



A general stochastic matching model on multigraphs

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Abstract. We extend the general stochastic matching model on graphs introduced in [Mairesse and Moyal \(2016\)](#), to matching models on multigraphs, that is, graphs with self-loops. The evolution of the model can be described by a discrete time Markov chain whose positive recurrence is investigated. Necessary and sufficient stability conditions are provided, together with the explicit form of the stationary probability in the case where the matching policy is ‘First Come, First Matched’.

1. Introduction

Over the past decade, an increasing interest has been dedicated to stochastic systems in which incoming elements are matched according to specified compatibility rules. This is, first, a natural representation of service systems in which customers and servers are of different classes, and where designated classes of servers can serve designated classes of customers. For this general class of queueing models, termed skill-based queueing systems, it is then natural to investigate the conditions for the existence of a stationary state, and under these conditions, to design and control the model at best, for given performance metrics (end-to-end delay, matching rates, fairness, etc.). Such models are classical queueing systems, in the sense that there is a dissymmetry between customers and servers: customers come and depart the system, whereas servers are part of the ‘hardware’, remain in the system, and switch to the service of another customer when they have completed one (with possible vacation times in-between services).

In [Caldentey et al. \(2009\)](#) (see also [Adan and Weiss, 2012](#)), a variant of such skill-based systems was introduced, which are now commonly referred to as ‘Bipartite matching models’ (BM): couples customer/server enter the system at each time point, and customers and servers play symmetric roles: exactly like customers, servers come and go into the system. Upon arrival, they wait for a compatible customer, and as soon as they find one, leave the system together with it. These

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settings are suitable to various fields of applications, among which, blood banks, organ transplants, housing allocation, job search, dating websites, and so on. In both references, compatible customers and servers are matched according to the FCFS (‘First Come, First Served’) service discipline. In [Adan et al. \(2018a\)](#), a subtle dynamic reversibility property is shown, entailing that the stationary state of such systems under FCFS, can be obtained in a product form. Moreover, a sub-additivity property is proved, allowing (under stability conditions) the construction of a unique stationary bi-infinite matching of the customers and servers, by a coupling-from-the-past (CFTP) technique. Interestingly, the product-form of the stationary state can then be adapted to various skill-based queueing models as well, and in particular those applying (various declinations of) the so-called FCFM-ALIS (Assign the Longest Idling Server) service discipline - see e.g. [Adan and Weiss \(2014\)](#), and various extensions of BM models in [Adan et al. \(2018b\)](#); [Büke and Chen \(2015, 2017\)](#). In [Bušić et al. \(2013\)](#), the settings of [Caldentey et al. \(2009\)](#); [Adan and Weiss \(2012\)](#) are generalized to more general service disciplines (termed ‘matching policies’ in this context), and necessary and sufficient conditions for the stability of the system are introduced, which are functions of the compatibility graph and of the matching policy. Moreover, as opposed to the previously cited references, the results in [Bušić et al. \(2013\)](#) do not assume the independence between the types of the entering customer and the entering server. The system is then called Extended Bipartite Matching Model (EBM, for short), and suits applications in which independence between the classes of the customers and servers entering simultaneously cannot be assumed. In [Moyal et al. \(2018\)](#), a CFTP result is obtained, showing the existence of a unique bi-infinite matching in various cases for EBM models, and for a broader class of matching policies than FCFS, thereby generalizing the results of [Adan et al. \(2018a\)](#).

For the purpose of modeling concrete systems, the need then arose to extend these different models. Indeed, in many applications the assumption of pairwise arrivals may appear somewhat artificial, and it is more realistic to assume that arrivals are simple. In addition, all the aforementioned references assume that the compatibility graph is bipartite, namely there are easily identifiable classes of *servers* and classes of *customers*, whatever these mean: donors/receivers, houses/applicants, jobs/applicants, and so on. However, in many cases the context requires that the compatibility graph take a general (i.e., not necessarily bipartite) form. For instance, in dating websites, it is a priori not possible to split items into two sets of classes (customers and servers) with no possible matches within those sets. Similarly, in kidney exchange programs, intra-incompatible couples donor/receiver enter the system, looking for a compatible couple to perform a ‘crossed’ transplant. Then, it is convenient to represent couples donor/receiver as *single* items, and compatibility between couples means that a kidney exchange can be performed between the two couples (the donor of the first couple can give to the receiver of the second, and the donor of the second can give to the receiver of the first). In particular, if one consider blood types as a primary compatibility criterion, the compatibility graph between couples is naturally non-bipartite. Motivated by these observations, a variant model was introduced in [Mairesse and Moyal \(2016\)](#), in which items arrive one by one and the compatibility graph is general, i.e., not necessarily bipartite: specifically, in this so-called *General stochastic Matching model* (GM for short), items enter one by one in discrete time in a buffer, and belong to determinate classes in a finite set \mathcal{V} . Upon each arrival, the class of the incoming item is drawn independently of everything else, from a distribution μ having full support \mathcal{V} . A connected graph G whose set of nodes is precisely \mathcal{V} , determines the compatibility among classes. Then, an incoming item is either immediately matched, if there is a compatible item in line, or else stored in a buffer. It is the role of the matching policy Φ to determine the match of the incoming item in case of a multiple choice. Then, the two matched items immediately leave the system forever. The *stability region* of the model, given G and Φ , is then defined as the set of measures μ such that the model is positive recurrent. A necessary condition for the stability of GM models is provided in [Mairesse and Moyal \(2016\)](#) (see (4.1) below). In particular, the latter condition is empty if and only the compatibility graph is bipartite (which partly justifies why items

