})_{i,j} \in S$ such that M is a

stochastic matrix and $uM = v$, i.e.

$$\mathcal{M}_S(u, v) = \left\{ M = (m_{ij})_{i,j \in S} : \begin{array}{l} \text{for any } i, j \in S, 0 < m_{ij} < 1; \\ \text{for any } i \in S, \sum_{j \in S} m_{ij} = 1; \\ \text{for any } j \in S, \sum_{i \in S} u(i)m_{ij} = v(j). \end{array} \right\}.$$

As a particular case, when $u = v = p$, the vector p is a left-eigenvector of M associated to the eigenvalue 1 and we denote the set $\mathcal{M}_S(p, p)$ simply by $\mathcal{M}_S(p)$. We also define a subset $\mathcal{M}_S^{\text{sym}}(p)$ of $\mathcal{M}_S(p)$ by:

$$\mathcal{M}_S^{\text{sym}}(p) = \{ M \in \mathcal{M}_S(p) : \forall i, j \in S, p(i)m_{ij} = p(j)m_{ji} \}.$$

Our first Lemma 9.1 is about the dimension of $\mathcal{M}_S(u, v)$.

LEMMA 9.1. — *For any positive probabilities u and v on S , the manifold $\mathcal{M}_S(u, v)$ satisfies:*

$$\dim \mathcal{M}_S(u, v) = (n - 1)^2.$$

Proof. — First, we prove $\dim \mathcal{M}_S(u, v) \leq (n - 1)^2$. $\mathcal{M}_S(u, v)$ is defined by the $2n$ linear equations $\forall i \in S, \sum_{j \in S} m_{ij} = 1$ and $\forall j \in S, \sum_{i \in S} u(i)m_{ij} = v(j)$. This gives $2n - 1$ independent linear equations on the n^2 variables $(m_{ij})_{i,j \in S}$. So $\dim \mathcal{M}_S(p) \leq n^2 - (2n - 1) = (n - 1)^2$.

We do not have the equality yet because we have the additional condition: $\forall i, j \in S, m_{ij} > 0$. Hence, we have to ensure that $\mathcal{M}_S(u, v)$ is not empty, and that we are not in any other degenerate case for which the dimension would be strictly smaller than $(n - 1)^2$. For that, we first exhibit a solution of the system such that $m_{ij} > 0$ and then find a neighbourhood around this solution having the dimension we want.

First, the matrix $M = (v(j))_{i,j \in S}$ is in $\mathcal{M}_S(u, v)$. Now, let $s \in S$ be a distinguished element of S . Let us set: $S^* = S \setminus \{s\}$. One can check that there exists a neighbourhood V_0 of 0 in $\mathbb{R}^{(S^*)^2}$ such that for any $(\epsilon_{ij} : i, j \in S^*) \in V_0$, the matrix $M_\epsilon = (m_{ij})_{i,j \in S}$ defined by:

$$\begin{aligned} m_{ij} &= v(j) + \epsilon_{ij} \text{ for any } i, j \in S^*, \\ m_{is} &= v(s) - \sum_{j \in S^*} \epsilon_{ij}, \\ m_{sj} &= v(j) - \frac{\sum_{i \in S^*} u(i)\epsilon_{ij}}{u(s)}, \\ m_{ss} &= v(s) + \frac{\sum_{i \in S^*} \sum_{j \in S^*} u(i)\epsilon_{ij}}{u(s)}, \end{aligned}$$

is positive, stochastic, and satisfies $uM = v$. So,

$$\dim \mathcal{M}_S(p) > \dim(S^*)^2 = (n - 1)^2.$$

In the particular case when $u = v = p$, we obtain the following.

COROLLARY 9.2. — *Let S be a finite set of size n , then:*

$$\dim \mathcal{M}_S(p) = (n - 1)^2.$$

Now we give two properties about families of matrices in $\mathcal{M}_S(p)$.

LEMMA 9.3. — *Let S be a finite set and p be a probability on S . Let $(M_k = (m_{k,ij})_{i,j \in S} : k \in S)$ be a collection of positive matrices indexed by S such that, for any $i, j \in S$,*

$$(9.1) \quad \sum_{k \in S} p(k)m_{k,ij} = p(j).$$

Let $s \in S$ and define $S^* = S \setminus \{s\}$. If, for any $k \in S^*$, $M_k \in \mathcal{M}_S(p)$, then $M_s \in \mathcal{M}_S(p)$.

Proof. — By (9.1), the coefficients of the matrix M_s satisfy, for any $i, j \in S$,

$$m_{s,ij} = \frac{p(j) - \sum_{k \in S^*} p(k)m_{k,ij}}{p(s)}.$$

First, let us prove that M_s is stochastic: for any i ,

$$\sum_{j \in S} m_{s,ij} = \frac{1 - \sum_{k \in S^*} p(k)}{p(s)} = \frac{1 - (1 - p(s))}{p(s)} = 1;$$

then, that p is a left-eigenvector of M_s : for any j ,

$$\begin{aligned} \sum_{i \in S} p(i)m_{s,ij} &= \frac{p(j) - \sum_{k \in S^*} p(k) \sum_{i \in S} p(i)m_{k,ij}}{p(s)} \\ &= \frac{p(j) - \sum_{k \in S^*} p(k)p(j)}{p(s)} \\ &= p(j) \frac{1 - (1 - p(s))}{p(s)} = p(j). \end{aligned}$$

LEMMA 9.4. — *Let S be a finite set and let p be a probability on S . Let $M = (m_{ij})_{i,j \in S}$ be a matrix in $\mathcal{M}_S(p)$. Then $\widetilde{M} = \left(\frac{p(j)}{p(i)}m_{ji}\right)_{i,j \in S} \in \mathcal{M}_S(p)$.*

Proof. — First, let us prove that \widetilde{M} is stochastic: for any $i \in S$, $\sum_{j \in S} \widetilde{m}_{ij} = \sum_{j \in S} \frac{p(j)}{p(i)}m_{ji} = 1$; then, that p is a left-eigenvector of \widetilde{M} : for any $j \in S$, $\sum_{i \in S} p(i)\widetilde{m}_{ij} = \sum_{i \in S} p(j)m_{ji} = p(j)$.

Finally, we get the dimension of $\mathcal{M}_S^{\text{sym}}(p)$.

LEMMA 9.5. — *Let S be a finite set of size n and p be a positive probability on S , then:*

$$\dim \mathcal{M}_S^{\text{sym}}(p) = \frac{(n-1)n}{2}.$$

Proof. — First, $\dim \mathcal{M}_S^{\text{sym}}(p) \leq \frac{(n-1)n}{2}$ because we know by the proof of Lemma 9.1 that we can describe a matrix in the manifold $\mathcal{M}_S(p)$ by knowing $(m_{ij} : i, j \in S)$. But, with the new constraint $p(i)m_{ij} = p(j)m_{ji}$ for any $i, j \in S$, it is sufficient to know only $(m_{ij} : i \leq j, i, j \in S)$.

Conversely, let us take $(m_{ij} : i \leq j, i, j \in S)$ in a neighbourhood V of $(m_{ij} = p(j) : i \leq j, i, j \in S)$ in $\mathbb{R}^{n(n-1)/2}$. Let us take:

- for any $i, j \in S, i > j, m_{ij} = \frac{p(j)}{p(i)}m_{ji}$;
- for any $i \in S, m_{is} = 1 - \sum_{j \in S} m_{ij}$;

- for any $j \in S$, $m_{sj} = \frac{p(j) - \sum_{i \in S} p(i)m_{ij}}{p(s)}$;
- $m_{ss} = 1 - \sum_{j \in S} m_{sj}$.

By the same argument as in the proof of Lemma 9.1, there exists a neighbourhood V of dimension $\frac{(n-1)n}{2}$ such that for any point on it, $M = (m_{ij})_{ij \in S} \in \mathcal{M}_S^{\text{sym}}(p)$. So,

$$\dim \mathcal{M}_S^{\text{sym}}(p) > \frac{(n-1)n}{2}.$$

These preliminary results will be useful to prove dimensions of sets of (quasi-)reversible PCA.

9.2. Dimensions of $\mathcal{T}_S(p)$ and its subsets

THEOREM 9.6. — *Let S be a set of size n , and p be a positive probability on S .*

- (1) $\dim(\mathcal{T}_S(p)) = n^2(n-1)^2$.
- (2) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } r\text{-quasi-reversible}\}) = n(n-1)^3$,
- (3) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } r^{-1}\text{-quasi-reversible}\}) = n(n-1)^3$,
- (4) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-quasi-reversible}\}) = (n-1)^4$.
- (5) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } v\text{-reversible}\}) = \frac{(n-1)^2 n(n+1)}{2}$.
- (6) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } r^2\text{-reversible}\}) = \frac{(n-1)^2 n(n+1)}{2}$.
- (7) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } h\text{-reversible}\}) = \frac{n^3(n-1)}{2}$.
- (8) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r^2, v \rangle\text{-reversible}\}) = \frac{(n-1)n^2(n+1)}{4}$.
- (9) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \rangle\text{-reversible}\}) = \frac{n(n-1)(n^2-3n+4)}{4}$. ⁽¹⁾
- (10) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \circ v \rangle\text{-reversible}\}) = \frac{(n-1)^2(n^2-2n+2)}{2}$. ⁽²⁾
- (11) $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-reversible}\}) = \frac{n(n-1)(n^2-n+2)}{8}$. ⁽³⁾

Proof. — Let $s \in S$, and $S^* = S \setminus \{s\}$.

(1). — By Theorem 3.1, a PCA A is in $\mathcal{T}_S(p)$ if for all $a, c \in S$, $(T(a, b, c; d))_{b, d \in S} \in \mathcal{M}_S(p)$. It follows, by Corollary 9.2, that: $\dim \mathcal{T}_S(p) = |S|^2 \dim \mathcal{M}_S(p) = n^2(n-1)^2$.

(2). — By Theorem 3.1, as $A \in \mathcal{T}_S(p)$, for any $a, c \in S$, $(T(a, b, c; d))_{b, d \in S} \in \mathcal{M}_S(p)$. Moreover, A is r -reversible so: $\sum_{c \in S} p(c)T(a, b, c; d) = p(d)$. By Lemma 9.3, for any $a \in S$, we can choose freely $(T(a, b, c; d))_{b, d \in S : c \in S^*} \in \mathcal{M}_S(p)$, and $(T(a, b, s; d))_{b, d \in S}$ is then uniquely obtained from them and in $\mathcal{M}_S(p)$. Thus,

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } r\text{-quasi-reversible}\}) = |S||S| \dim \mathcal{M}_S(p) = n(n-1)^3.$$

(3). — The proof is similar to the proof of Lemma 9.5.

⁽¹⁾ OEIS A006528

⁽²⁾ OEIS A037270

⁽³⁾ OEIS A002817

(4). — As before, for any $a, c \in S$, $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$. By Theorem 4.4, we need in addition that, for any $b, d \in S$,

$$\begin{aligned} \sum_{a \in S} p(a)T(a, b, c; d) &= p(d) \text{ for any } c \in S, \text{ and} \\ \sum_{c \in S} p(c)T(a, b, c; d) &= p(d) \text{ for any } a \in S. \end{aligned}$$

Hence, we can choose freely a collection of $|S|^2$ matrices $((T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p) : a, c \in S^*)$. Then, by Lemma 9.3, matrices $((T(s, b, c; d))_{b, d} \in \mathcal{M}_S(p) : c \in S^*)$ and $(T(a, b, s; d))_{b, d} \in \mathcal{M}_S(p) : a \in S^*$ are uniquely defined and in $\mathcal{M}_S(p)$. Finally, the last matrix $(T(s, b, s; d))_{b, d} \in \mathcal{M}_S(p)$ can be obtained from two various methods but define the same matrix at the end (the proof is similar to the one of Lemma 9.1). Hence,

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-quasi-reversible}\}) = |S|^2 \dim \mathcal{M}_S(p) = (n-1)^4.$$