enter by pairs in BM and EBM models - otherwise the model could not be stabilizable). On another hand, it is proven in [Mairesse and Moyal \(2016\)](#) that the matching policy ‘Match the Longest’ has a maximal stability region, that is, the latter necessary condition is also sufficient (we then say that the latter policy is *maximal*). However, [Moyal and Perry \(2017\)](#) shows that in fact, aside for a particular class of graphs, random policies are never maximal, and that there always exists a strict priority policy that isn’t maximal either. Then, by adapting the dynamic reversibility argument of [Adan et al. \(2018a\)](#) to the GM models, [Moyal et al. \(2021\)](#) shows that the matching policy First Come, First Matched (FCFM) is also maximal, and derives the stationary probability in a product form. More recently, following the work of [Nazari and Stolyar \(2019\)](#), matching policies of the broader *Max-Weight* type (including ‘Match the Longest’) are shown to be maximal, and drift inequalities allow to bound the speed of convergence to the equilibrium, and the first two moments of the stationary state. Variants of the GM model to the case of (i) hypergraphical structures (i.e. matching items by groups of two or more) and (ii) graphical systems with renegeing are investigated, respectively in [Gurvich and Ward \(2014\)](#); [Nazari and Stolyar \(2019\)](#); [Rahmé and Moyal \(2019\)](#) and [Jonckheere et al. \(2020\)](#) (see also [Boxma et al. \(2011\)](#)).

Motivated again by concrete applications, in the present article we present a further extension of the GM model. Indeed, in various contexts, among which dating websites and peer-to-peer interfaces, it is natural to assume that items *of the same class* can be matched together. Hence, the need to generalize the previous line of research to the case where the matching architecture is a *multigraph* (a graph admitting *self-loops*, that is, edges connecting nodes to themselves), rather than just a graph. This generalization is the core subject of the present paper. We show how several stability results of [Mairesse and Moyal \(2016\)](#); [Moyal et al. \(2021\)](#); [Jonckheere et al. \(2020\)](#) can be generalized to the case of a multigraphical matching structure. As is easily seen, the buffer of a matching model on a multigraph is hybrid by essence: nodes admitting self-loops (if any) admit at most one item in line, whereas nodes with no self-loops (if any) have unbounded queues. A matching model on a multigraph typically has a larger stability region than the corresponding model on a graph on which all self-loops are erased (the *maximal subgraph* of the latter - see Definition 2.2), but the interplay between self-looped nodes and their non-self-looped neighbors needs to be clearly understood: intuitively, the arrival flows to self-looped nodes appear as auxiliary flows helping their neighboring non-self-looped nodes to stabilize their own queues - provided that the arrivals to self-looped nodes don’t match too often with one another. On another hand, in the extreme case where all nodes are self-looped, the model is finite and has a flavor of statistical-physical system: it is an irreducible Markov chain on $\{0, 1\}^{|\mathcal{V}|}$ with local interactions - see Example 5.1 below. *En route*, by showing results for stochastic matching models on multigraphs, we show various results that have their own inner interest for GM models on graphs - see in particular Propositions 4.2 and 4.12 and Sub-section 7.5 below.

This paper is organized as follows: we start by some preliminary in Section 2, and in particular by introducing the main definitions and properties of multigraphs. In Section 3, we formally introduce the present model. In Section 4, we present our main results for GM models on multigraphs, among which, the maximality and the explicit product form of the stationary probability for the FCFM policy, and the maximality of Max-Weight policies. To illustrate these results, several examples are presented in Section 5. The proofs of our main results are then presented in Sections 6, 7 and 8.

2. Preliminary

General notation. We denote by \mathbb{R} the set of real numbers, by \mathbb{N} the set of non-negative integers and by \mathbb{N}_+ the subset of positive integers. For any $p, q \in \mathbb{N}_+$, we denote by $\llbracket p, q \rrbracket$ the integer interval $[p, q] \cap \mathbb{N}_+$. For $a, b \in \mathbb{R}$, we write $a \vee b$ and $a \wedge b$ for the maximum and the minimum of a and b , respectively.

We let \mathfrak{S}_n denote the symmetric group on the set $\llbracket 1, n \rrbracket$, i.e. the set of permutations of $\llbracket 1, n \rrbracket$.

For any finite set A , we denote by $|A|$ the cardinality of A . The set A is often implicitly ordered, and identified with $\llbracket 1, |A| \rrbracket$. The set of probability measures having full support on A is denoted by $\mathcal{M}(A)$.

Words. For $k \in \mathbb{N}_+$ and k finite sets A_1, \dots, A_k , we identify the cartesian product $A_1 \times A_2 \times \dots \times A_k$ with the set, denoted by $A_1 A_2 \dots A_k$, of *words* of length k whose i -th letter is an element of A_i , for all $i \in \llbracket 1, k \rrbracket$. In particular, A^k is identified with the set of words of length k over the alphabet A . We then denote by $A^* \triangleq \bigcup_{k \in \mathbb{N}} A^k$ the set of finite words over the alphabet A . We denote the *length* of $w \in A^*$ by $|w|$, so that if $w \in A^k$, $|w| = k$.

For $w \in A^*$ and $B \subset A$, we introduce the notation $|w|_B \triangleq \text{Card}\{i \in \{1, \dots, |w|\} : w_i \in B\}$. For a letter $a \in A$, we denote simply by $|w|_a \triangleq |w|_{\{a\}}$ the number of occurrences of the letter a in the word w .