(5). — If $A \in \mathcal{T}_S(p)$ is v -reversible, then $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$ and $T(a, b, c; d) = T(c, b, a; d)$. So, matrices $\{(T(a, b, a; d))_{b, d} \in \mathcal{M}_S(p) : a \in S\}$ can be freely chosen in $\mathcal{M}_S(p)$, but as $T(a, b, c; d) = T(c, b, a; d)$ when $a \neq c$, hence only $\{(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p) : a < c\}$ can be chosen freely in $\mathcal{M}_S(p)$, $\{(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p) : a > c\}$ are imposed by $\{(T(c, b, a; d))_{b, d} \in \mathcal{M}_S(p) : c < a\}$. Hence

$$\begin{aligned} \dim(\{A \in \mathcal{T}_S(p) : A \text{ is } v\text{-reversible}\}) &= \left(|S| + \binom{|S|}{2}\right) \dim \mathcal{M}_S(p) \\ &= \left(n + \frac{n(n-1)}{2}\right) (n-1)^2 \\ &= \frac{(n-1)^2 n(n+1)}{2}. \end{aligned}$$

(6). — If $A \in \mathcal{T}_S(p)$ is r^2 -reversible, then $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$ and $T(c, d, a; b) = \frac{p(b)}{p(d)}T(a, b, c; d)$. Hence, if we take a matrix $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$ with $a < c$, then $(T(c, b, a; d))_{b, d} \in \mathcal{M}_S(p)$ is known and $\in \mathcal{M}_S(p)$ by Lemma 9.4. So, we can just choose freely matrices $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$ with $a < c$. That is why the dimension is the same as for v -reversible matrices.

(7). — If $A \in \mathcal{T}_S(p)$ is h -reversible, then $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$ and $T(a, d, c; b) = \frac{p(b)}{p(d)}T(a, b, c; d)$. Then, for any $a, c \in S$, $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S^{\text{sym}}(p)$ and, moreover, they can be chosen freely. So, by Lemma 9.5,

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } h\text{-reversible}\}) = |S|^2 \dim \mathcal{M}_S^{\text{sym}}(p) = \frac{(n-1)n^3}{2}.$$

(8). — If $A \in \mathcal{T}_S(p)$ is $\langle r^2, v \rangle$ -reversible, then $(T(a, b, c; d))_{b, d} \in \mathcal{M}_S(p)$, $T(a, b, c; d) = T(c, b, a; d)$ and $T(a, d, c; b) = \frac{p(b)}{p(d)}T(a, b, c; d)$. Then, it is equivalent to

choose freely $\{(T(a, b, c; d))_{b,d} : a \in c\}$ in $\mathcal{M}_S^{\text{sym}}(p)$. That's why,

$$\begin{aligned} \dim \left(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r^2, v \rangle\text{-reversible}\} \right) &= \left(|S| + \binom{|S|}{2} \right) \dim \mathcal{M}_S^{\text{sym}}(p) \\ &= \frac{n(n+1)}{2} \frac{(n-1)n}{2} \\ &= \frac{(n-1)n^2(n+1)}{4}. \end{aligned}$$

(9), (10), (11). — Proofs are long and relatively similar. They are done in Section 9.3.

COROLLARY 9.7. — *Let S be a set of size n , then:*

$$\dim(\cup_p \mathcal{T}_S(p)) = (n^3 - n^2 + 1)(n - 1).$$

Proof. — We just add to the previous result the dimension of the set of positive probability measures on S , which is equal to $n - 1$.

Let us now say a word about the dimension of the set $\mathcal{T}_S(F, B)$ of PCA having a (F, B) -HZMC invariant distribution.

PROPOSITION 9.8. — *Let S be a set of size n . For any (F, B) such that $FB = BF$,*

$$\dim \mathcal{T}_S(F, B) = n^2(n - 1)^2.$$

Proof. — For any (F, B) , A is in $\mathcal{T}_S(F, B)$ iff the two following conditions hold (see Proposition 5.3):

- (1) for any $a, b, c \in S$, $\sum_d T(a, b, c; d) = 1$,
- (2) for any $a, c, d \in S$,

$$\frac{F(a; d)B(d; c)}{(FB)(a; c)} = \sum_b \frac{B(a; b)F(b; c)}{(FB)(a; c)} T(a, b, c; d).$$

Now, by Lemma 9.1, for any positive vectors u, v ,

$$\dim \mathcal{M}_S(u, v) = (n - 1)^2.$$

To conclude, we just have to say that, for any $a, c \in S$, we can take freely $(T(a, b, c; d))_{b,d} \in \mathcal{M}_S(u, v)$

$$\text{with } u = \left(\frac{B(a; b)F(b; c)}{(FB)(a; c)} \right)_{b \in S} \text{ and } v = \left(\frac{F(a; d)B(d; c)}{(FB)(a; c)} \right)_{d \in S}.$$

Let us however mention that getting the dimension of $\cup_{\{(F,B):FB=BF\}} \mathcal{T}_S(F, B)$ seems out of reach. Understanding the structure of the set $\{(F, B) : FB = BF\}$ is indeed listed as a difficult problem, see [Ger61, Gur92, MT55].

9.3. Proofs of Points 9, 10 and 11 of Theorem 9.6

We recall that S is a set of size n , s a given element of S , and p a positive probability measure on S . We denote $S' = S \setminus \{s\}$.

The proofs of the last three points of Theorem 9.6 are long because they consist in reducing an affine system with $|S|^4$ equations and $|S|^4$ variables (containing some redundant equations) into one with only free equations describing the same manifold. Furthermore, we must ensure that there exists a solution with positive coefficients and that we are not in a degenerate case (see the discussion in the middle of the proof of Lemma 9.1). Since the proofs of the three points are similar, but not exactly the same, we first define some conditions that are useful for the three cases, then we detail the proof of Point (9) and finally, we focus on the differences for the two other cases in comparison with Point (9).

9.3.1. Preliminary results

This section is technical and must be seen as a reference for the sections that are following, so it can be omitted in a first lecture.

First, we define some conditions on the transition kernel T .

Cond. 20. — For any $a, b, c, d \in S$, we have

$$(9.2) \quad T(a, b, c; s) = 1 - \sum_{d \in S} T(a, b, c; d);$$

$$(9.3) \quad T(s, b, c; d) = \frac{p(d)}{p(s)} - \sum_{a \in S} \frac{p(a)}{p(s)} T(a, b, c; d);$$

$$(9.4) \quad T(a, s, c; d) = \frac{p(d)}{p(s)} - \sum_{b \in S} \frac{p(b)}{p(s)} T(a, b, c; d);$$

$$(9.5) \quad T(a, b, s; d) = \frac{p(d)}{p(s)} - \sum_{c \in S} \frac{p(c)}{p(s)} T(a, b, c; d);$$

$$(9.6) \quad T(s, b, c; s) = p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_{a \in S} \sum_{d \in S} \frac{p(a)}{p(s)} T(a, b, c; d);$$

$$(9.7) \quad T(a, s, c; s) = p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_{b \in S} \sum_{d \in S} \frac{p(b)}{p(s)} T(a, b, c; d);$$

$$(9.8) \quad T(a, b, s; s) = p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_{c \in S} \sum_{d \in S} \frac{p(c)}{p(s)} T(a, b, c; d);$$

$$(9.9) \quad T(s, s, c; d) = p(d) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_{a \in S} \sum_{b \in S} \frac{p(a)p(b)}{p(s)^2} T(a, b, c; d);$$

$$(9.10) \quad T(s, b, s; d) = p(d) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_{a \in S} \sum_{c \in S} \frac{p(a)p(c)}{p(s)^2} T(a, b, c; d);$$

$$(9.11) \quad T(a, s, s; d) = p(d) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_{b \in S} \sum_{c \in S} \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d);$$

$$(9.12) \quad T(s, s, c; s) = p(s) \left(1 + \left(\frac{1 - p(s)}{p(s)} \right)^3 \right) - \sum_{a \in S} \sum_{b \in S} \sum_{d \in S} \frac{p(a)p(b)}{p(s)^2} T(a, b, c; d);$$

$$(9.13) \quad T(s, b, s; s) = p(s) \left(1 + \left(\frac{1 - p(s)}{p(s)} \right)^3 \right) - \sum_a S \sum_c S \sum_d S \frac{p(a)p(c)}{p(s)^2} T(a, b, c; d);$$

$$(9.14) \quad T(a, s, s; s) = p(s) \left(1 + \left(\frac{1 - p(s)}{p(s)} \right)^3 \right) - \sum_b S \sum_c S \sum_d S \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d);$$

$$(9.15) \quad T(s, s, s; d) = p(d) \left(1 + \left(\frac{1 - p(s)}{p(s)} \right)^3 \right) - \sum_a S \sum_b S \sum_c S \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d);$$

$$(9.16) \quad T(s, s, s; s) = p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^4 \right) + \sum_a S \sum_b S \sum_c S \sum_d S \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d).$$

Cond. 21. — For any $a, b, c \in S$, $\sum_d S T(a, b, c; d) = 1$.

Cond. 22. — For any $a, c, d \in S$, $\sum_b S p(b)T(a, b, c; d) = p(d)$.

Cond. 23. — For any $a, b, c, d \in S$, $0 < T(a, b, c; d) < 1$.

LEMMA 9.9. — Cond. 20 \Rightarrow Cond. 21

Proof. — For any $a, b, c \in S$,

$$\begin{aligned} \sum_d S T(a, b, c; d) &= T(a, b, c; s) + \sum_d S T(a, b, c; d) \\ &= 1 - \sum_d S T(a, b, c; d) + \sum_d S T(a, b, c; d) \\ &= 1. \end{aligned}$$

For any $a, b \in S$,

$$\begin{aligned} \sum_d S T(a, b, s; d) &= T(a, b, s; s) + \sum_d S T(a, b, s; d) \\ &= p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_c S \sum_d S \frac{p(c)}{p(s)} T(a, b, c; d) \\ &\quad + \sum_d S \left(\frac{p(d)}{p(s)} - \sum_c S \frac{p(c)}{p(s)} T(a, b, c; d) \right) \\ &= p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \frac{1 - p(s)}{p(s)} \\ &= p(s) - (1 - p(s)) \frac{1 - p(s)}{p(s)} + \frac{1 - p(s)}{p(s)} \\ &= p(s) + (1 - p(s)) = 1. \end{aligned}$$

Similarly, for any $a, b, c \in S$,

$$\sum_{d \in S} T(a, s, c; d) = 1 \text{ and } \sum_{d \in S} T(s, b, c; d) = 1.$$

For any $a \in S$,

$$\begin{aligned} \sum_{d \in S} T(a, s, s; d) &= T(a, s, s; s) + \sum_{d \in S} T(a, s, s; d) \\ &= p(s) \left(1 + \left(\frac{1-p(s)}{p(s)} \right)^3 \right) - \sum_b \sum_c \sum_d \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d) \\ &\quad + \sum_{d \in S} \left(p(d) \left(1 - \left(\frac{1-p(s)}{p(s)} \right)^2 \right) + \sum_b \sum_c \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d) \right) \\ &= p(s) \left(1 + \left(\frac{1-p(s)}{p(s)} \right)^3 \right) + (1-p(s)) \left(1 + \left(\frac{1-p(s)}{p(s)} \right)^2 \right) \\ &= p(s) + \frac{(1-p(s))^3}{p(s)^2} + 1 - p(s) - \frac{(1-p(s))^3}{p(s)^2} \\ &= 1. \end{aligned}$$

Similarly, for any $b, c \in S$,

$$\sum_{d \in S} T(s, b, s; d) = 1 \text{ and } \sum_{d \in S} T(s, s, c; d) = 1.$$

Finally,

$$\begin{aligned} \sum_{d \in S} T(s, s, s; d) &= T(s, s, s; s) + \sum_{d \in S} T(s, s, s; d) \\ &= p(s) \left(1 - \left(\frac{1-p(s)}{p(s)} \right)^4 \right) + \sum_a \sum_b \sum_c \sum_d \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d) \\ &\quad + \sum_{d \in S} \left(p(d) \left(1 + \left(\frac{1-p(s)}{p(s)} \right)^3 \right) - \sum_a \sum_b \sum_c \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d) \right) \\ &= p(s) - \frac{(1-p(s))^4}{p(s)^3} + 1 - p(s) + \frac{(1-p(s))^4}{p(s)^3} \\ &= 1. \end{aligned}$$

9.3.2. Proof of (9) of Theorem 9.6 (r -reversible)

To prove point (9), we define now the following condition:

Cond. 24. — For any $a, b, c, d \in S$, $p(a)T(a, b, c; d) = p(d)T(b, c, d; a)$. Hence, by Theorems 3.1 and 4.3,

$$\begin{aligned} (9.17) \quad &\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \rangle\text{-reversible}\}) \\ &= \dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 21} + \text{Cond. 22} + \text{Cond. 23} + \text{Cond. 24}\} \end{aligned}$$

Now, we define a condition similar to Cond. 24 but only on S :

Cond 24*. — For any $a, b, c, d \in S$, $p(a)T(a, b, c; d) = p(d)T(b, c, d; a)$.