The concatenation of k words w^1, w^2, \dots, w^k of A^* , that is, the word w in which appear successively from left to right, the words w^1, w^2, \dots, w^k , is denoted by $w = w^1 w^2 \dots w^k$. In particular, for a word w and a letter i , the word wi denotes the concatenation of the word w with the single-letter word i , in that order. Any word $w \in A^*$ of length $|w| = q$ is written $w = w_1 w_2 \dots w_q$, and for any $i \in \llbracket 1, q \rrbracket$, we denote by $w_{[i]}$ the word of length $|w| - 1$ obtained from w by deleting its i -th letter w_i . The empty word (i.e. the unique word of A^* of length 0) is denoted ε . For any word $w = w_1 w_2 \dots w_q$, the *prefix* of w of length $k \leq q$ is the word $w' = w_1 w_2 \dots w_k$.

For any $w \in A^*$, we let $[w] \triangleq (|w|_a)_{a \in A} \in \mathbb{N}^{|A|}$ be the *commutative image* of w . For any integer q , the vectors of \mathbb{N}^q are denoted as $w \triangleq (w(1), \dots, w(q))$. We let, for any $i \in \llbracket 1, q \rrbracket$, \mathbf{e}_i be the i -th vector of the canonical basis of \mathbb{R}^q .

Multigraphs. Hereafter, a *multigraph* is given by a couple $G = (\mathcal{V}, \mathcal{E})$, where \mathcal{V} is the (finite) set of nodes and $\mathcal{E} \subset \mathcal{V} \times \mathcal{V}$ is the set of edges. All graphs considered hereafter are undirected, that is, $(u, v) \in \mathcal{E} \implies (v, u) \in \mathcal{E}$, for all $u, v \in \mathcal{V}$. We write $u-v$ or $v-u$ for $(u, v) \in \mathcal{E}$, and $u \neq v$ (or $v \neq u$) else. Elements of the form $(v, v) \in \mathcal{E}$, for $v \in \mathcal{V}$, are called *self-loops*. For any multigraph $G = (\mathcal{V}, \mathcal{E})$ and any $U \subset \mathcal{V}$, we denote

$$\mathcal{E}(U) \triangleq \{v \in \mathcal{V} : \exists u \in U, u - v\}$$

the neighborhood of U , and for $u \in \mathcal{V}$, we write for short $\mathcal{E}(u) \triangleq \mathcal{E}(\{u\})$. The set \mathcal{V} can then be partitioned in $\mathcal{V} = \mathcal{V}_1 \cup \mathcal{V}_2$, where $\mathcal{V}_1 \triangleq \{u \in \mathcal{V} : u-u\}$ and $\mathcal{V}_2 \triangleq \{u \in \mathcal{V} : u \neq u\}$, i.e., \mathcal{V}_1 contains all nodes from which a self-loop emanates, if any, and \mathcal{V}_2 is the complement set of \mathcal{V}_1 in \mathcal{V} . A multigraph having no self-loop, that is, a couple $G = (\mathcal{V}, \mathcal{E})$ such that $\mathcal{V}_1 = \emptyset$, is simply a *graph*. Observe that, with respect to the classical notion of multigraphs, we assume hereafter that all edges are simple. For any node $i \in \mathcal{V}$, we denote by

$$\text{deg}(i) = |\mathcal{E}(i)|,$$

the *degree* of node i , that is, the number of neighbors of i (possibly including i itself if $i \in \mathcal{V}_1$). Notice that, by defining \mathcal{E} as a set of (ordered) couples as we did above, for any i, j such that $i-j$, (i, j) appears in \mathcal{E} together with (j, i) . In particular we get that

$$\sum_{i \in \mathcal{V}} \text{deg}(i) = |\mathcal{E}|. \quad (2.1)$$

For any multigraph $G = (\mathcal{V}, \mathcal{E})$ and any $U \subset \mathcal{V}$, the *subgraph induced by U* in G is the multigraph $(U, \mathcal{E} \cap (U \times U))$. An *independent set* of G is a non-empty subset $\mathcal{I} \subset \mathcal{V}$ which does not include any pair of neighbors, i.e. : $(\forall (i, j) \in \mathcal{I}^2, i \neq j)$. We let $\mathbb{I}(G)$ be the set of independent sets of G . Then, observe that $\forall \mathcal{I} \in \mathbb{I}(G), \mathcal{I} \cap \mathcal{V}_1 = \emptyset$, i.e. $\mathcal{I} \subset \mathcal{V}_2$. An independent set is said maximal, if it is not strictly included in another independent set.

Let us now recall and introduce the following definitions:

Definition 2.1. A graph $G = (\mathcal{V}, \mathcal{E})$ is said to be complete q -partite (or blow-up graph of order q) if \mathcal{V} can be partitioned into q maximal independent sets $\mathcal{I}_1, \dots, \mathcal{I}_q$, such that for any $k, \ell \in \llbracket 1, q \rrbracket$, $k \neq \ell$ and any $i_k \in \mathcal{I}_k$ and $i_\ell \in \mathcal{I}_\ell$, we have that $i_k - i_\ell$.

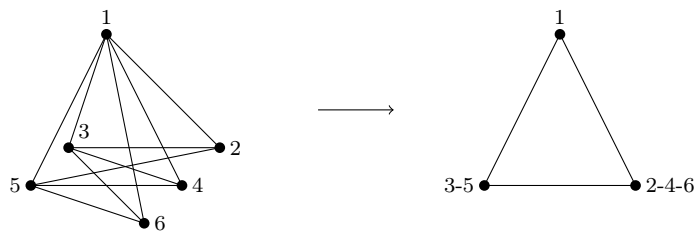


FIGURE 2.1. Complete 3-partite subgraph (left), complete graph of order 3 (right).