We have some properties that connect all these previous conditions by the two following Lemmas 9.10 and 9.11.

LEMMA 9.10. — (Cond. 21 + Cond. 22 + Cond. 24) \Leftrightarrow (Cond. 21 + Cond. 24)

Proof. — \Rightarrow is obvious. Now to prove \Leftarrow we do the following computation: for any $a, c, d \in S$,

$$\begin{aligned} \sum_b p(b)T(a, b, c; d) &= \sum_b p(b) \frac{p(d)}{p(a)} T(b, c, d; a) \\ &= \sum_b p(b) \frac{p(d)}{p(a)} \frac{p(a)}{p(b)} T(c, d, a; b) = p(d). \end{aligned}$$

LEMMA 9.11. — (Cond. 21 + Cond. 24) \Leftrightarrow (Cond. 20 + Cond. 24*)

Proof. — This proof is algebraic.

\Rightarrow . — Let suppose that T satisfy Cond. 21 + Cond. 24. Then Cond. 24* obviously holds. Now, we will prove that Cond. 20 holds too. For any $a, b, c \in S$,

$$T(a, b, c; s) = 1 - \sum_d T(a, b, c; d).$$

For any $a, b, d \in S$,

$$\begin{aligned} T(a, b, s; d) &= \frac{p(d)}{p(s)} T(d, a, b; s) \\ &= \frac{p(d)}{p(s)} \left(1 - \sum_c T(d, a, b; c) \right) = \frac{p(d)}{p(s)} - \sum_c \frac{p(c)}{p(s)} T(a, b, c; d). \end{aligned}$$

Similarly, we get (9.3) and (9.4).

For any $a, b \in S$,

$$\begin{aligned} T(a, b, s; s) &= 1 - \sum_d T(a, b, s; d) \\ &= 1 - \sum_d \left(\frac{p(d)}{p(s)} - \sum_c \frac{p(c)}{p(s)} T(a, b, c; d) \right) \\ &= \frac{2p(s) - 1}{p(s)} + \sum_c \sum_d \frac{p(c)}{p(s)} T(a, b, c; d) \\ &= p(s) - \frac{(1 - p(s))^2}{p(s)} + \sum_c \sum_d \frac{p(c)}{p(s)} T(a, b, c; d) \\ &= p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_c \sum_d \frac{p(c)}{p(s)} T(a, b, c; d). \end{aligned}$$

Similarly, we get (9.6) and (9.7).

For any $a, d \in S$,

$$\begin{aligned}
T(a, s, s; d) &= \frac{p(d)}{p(s)} T(d, a, s; s) \\
&= \frac{p(d)}{p(s)} \left(2 - \frac{1}{p(s)} + \sum_b \sum_c \frac{p(b)}{p(s)} T(d, a, b; c) \right) \\
&= \frac{p(d)}{p(s)} \left(2 - \frac{1}{p(s)} \right) + \sum_b \sum_c \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d) \\
&= p(d) \left(1 - \left(\frac{1-p(s)}{p(s)} \right)^2 \right) + \sum_b \sum_c \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d);
\end{aligned}$$

Similarly, we get (9.10) and (9.9).

For any $a \in S$,

$$\begin{aligned}
T(a, s, s; s) &= 1 - \sum_d T(a, s, s; d) \\
&= 1 - \sum_d \left(\frac{p(d)}{p(s)} \left(2 - \frac{1}{p(s)} \right) + \sum_b \sum_c \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d) \right) \\
&= \frac{3p(s)^2 - 3p(s) + 1}{p(s)^2} - \sum_b \sum_c \sum_d \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d) \\
&= p(s) \left(1 + \left(\frac{1-p(s)}{p(s)} \right)^3 \right) - \sum_b \sum_c \sum_d \frac{p(b)p(c)}{p(s)^2} T(a, b, c; d);
\end{aligned}$$

Similarly, we get (9.13) and (9.12).

For any $d \in S$,

$$\begin{aligned}
T(s, s, s; d) &= \frac{p(d)}{p(s)} T(s, s, d; s) \\
&= p(d) \left(1 - \frac{(1-p(s))^3}{p(s)^3} \right) - \sum_a \sum_b \sum_c \frac{p(b)p(c)p(d)}{p(s)^3} T(b, c, d; a) \\
&= p(d) \left(1 + \left(\frac{1-p(s)}{p(s)} \right)^3 \right) - \sum_a \sum_b \sum_c \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d)
\end{aligned}$$

and, finally,

$$\begin{aligned}
T(s, s, s; s) &= 1 - \sum_d T(s, s, s; d) \\
&= 1 - \sum_d \left(p(d) \left(1 + \frac{(1-p(s))^3}{p(s)^3} \right) \right. \\
&\quad \left. - \sum_a \sum_b \sum_c \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d) \right)
\end{aligned}$$

$$\begin{aligned}
 &= 1 - (1 - p(s)) \left(1 + \frac{(1 - p(s))^3}{p(s)^3} \right) \\
 &\quad + \sum_a \sum_S \sum_b \sum_S \sum_c \sum_S \sum_d \sum_S \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d) \\
 &= p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^4 \right) + \sum_a \sum_S \sum_b \sum_S \sum_c \sum_S \sum_d \sum_S \frac{p(a)p(b)p(c)}{p(s)^3} T(a, b, c; d).
 \end{aligned}$$

So, Cond. 20 holds.

⇐. — Now, suppose that Cond. 20 and Cond. 24* hold. Cond. 21 hold by Lemma 9.9. We will prove that Cond. 24 holds. It is obvious when $a, b, c, d \in S$ by Cond. 24*. Furthermore, we have the following properties.

For any $a, b, c \in S$,

$$\begin{aligned}
 p(a)T(a, b, c; s) &= p(a) \left(1 - \sum_{d \in S} T(a, b, c; d) \right) \\
 &= p(a) - \sum_{d \in S} p(a)T(a, b, c; d) \\
 &= p(s) \left(\frac{p(a)}{p(s)} - \sum_{d \in S} \frac{p(d)}{p(s)} T(b, c, d; a) \right) \\
 &= p(s)T(b, c, s, a).
 \end{aligned}$$

For any $a, b, d \in S$,

$$\begin{aligned}
 p(a)T(a, b, s; d) &= \frac{p(a)p(d)}{p(s)} - \sum_{c \in S} \frac{p(c)}{p(s)} p(a)T(a, b, c; d) \\
 &= \frac{p(a)p(d)}{p(s)} - \sum_{c \in S} \frac{p(c)}{p(s)} p(d)T(b, c, d; a) \\
 &= p(d) \left(\frac{p(a)}{p(s)} - \sum_{c \in S} \frac{p(c)}{p(s)} T(b, c, d; a) \right) \\
 &= p(d)T(b, s, d; a).
 \end{aligned}$$

Similarly, for any $a, c, d \in S$, $p(a)T(a, s, c; d) = p(d)T(s, c, d; a)$.

For any $b, c, d \in S$,

$$\begin{aligned}
 p(s)T(s, b, c; d) &= p(d) - \sum_{a \in S} p(a)T(a, b, c; d) \\
 &= p(d) \left(1 - \sum_{a \in S} T(b, c, d; a) \right) \\
 &= p(d)T(b, c, d; s).
 \end{aligned}$$

For any $a, b \in S$,

$$\begin{aligned} p(a)T(a, b, s; s) &= p(a)p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_c \sum_d \frac{p(c)}{p(s)} p(a)T(a, b, c; d) \\ &= p(a)p(s) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_c \sum_d \frac{p(c)}{p(s)} p(d)T(b, c, d; a) \\ &= p(s) \left(p(a) \left(1 - \left(\frac{1 - p(s)}{p(s)} \right)^2 \right) + \sum_c \sum_d \frac{p(c)p(d)}{p(s)^2} T(b, c, d; a) \right) \\ &= p(s)T(b, s, s; a). \end{aligned}$$

The other cases are similar and left to the readers.

Due to (9.17) and the two preceding lemmas, we obtain

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \rangle\text{-reversible}\}) \\ \triangleq \dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24}\}.$$

Now, we compute $\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24}\}$ to find the upper bound.

LEMMA 9.12. — For any finite set S ,

$$\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24}\} = \frac{n(n-1)(n^2-3n+4)}{4}.$$

Proof. — This proof is half-algebraic and half-combinatorics. The goal is to use Cond. 24* to split the set $\{T(a, b, c; d) : a, b, c, d \in S\}$ in some subsets such that variables in each subset depend of only one free parameter. The partition is the following one:

$$\begin{aligned} &\{\{T(i, i, i; i)\} : i \in S\} \\ &\bigcup \{\{T(i, i, i; j), T(i, i, j; i), T(i, j, i; i), T(j, i, i; i)\} : i, j \in S, i \neq j\} \\ &\bigcup \{\{T(i, j, i; j), T(j, i, j; i)\} : i, j \in S, i < j\} \\ &\bigcup \{\{T(i, i, j; j), T(i, j, j; i), T(j, j, i; i), T(j, i, i; j)\} : i, j \in S, i \neq j\} \\ &\bigcup \{\{T(i, k, i; j), T(k, i, j; i), T(i, j, i; k), T(j, i, k; i)\} : i, j, k \in S, i \neq j, k, j < k\} \\ &\bigcup \{\{T(i, i, j; k), T(i, j, k; i), T(j, k, i; i), T(k, i, i; j)\} : i, j, k \in S, i \neq j \neq k \neq i\} \\ &\bigcup \{\{T(a, b, c; d), T(b, c, d; a), T(c, d, a; b), T(d, a, c; b)\} \\ &\qquad : a, b, c, d \in S, a \neq b \neq c \neq d \neq a \neq c, d \neq b\} \end{aligned}$$

One can check that, in each subset of this partition, there is exactly only one free variable, according to Cond. 24*, see Table 9.1 to find the equations that connect them. Now, the dimension is just the size of this partition. Enumeration is done in Table 9.1. By adding the fourth column, we find

$$\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24}\} = \frac{n(n-1)(n^2-3n+4)}{4}.$$

Table 9.1. Partition of $\{T(a, b, c; d) : a, b, c, d \in S\}$ according to Cond. 24*. On each line, we detail one of the type of the subset involved in the partition. The first column is the subset type. The second gives the equations that connect the variables in the subset; these equations are obtained by specifications of Cond. 24*. The third column gives conditions on the arguments to get independent sets when we enumerate them. The fourth column is the enumeration of subsets of that type.

Subset type	Involved equations	Conditions on the arguments	Number of subsets of this type
$\{T(i, i, i; i)\}$	$T(i, i, i; i)$	$i \in S$	$ S = n - 1$
$\{T(i, i, i; j), T(i, i, j; i), T(i, j, i; i), T(j, i, i; i)\}$	$p(i)T(i, i, i; j)$ $= p(j)T(i, i, j; i)$ $= p(j)T(i, j, i; i)$ $= p(j)T(j, i, i; i)$	$i, j \in S$ $i \neq j$	$\binom{ S }{1} \binom{ S - 1}{1}$ $= (n - 1)(n - 2)$
$\{T(i, j, i; j), T(j, i, j; i)\}$	$p(i)T(i, j, i; j)$ $= p(j)T(j, i, j; i)$	$i, j \in S$ $i < j$	$\binom{ S }{2} = \frac{(n - 1)(n - 2)}{2}$
$\{T(i, i, j; j), T(i, j, j; i), T(j, j, i; i), T(j, i, i; j)\}$	$p(i)T(i, i, j; j)$ $= p(j)T(i, j, j; i)$ $= p(j)T(j, j, i; i)$ $= p(i)T(j, i, i; j)$	$i, j \in S$ $i \neq j$	$\binom{ S }{2} = \frac{(n - 1)(n - 2)}{2}$
$\{T(i, k, i; j), T(k, i, j; i), T(i, j, i; k), T(j, i, k; i)\}$	$p(i)p(k)T(i, k, i; j)$ $= p(j)p(k)T(k, i, j; i)$ $= p(i)p(j)T(i, j, i; k)$ $= p(j)p(k)T(j, i, k; i)$	$i, j, k \in S$ $i \neq j, k$ $j < k$	$\binom{ S }{1} \binom{ S - 1}{2}$ $= \frac{(n - 1)(n - 2)(n - 3)}{2}$
$\{T(i, i, j; k), T(i, j, k; i), T(k, j, i; i), T(j, i, i; k)\}$	$p(i)p(j)T(i, i, j; k)$ $= p(j)p(k)T(i, j, k; i)$ $= p(j)p(k)T(j, k, i; i)$ $= p(i)p(k)T(k, i, i; j)$	$i, j, k \in S$ $i \neq j \neq k \neq i$	$\binom{ S }{1} \binom{ S - 1}{1} \binom{ S - 2}{1}$ $= (n - 1)(n - 2)(n - 3)$
$\{T(a, b, c; d), T(b, c, d; a), T(c, d, a; b), T(d, a, b; c)\}$	$p(a)p(b)p(c)T(a, b, c; d)$ $= p(b)p(c)p(d)T(b, c, d; a)$ $= p(a)p(c)p(d)T(c, d, a; b)$ $= p(a)p(b)p(d)T(d, a, b; c)$	$a, b, c, d \in S$ $a < b, c, d$ $b \neq c \neq d \neq b$	$\frac{1}{4} S (S - 1)(S - 2)(S - 3)$ $= \frac{(n - 1)(n - 2)(n - 3)(n - 4)}{4}$