In other words, a complete q -partite graph is a blow-up of the complete graph of size q , in the sense that all nodes are duplicated into one, or several distinct and unconnected nodes having the same neighbors as the original node. See an example on Figure 2.1.

Definition 2.2. Let $G = (\mathcal{V}, \mathcal{E})$ be a multigraph. The *maximal subgraph* of G is the graph $\check{G} = (\mathcal{V}, \check{\mathcal{E}})$ obtained by deleting all self-loops in G , that is

$$\check{\mathcal{E}} \triangleq \mathcal{E} \setminus \{(i, i) : i \in \mathcal{V}_1\}. \tag{2.2}$$

See an example on Figure 2.2.

Definition 2.3. Let $G = (\mathcal{V}_1 \cup \mathcal{V}_2, \mathcal{E})$ be a multigraph. The *minimal blow-up graph* of G is the graph $\hat{G} = (\hat{\mathcal{V}}, \hat{\mathcal{E}})$ defined as follows:

$$\hat{\mathcal{V}} \triangleq \mathcal{V} \cup \underline{\mathcal{V}}_1 \quad \text{and} \quad \hat{\mathcal{E}} \triangleq \check{\mathcal{E}} \cup \underline{\mathcal{E}}_1, \tag{2.3}$$

where $\underline{\mathcal{V}}_1$ is a disjoint copy of \mathcal{V}_1 , $\check{\mathcal{E}}$ is defined by (2.2) and

$$\underline{\mathcal{E}}_1 \triangleq \{(\underline{i}, j) : (i, j) \in \mathcal{E}, i \in \mathcal{V}_1, j \in \mathcal{V}\}.$$

In other words, \hat{G} is obtained from G by duplicating each node having a self-loop by two nodes having the same neighborhood and replacing each self-loop by an edge between the node and its copy. See an example in Figure 2.2. For any set $\mathcal{A} \subset \mathcal{V}_1$, we denote by $\underline{\mathcal{A}}$ the set of all copies of elements of \mathcal{A} , that is

$$\underline{\mathcal{A}} \triangleq \{\underline{i} : i \in \mathcal{A}\}.$$

For any element $j \in \underline{\mathcal{A}}$, we will also denote by \underline{j} the unique element $i \in \mathcal{A}$ such that $j = \underline{i}$. The maximal subgraph \check{G} of G is then called *reduced graph* of \hat{G} .

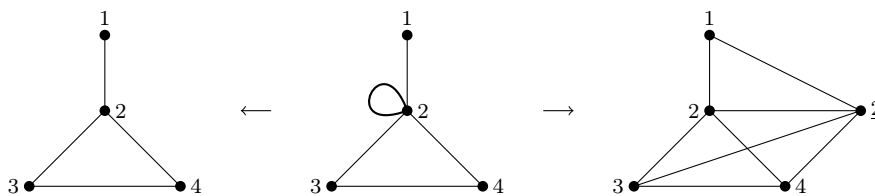


FIGURE 2.2. A multigraph G (middle), its maximal subgraph \check{G} (left) and its minimal blow-up graph \hat{G} (right).

Throughout this paper, all considered multigraphs are connected, that is, for any $u, v \in \mathcal{V}$, there exists a subset $\{v_0 \triangleq u, v_1, v_2, \dots, v_p \triangleq v\} \subset \mathcal{V}$ such that $v_i - v_{i+1}$, for any $i \in \llbracket 0, p - 1 \rrbracket$.

3. The model

All the random variables (r.v., for short) hereafter are defined on a common probability space $(\Omega, \mathcal{F}, \mathbb{P})$.

3.1. *Stochastic matching model on a multigraph.* Generalizing the model introduced in [Mairesse and Moyat \(2016\)](#) to multigraphs (rather than only graphs), a *matching model* is formally specified by the triple (G, Φ, μ) , where

- (1) $G = (\mathcal{V}, \mathcal{E})$ is a connected multigraph having at least two nodes;
- (2) Φ is the *matching policy*, to be properly defined later;
- (3) μ is an element of $\mathcal{M}(\mathcal{V})$, i.e. a probability measure having full support \mathcal{V} .

The dynamics of the matching model associated to (G, Φ, μ) is then similar to that of stochastic matching models on general graphs, as in [Mairesse and Moyat \(2016\)](#): start with an empty “buffer” and, for any $n \in \mathbb{N}_+$, draw an element V_n of \mathcal{V} from the probability measure μ , independently of $\sigma(\{V_1, V_2, \dots, V_{n-1}\})$, and apply the following rules:

- if there is no element of class i in the buffer such that $V_n - i$, then add an item of class V_n to the buffer;
- otherwise, do not add V_n and remove from the buffer an element of class i such that $V_n - i$ (we say that V_n and i are *matched* together). If several elements i of the buffer are such that $V_n - i$, the one to be removed depends on a *matching policy* to be specified for the considered model.

3.2. *State spaces.* We reproduce here the state description of the model introduced in [Mairesse and Moyat \(2016\)](#) for the stochastic model on general graphs, and then [Moyat et al. \(2021\)](#) for the same model under FCFM. Fix a connected multigraph $G = (\mathcal{V}, \mathcal{E})$, in the sense specified above, until the end of this section. Fix an integer $n_0 \geq 1$, a realization v_1, \dots, v_{n_0} of V_1, \dots, V_{n_0} , and define the word $z \triangleq v_1 \dots v_{n_0} \in \mathcal{V}^*$. Then, for any matching policy Φ , there exists a unique *matching* of the word z , that is, a graph on the set of nodes $\{v_1, \dots, v_{n_0}\}$, whose edges represent the matches performed in the system until time n_0 , if the successive arrivals are given by z . This matching is denoted by $M^\Phi(z)$. The state of the system is then defined as the word $W^\Phi(z) \in \mathcal{V}^*$, whose letters are the classes of the unmatched items at time n_0 , i.e. the isolated vertices in the matching $M^\Phi(z)$, in their order of arrivals. The word $W^\Phi(z)$ is called *queue detail* at time n_0 . Then, any admissible queue detail belongs to the set

$$\mathbb{W} \triangleq \left\{ w \in \mathcal{V}^* : \forall i \neq j \text{ s.t. } (i, j) \in \mathcal{E}, |w|_i |w|_j = 0 \text{ and } \forall i \in \mathcal{V}_1, |w|_i \leq 1 \right\}. \quad (3.1)$$

As will be seen below, depending on the service discipline Φ , we can also restrict the available information on the state of the system at time n_0 , to a vector only keeping track of the number of items of the various classes remaining unmatched at n_0 , that is, of the number of occurrences of the various letters of the alphabet \mathcal{V} in the word $W^\Phi(z)$. This restricted state thus equals the commutative image of $W^\Phi(z)$ and is called *class detail* of the system. It takes values in the set

$$\begin{aligned} \mathbb{X} &\triangleq \left\{ x \in \mathbb{N}^{|\mathcal{V}|} : \forall i \neq j \text{ s.t. } (i, j) \in \mathcal{E}, x(i)x(j) = 0 \text{ and } \forall i \in \mathcal{V}_1, x(i) \leq 1 \right\} \\ &= \left\{ [w] : w \in \mathbb{W} \right\}. \end{aligned}$$

3.3. *Matching policies.* We now present and formally define the set of usual matching policies that can be considered,

Definition 3.1. A matching policy Φ is said *admissible* if the choice of the match of an incoming item depends solely on the queue detail upon the arrival (and possibly on an independent uniform draw, in case of a tie).

An admissible matching policy can be formally characterized by an action \odot_Φ of \mathcal{V} on \mathbb{W} , defined as follows: if w is the queue detail at a given time and the input is augmented by the arrival of $v \in \mathcal{V}$ at that time, then the new queue detail w' and w satisfies the relation:

$$w' = w \odot_\Phi v. \tag{3.2}$$

Notice that the action \odot_Φ is possibly random. See below.

3.3.1. *Matching policies that depend on the arrival times.* In ‘First Come, First Matched’ (FCFM), the oldest item in line is chosen, so the map \odot_{FCFM} is given, for all $w \in \mathbb{W}$ and all $v \in \mathcal{V}$, by

$$w \odot_{\text{FCFM}} v \triangleq \begin{cases} wv & \text{if } |w|_{\mathcal{E}(v)} = 0, \\ w_{[\Phi(w,v)]} & \text{else, where } \Phi(w, v) = \min\{k \in [1; |w|] : w_k \in \mathcal{E}(v)\}. \end{cases}$$

In ‘Last Come, First Matched’ (LCFM), the updating map \odot_{LCFM} is analog to \odot_{FCFM} , for $\Phi(w, v) = \max\{k \in [1; |w|] : w_k \in \mathcal{E}(v)\}$.

3.3.2. *Class-admissible matching policies.* A matching policy Φ is said to be *class-admissible* if it can be implemented upon the sole knowledge of the class-detail of the system. Let us define, for any $x \in \mathbb{X}$ and any $v \in \mathcal{V}$,

$$\mathcal{P}(x, v) \triangleq \{j \in \mathcal{E}(v) : x(j) > 0\},$$

the set of classes of available compatible items with the entering class v -item, if the class-detail of the system is given by x . Then, a class-admissible policy Φ is fully characterized by a (possibly random) mapping p_Φ , such that $p_\Phi(x, v)$ denotes the class of the match chosen by the entering v -item under Φ , in a system of class-detail x , such that $\mathcal{P}(x, v)$ is non-empty. Then, the arrival of v entails the following action on the class-detail:

$$x \odot_\Phi v \triangleq \begin{cases} x + \mathbf{e}_v & \text{if } \mathcal{P}(x, v) = \emptyset, \\ x - \mathbf{e}_{p_\Phi(x,v)} & \text{else.} \end{cases} \tag{3.3}$$

Remark 3.2. As is easily seen, to any class-admissible policy Φ corresponds an admissible policy, if one makes precise the rule of choice of match for the incoming items *within* the class that is chosen by Φ , in the case where more than one item of that class is present in the system. In this paper, we always assume that within classes, the item chosen is always the *oldest* in line, i.e. we always apply the FCFM policy *within classes*. Under this convention, any class-admissible policy Φ is admissible, that is, the mapping \odot_Φ from $\mathbb{X} \times \mathcal{V}$ to \mathbb{X} can be detailed into a map \odot_Φ from $\mathbb{W} \times \mathcal{V}$ to \mathbb{W} , as in (3.2), such that for any queue detail w and any v ,

$$[w \odot_\Phi v] = [w] \odot_\Phi v.$$

Class-admissible random policies. In a random policy, the only information that is needed to determine the choice of the match of an incoming item is whether its various compatible classes have an empty queue or not. Specifically, the order of preference of each incoming item is drawn upon the arrival following a given probability distribution; then, the considered item investigates its compatible classes in that order, until it finds one having a non-empty buffer, if any. The incoming item is then matched with an item of the latter class. In other words, upon each arrival of an item of class v , a permutation $\sigma = (\sigma(1), \dots, \sigma(|\mathcal{E}(v)|))$ is drawn from a given probability distribution on $\mathfrak{S}_{\mathcal{E}(v)}$, and we set

$$p_\Phi(x, v) \triangleq \sigma(k), \text{ where } k = \min\{i \in \mathcal{E}(v) : \sigma(i) \in \mathcal{P}(x, v)\}. \tag{3.4}$$

In particular, the uniform policy U corresponds to the uniform distribution on $\mathfrak{S}_{\mathcal{E}(v)}$.