To get the lower bound for $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \rangle\text{-reversible}\})$, we use a similar trick that we have done in the proof of Lemma 9.1. We first remark that $T(a, b, c; d) = p(d)$ is a solution and, then by all the previous equations, it is not difficult to construct a neighbourhood whose dimension is $\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24}\}$ and for which we do not lose positivity of $T(a, b, c; d)$ for any $a, b, c, d \in S$. Then, we obtain

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \rangle\text{-reversible}\}) > \dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24}\}.$$

That ends the proof of point (9) of Theorem 9.6.

9.3.3. Proof of (10) of Theorem 9.6 ($r \circ v$ -reversible)

The proof of (10) is similar to the one of (9). Hence, we will omit some parts of the proof that are the same. We only detail the partition in Lemma 9.14, because it differs from the one of Lemma 9.12.

The conditions we will need here are the two following ones.

Cond. 25. — For any $a, b, c, d \in S$, $p(a)T(a, b, c; d) = p(d)T(d, c, b; a)$.

*Cond 25**. — For any $a, b, c, d \in S$, $p(a)T(a, b, c; d) = p(d)T(d, c, b; a)$.

The conditions above are linked by the following lemma.

LEMMA 9.13. — (*Cond. 21 + Cond. 22 + Cond. 25*) \Leftrightarrow (*Cond. 20 + Cond. 25*).

Proof. — The proof is similar to the one of Lemma 9.11.

Hence, by Theorems 3.1 and 4.3 and Lemma 9.13, we obtain

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } \langle r \circ v \rangle\text{-reversible}\}) \\ \leq \dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 25}\}.$$

Now, we compute the upper bound.

LEMMA 9.14. — *For any finite set S :*

$$\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 25}\} = \frac{(n-1)^2(n^2-2n+2)}{2}.$$

Proof. — The proof is similar to the one of Lemma 9.12, except that the variable space is not partitioned in the same way. The new partition (based on *Cond. 25**) and its enumeration is given in the Table 9.2. Thus, the size of this partition is $\frac{(n-1)^2(n^2-2n+2)}{2}$.

The end of the proof is like the ones of Lemmas 9.1 and 9.12. It consists in checking that there exists a neighbourhood of the point $(T(a, b, c; d) = p(d) : a, b, c, d \in S)$ with the good dimension such that any point of this neighbourhood satisfies the required conditions.

9.3.4. Proof of (11) of Theorem 9.6 (D_4 -reversible)

The proof of point (11) is similar to the two previous ones. We begin by introducing the two new following conditions.

Cond. 26. — For any $a, b, c, d \in S$, $T(a, b, c; d) = T(c, b, a; d)$.

*Cond 26**. — For any $a, b, c, d \in S$, $T(a, b, c; d) = T(c, b, a; d)$.

We have then the following relation.

LEMMA 9.15. — (*Cond. 21 + Cond. 24 + Cond. 26*) \Leftrightarrow (*Cond. 20 + Cond. 24 + Cond. 26*).

By Theorems 3.1 and 4.3 and Lemma 9.15, we have

$$\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-reversible}\}) \\ \subset \dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24} + \text{Cond. 26}\}.$$

Now, we compute the dimension.

LEMMA 9.16. —

$$\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24} + \text{Cond. 26}\} = \frac{(n-1)^2(n^2-2n+2)}{2}.$$

Proof. — As before, the main argument is to find the partition of T based on Cond. 24* and Cond. 26*. This partition and its enumeration is given in Table 9.3. Thus, the size of this partition is $\frac{n(n-1)(n^2-n+2)}{8}$.

To prove equality between $\dim(\{A \in \mathcal{T}_S(p) : A \text{ is } D_4\text{-reversible}\})$ and $\dim\{(T(a, b, c; d) : a, b, c, d \in S) : \text{Cond. 24} + \text{Cond. 26}\}$, we use the same trick as developed in the end of the proof of Lemma 9.1.

Table 9.2. Partition of $\{T(a, b, c; d) : a, b, c, d \in S\}$ according to Cond. 25*.