Priority policies. In a priority policy, for any $v \in \mathcal{V}$, the order of preference of v in $\mathcal{E}(v)$ is fixed beforehand. In other words, upon the arrival of an item of class v , the permutation σ of $\mathfrak{S}_{\mathcal{E}(v)}$ is deterministic and corresponds to the order of preference of class v -item in $\mathcal{E}(v)$. This is thus a particular case of random policy.

Max-Weight policies. The Max-Weight (MW) policies are an important class of class-admissible policies, in which matches are based upon the queue length and a fixed reward that is associated to each match. Formally, for any $(i, j) \in \mathcal{E}$, we let $w_{i,j}$ be the reward associated to the match of an i -item with a j -item, and fix a real parameter β .

Then, in a system of class-detail x , the match of the incoming v -item is given by

$$p_\Phi(x, v) \triangleq \operatorname{argmax} \{ \beta x(j) + w_{v,j} : j \in \mathcal{P}(x, v) \},$$

where ties are broken uniformly at random whenever the above is non-unique. In other words, j maximizes a linear combination of the queue-size and the rewards. Several particular cases are to be mentioned:

- (i) If $\beta > 0$ and the rewards are constant (i.e. $w_{i,j} = w_{i',j'}$, for any (i, j) and $(i', j') \in \mathcal{E}$), then the matching policy is ‘Match the Longest’ (ML), i.e., the incoming v -item is matched upon the arrival with an item of the compatible class having the longest queue size (ties being broken uniformly at random).
- (ii) If $\beta < 0$ and the rewards are constant, then the matching policy is ‘Match the Shortest’ (MS), i.e., the incoming v -item is matched upon the arrival with an item of the compatible class having the shortest queue size (ties being broken uniformly at random).
- (iii) If $\beta = 0$ and $w_{i,j} \neq w_{i,j'}$ for any $i \in \mathcal{V}$ and any $j \neq j' \in \mathcal{E}(i)$ (implying that there is a strict ordering of rewards for all possible matches of any given class), then the matching policy is of a priority type, defined above.

3.3.3. \mathcal{V}_2 -favorable policies. An important class of matching policies is given by the following:

Definition 3.3. We say that an admissible matching policy Φ on G is \mathcal{V}_2 -favorable if any incoming item always prioritizes a match with a compatible item of class in \mathcal{V}_2 over a compatible item of class in \mathcal{V}_1 , whenever it has the choice. Formally, if the class-detail is given by $x \in \mathbb{X}$ and the arrival is of class v , it never occurs that the incoming v -item is matched with a j -item, for some $j \in \mathcal{V}_1$, while $\mathcal{P}(x, v) \cap \mathcal{V}_2 \neq \emptyset$.

3.4. *Primary Markov representation.* The Markov representation of the model is similar to that of general matching models on graphs. Denote, for all $w \in \mathbb{W}$ and all $n \geq 1$, by $W_n^{\{w\}}$, the buffer-content at time n (i.e. just after the arrival of the item V_n) if the buffer-content at time 0 was set to w . In other words,

$$\begin{cases} W_0^{\{w\}} &= w, \\ W_n^{\{w\}} &= W^\Phi(wV_1 \dots V_n), \quad n \in \mathbb{N}_+. \end{cases}$$

It readily follows from (3.2) and Remark 3.2 that the buffer-content sequence $\{W_n^{\{w\}}\}_{n \in \mathbb{N}}$ is a Markov chain. Indeed, for any $w \in \mathbb{W}$, we have

$$W_{n+1}^{\{w\}} = W_n^{\{w\}} \odot_\Phi V_{n+1}, \quad \forall n \in \mathbb{N}.$$

For a fixed initial condition and for all $n \in \mathbb{N}$, we denote, for all $B \subset \mathcal{V}$, by $W_n(B)$, the number of items in line of classes in B at time n , and by $|W_n|$, the total number of items in the system at

time n . In other words,

$$\begin{cases} W_n(B) & \triangleq \sum_{i \in B} W_n(i), \\ |W_n| & \triangleq W_n(\mathcal{V}) = \sum_{i \in \mathcal{V}} W_n(i). \end{cases}$$

In line with [Mairesse and Moyal \(2016\)](#), for any admissible matching policy Φ , we define the *stability region* associated to G and Φ as the set of measures

$$\text{STAB}(G, \Phi) \triangleq \{ \mu \in \mathcal{M}(\mathcal{V}) : \{W_n\}_{n \in \mathbb{N}} \text{ is positive recurrent} \}. \tag{3.5}$$

Definition 3.4. We say that a multigraph G is stabilizable if $\text{STAB}(G, \Phi) \neq \emptyset$, for some matching policy Φ . If not, G is said non-stabilizable.

Remark 3.5. If G is such that $\mathcal{V} = \mathcal{V}_1$, i.e. all nodes of the multigraph have a self-loop, we say, for obvious reasons, that the considered matching models are *finite*. Then any matching model on G is necessarily stable, that is, for any admissible Φ we have that

$$\text{STAB}(G, \Phi) = \mathcal{M}(\mathcal{V}).$$

Indeed, the Markov chain $\{W_n\}_{n \in \mathbb{N}}$ is irreducible on the finite state space \mathbb{W} , containing only words having size less or equal to the cardinality of the largest independent set of G .

4. Main results

We now state the main results of this paper. Similarly to [Mairesse and Moyal \(2016\)](#), we will be led to consider the set

$$\text{NCOND}(G) \triangleq \{ \mu \in \mathcal{M}(\mathcal{V}) : \forall \mathcal{I} \in \mathbb{I}(G), \mu(\mathcal{I}) < \mu(\mathcal{E}(\mathcal{I})) \}. \tag{4.1}$$

Let us immediately observe that

Lemma 4.1. *For any connected multigraph G , we have that*

$$\text{NCOND}(\check{G}) \subseteq \text{NCOND}(G).$$

Proof: Let $\mu \in \text{NCOND}(\check{G})$ and $\mathcal{I} \in \mathbb{I}(G)$. Plainly, \mathcal{I} is then also an element of $\mathbb{I}(\check{G})$, so we have that $\mu(\mathcal{I}) < \mu(\check{\mathcal{E}}(\mathcal{I}))$. But as $\mathcal{I} \subset \mathcal{V}_2$ we also have that $\check{\mathcal{E}}(\mathcal{I}) = \mathcal{E}(\mathcal{I})$, which concludes the proof. \square

It is stated in Theorem 1 of [Mairesse and Moyal \(2016\)](#) that, if G is a graph, the set $\text{NCOND}(G)$ is non-empty if and only if G is not a bipartite graph. This result can be generalized to multigraphs, and completed as follows,

Proposition 4.2. *For any connected multigraph G , we have that*

$$\text{NCOND}(G) \neq \emptyset \iff G \text{ is not a bipartite graph.}$$

In that case, recalling (2.1), the probability measure μ_{deg} defined by

$$\mu_{deg}(i) = \frac{deg(i)}{|\mathcal{E}|}, \quad i \in \mathcal{V}, \tag{4.2}$$

is always an element of $\text{NCOND}(G)$.

Proposition 4.2 is proven in Section 6. From Proposition 2 in [Mairesse and Moyal \(2016\)](#), whenever G is a graph (i.e., $\mathcal{V}_1 = \emptyset$), the set $\text{STAB}(G, \Phi)$ is included in $\text{NCOND}(G)$ for any admissible policy Φ . In other words, for any measure μ , belonging to $\text{NCOND}(G)$ is necessary for the stability of the system (G, Φ, μ) , for any Φ . A similar result holds for any multigraph G :

Proposition 4.3. *For any connected multigraph $G = (\mathcal{V}, \mathcal{E})$ and any admissible matching policy Φ , we have that*

$$\text{STAB}(G, \Phi) \subset \text{NCOND}(G).$$

Proof: The proof is analog to that of Proposition 2 in Mairesse and Moyal (2016). □

Hence, the notion of maximality of a matching policy is:

Definition 4.4. For any connected multigraph G that is not a bipartite graph, a matching policy Φ is said maximal if the sets $\text{STAB}(G, \Phi)$ and $\text{NCOND}(G)$ coincide.

Whenever G is a graph, Theorem 1 of Moyal et al. (2021) shows, first, that the policy ‘First Come, First Matched’ (FCFM) is maximal, and second, that the stationary probability of the chain $\{W_n\}_{n \in \mathbb{N}}$ can be expressed in a remarkable product form. We generalize this result to multigraphs:

Theorem 4.5. *The matching policy ‘First Come, First Matched’ is maximal: for any connected multigraph G that is not a bipartite graph, we have that $\text{STAB}(G, \text{FCFM}) = \text{NCOND}(G)$. Moreover, for any $\mu \in \text{NCOND}(G)$ the unique stationary probability Π_W of the chain $\{W_n\}_{n \in \mathbb{N}}$ is defined by*

$$\begin{cases} \Pi_W(\varepsilon) &= \alpha; \\ \Pi_W(w) &= \alpha \prod_{l=1}^q \frac{\mu(w_l)}{\mu(\mathcal{E}(\{w_1, \dots, w_l\}))}, \text{ for all } w = w_1 \dots w_q \in \mathbb{W} \setminus \{\varepsilon\}, \end{cases}$$

where

$$\alpha^{-1} = 1 + \sum_{\mathcal{I} \in \mathbb{I}(\check{G})} \sum_{\sigma \in \mathfrak{S}_{|\mathcal{I}|}} \prod_{i=1}^{|\mathcal{I}|} \frac{\mu(e_{\sigma(i)})}{\mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})) - \mu(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2)}, \tag{4.3}$$

and where we denote $\mathcal{I} = \{e_1, \dots, e_{|\mathcal{I}|}\}$ for any $\mathcal{I} \in \mathbb{I}(\check{G})$.

Theorem 4.5 is proven in section 7.