Subset type	Involved equations	Conditions on the arguments	Number of subsets of this type
$\{T(i, i, i; i)\}$	$T(i, i, i; i)$	$i \in S$	$ S = n - 1$
$\{T(i, i, i; j), T(j, i, i; i)\}$	$p(i)T(i, i, i; j)$ $= p(j)T(j, i, i; i)$	$i, j \in S$ $i \neq j$	$\binom{ S }{1} \binom{ S - 1}{1}$ $= (n - 1)(n - 2)$
$\{T(i, i, j; i), T(i, j, i; i)\}$	$p(i)T(i, i, j; i)$ $= p(j)T(i, j, i; i)$	$i, j \in S$ $i \neq j$	$\binom{ S }{1} \binom{ S - 1}{1}$ $= (n - 1)(n - 2)$
$\{T(i, j, i; j), T(j, i, j; i)\}$	$p(i)T(i, j, i; j)$ $= p(j)T(j, i, j; i)$	$i, j \in S$ $i < j$	$\binom{ S }{2} = \frac{(n - 1)(n - 2)}{2}$
$\{T(i, i, j; j), T(j, j, i; i)\}$	$p(i)T(i, i, j; j)$ $= p(j)T(j, j, i; i)$	$i, j \in S$ $i < j$	$\binom{ S }{2} = \frac{(n - 1)(n - 2)}{2}$
$\{T(i, j, j; i)\}$	$T(i, j, j; i)$	$i, j \in S$ $i \neq j$	$\binom{ S }{1} \binom{ S - 1}{1}$ $= (n - 1)(n - 2)$
$\{T(i, i, j; k), T(k, j, i; i)\}$	$p(i)T(i, i, j; k)$ $= p(k)T(k, j, i; i)$	$i, j, k \in S$ $i \neq j \neq k \neq i$	$\binom{ S }{1} \binom{ S - 1}{1} \binom{ S - 2}{1}$ $= (n - 1)(n - 2)(n - 3)$
$\{T(i, j, i; k), T(k, i, j; i)\}$	$p(i)T(i, j, i; k)$ $= p(k)T(k, i, j; i)$	$i, j, k \in S$ $i \neq j \neq k \neq i$	$\binom{ S }{1} \binom{ S - 1}{1} \binom{ S - 2}{1}$ $= (n - 1)(n - 2)(n - 3)$
$\{T(i, j, k; i), T(i, k, j; i)\}$	$T(i, j, k; i)$ $= T(i, k, j; i)$	$i, j, k \in S$ $i \neq j, k$ $j < k$	$\binom{ S }{1} \binom{ S - 1}{2}$ $= \frac{(n - 1)(n - 2)(n - 3)}{2}$
$\{T(j, i, i; k), T(k, i, i; j)\}$	$p(j)T(j, i, i; k)$ $= p(k)T(k, i, i; j)$	$i, j, k \in S$ $i \neq j, k$ $j < k$	$\binom{ S }{1} \binom{ S - 1}{2}$ $= \frac{(n - 1)(n - 2)(n - 3)}{2}$
$\{T(a, b, c; d), T(d, c, b; a)\}$	$p(a)T(a, b, c; d)$ $= p(d)T(d, c, b; a)$	$a, b, c, d \in S$ $a < d$ $a \neq b \neq c \neq a$ $d \neq b, c$	$\frac{1}{2} S (S - 1)(S - 2)(S - 3)$ $= \frac{(n - 1)(n - 2)(n - 3)(n - 4)}{2}$

Table 9.3. Partition of $\{T(a, b, c; d) : a, b, c, d \in S\}$ according to Cond. 24* and Cond. 26*.

Subset type	Involved equations	Conditions on the arguments	Number of subsets of this type
$\{T(i, i, i; i)\}$	$T(i, i, i; i)$	$i \in S$	$ S = n - 1$
$\{T(i, i, i; j), T(i, i, j; i), T(i, j, i; i), T(j, i, i; i)\}$	$p(i)T(i, i, i; j)$ $= p(j)T(i, i, j; i)$ $= p(j)T(i, j, i; i)$ $= p(j)T(j, i, i; i)$	$i, j \in S$ $i \neq j$	$\binom{ S }{1} \binom{ S - 1}{1}$ $= (n - 1)(n - 2)$
$\{T(i, j, i; j), T(j, i, j; i)\}$	$p(i)T(i, j, i; j)$ $= p(j)T(j, i, j; i)$	$i, j \in S$ $i < j$	$\binom{ S }{2} = \frac{(n - 1)(n - 2)}{2}$
$\{T(i, i, j; j), T(i, j, j; i), T(j, j, i; i), T(j, i, i; j)\}$	$p(i)T(i, i, j; j)$ $= p(j)T(i, j, j; i)$ $= p(j)T(j, j, i; i)$ $= p(i)T(j, i, i; j)$	$i, j \in S$ $i < j$	$\binom{ S }{2} = \frac{(n - 1)(n - 2)}{2}$
$\{T(i, i, j; k), T(k, i, i; j), T(j, k, i; i), T(i, j, k; i), T(j, i, i; k), T(i, i, k; j), T(i, k, j; i), T(k, j, i; i)\}$	$p(i)p(j)T(i, i, j; k)$ $= p(j)p(k)T(k, i, i; j)$ $= p(j)p(k)T(j, k, i; i)$ $= p(i)p(k)T(i, j, k; i)$ $= p(i)p(j)T(j, i, i; k)$ $= p(j)p(k)T(i, i, k; j)$ $= p(j)p(k)T(i, k, j; i)$ $= p(i)p(k)T(k, j, i; i)$	$i, j, k \in S$ $i \neq j, k$ $j < k$	$\binom{ S }{1} \binom{ S - 1}{2}$ $= \frac{(n - 1)(n - 2)(n - 3)}{2}$
$\{T(i, j, i; k), T(k, i, j; i), T(i, k, i; j), T(j, i, k; i)\}$	$p(i)p(k)T(i, j, i; k)$ $= p(j)p(k)T(k, i, j; i)$ $= p(i)p(j)T(i, k, i; j)$ $= p(j)p(k)T(j, i, k; i)$	$i, j, k \in S$ $i \neq j, k$ $j < k$	$\binom{ S }{1} \binom{ S - 1}{2}$ $= \frac{(n - 1)(n - 2)(n - 3)}{2}$
$\{T(a, b, c; d), T(d, a, b; c), T(c, d, a; b), T(b, c, d; a), T(c, b, a; d), T(b, a, d; c), T(a, d, c; b), T(d, c, b; a)\}$	$p(a)p(b)p(c)T(a, b, c; d)$ $= p(b)p(c)p(d)T(b, c, d; a)$ $= p(a)p(c)p(d)T(c, d, a; b)$ $= p(a)p(b)p(d)T(d, a, b; c)$ $= p(a)p(b)p(c)T(c, b, a; d)$ $= p(b)p(c)p(d)T(d, c, b; a)$ $= p(a)p(c)p(d)T(a, d, c; b)$ $= p(a)p(b)p(d)T(b, a, d; c)$	$a, b, c, d \in S$ $a < b, c, d$ $b < c, d$ $c \neq d$	$\frac{1}{8} S (S - 1)(S - 2)(S - 3)$ $= \frac{(n - 1)(n - 2)(n - 3)(n - 4)}{8}$

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