Remark 4.6. If the model is finite, i.e. all nodes of G have self-loops or in other words, $\mathcal{V}_2 = \emptyset$, then it readily follows from Theorem 4.5 that the unique stationary probability on the finite state space \mathbb{W} , is given by

$$\begin{cases} \Pi_W(\varepsilon) &= \alpha; \\ \Pi_W(e_{\sigma(1)} \dots e_{\sigma(|\mathcal{I}|)}) &= \alpha \prod_{i=1}^{|\mathcal{I}|} \frac{\mu(e_{\sigma(i)})}{\mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\}))}, \text{ for all } \mathcal{I} \in \mathbb{I}(\check{G}), \sigma \in \mathfrak{S}_{|\mathcal{I}|}, \end{cases}$$

with the normalizing constant

$$\alpha = \left[1 + \sum_{\mathcal{I} \in \mathbb{I}(\check{G})} \sum_{\sigma \in \mathfrak{S}_{|\mathcal{I}|}} \prod_{i=1}^{|\mathcal{I}|} \frac{\mu(e_{\sigma(i)})}{\mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\}))} \right]^{-1}.$$

On another hand, as is shown in Theorem 3.2 of Jonckheere et al. (2020), all Max-Weight matching policies such that $\beta > 0$ are maximal whenever G is a graph. (Notice that Theorem 3.2 in Jonckheere et al. (2020) is in fact shown only for $\beta = 1$, however a generalization to any $\beta > 0$ is straightforward, by modifying the rewards accordingly.) In particular, the maximality of ‘Match the Longest’ (ML) for GM models was first proven in Theorem 2 of Mairesse and Moyal (2016), as a consequence of the corresponding result for EBM models, see Theorem 7.1 of Bušić et al. (2013). This result can also be generalized to multigraphs:

Theorem 4.7. *Any Max-Weight policy Φ such that $\beta > 0$ is maximal: for any multigraph G that is not a bipartite graph, we have that $\text{STAB}(G, \Phi) = \text{NCOND}(G)$.*

Aside from FCFM and Max-Weight policies, we can determine, or lower-bound, the stability region of the model for particular classes of multigraphs.

Definition 4.8. Let G be a connected multigraph. We say that G is complete p -partite, $p \geq 2$, if its maximal subgraph \check{G} is complete p -partite. Then, the minimal blow-up graph \hat{G} is itself called an *extended complete p -partite graph*.

Observe that an extended complete p -partite graph is *not* complete p -partite whenever the construction above is non-trivial, i.e., the multigraph in the above definition is not a graph, see an example on Figure 4.3.

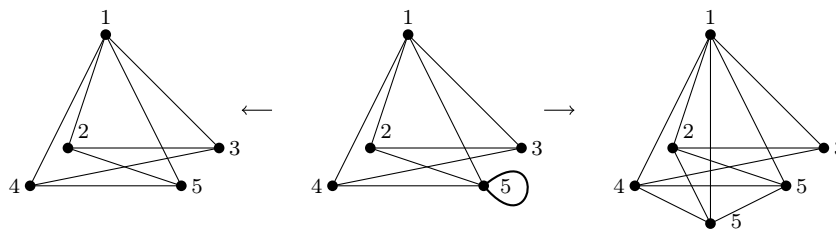


FIGURE 4.3. A multigraph G (middle), its maximal complete 3-partite subgraph \check{G} (left), and extended complete p -partite graph \hat{G} (right).

Theorem 4.9. Let G be a complete p -partite multigraph, $p \geq 2$. Then,

- (i) If $p \geq 3$ or $\mathcal{V}_1 \neq \emptyset$, then any \mathcal{V}_2 -favorable matching policy Φ is maximal, that is, $\text{STAB}(G, \Phi) = \text{NCOND}(G)$.
- (ii) If $p \geq 3$, then $\text{NCOND}(\check{G}) \subset \text{STAB}(G, \Phi)$, for any admissible matching policy Φ .

With the above results in hands, we have the following panorama regarding the stability region of a matching model on a connected multigraph G :

- (i) Any measure μ that does not belong to the set $\text{NCOND}(G)$ makes the system unstable;
- (ii) If G is a bipartite graph, then the model cannot be stable;
- (iii) Otherwise, the region $\text{NCOND}(G)$ is necessarily non-empty, and the models (G, FCFM, μ) and (G, Φ, μ) for any Max-Weight policy Φ with $\beta > 0$, are stable for any $\mu \in \text{NCOND}(G)$. In particular, in that case $\text{NCOND}(G)$ necessarily includes the measure μ_{deg} defined by (4.2), so any model $(G, \Phi, \mu_{\text{deg}})$, for $\Phi = \text{FCFM}$ or $\Phi = \text{MW}$ with $\beta > 0$, is stable.
- (iv) For any complete p -partite multigraph ($p \geq 2$) that is not a bipartite graph and any $\mu \in \text{NCOND}(G)$, any model (G, Φ, μ) such that $\mu \in \text{NCOND}(\check{G})$ or Φ is \mathcal{V}_2 -favorable, is stable.

As a by-product of Theorem 4.9 we can determine, or lower-bound, the stability region of GM models on extended complete p -partite graphs.

Definition 4.10. For any measures $\mu \in \mathcal{M}(\mathcal{V})$ and $\hat{\mu} \in \mathcal{M}(\hat{\mathcal{V}})$, we say that $\hat{\mu}$ extends μ on \hat{G} , and that μ reduces $\hat{\mu}$ on G , if

$$\begin{cases} \hat{\mu}(i) &= \mu(i), & \text{for all } i \in \mathcal{V}_2; \\ \hat{\mu}(i) + \hat{\mu}(\underline{i}) &= \mu(i), & \text{for all } i \in \mathcal{V}_1. \end{cases}$$

Definition 4.11. Let Φ and $\hat{\Phi}$ be two admissible matching policies, respectively on G and \hat{G} . We say that $\hat{\Phi}$ extends Φ on \hat{G} if, for any $\mu \in \mathcal{M}(\mathcal{V})$ and $\hat{\mu} \in \mathcal{M}(\hat{\mathcal{V}})$, whenever both systems (G, Φ, μ) and $(\hat{G}, \hat{\Phi}, \hat{\mu})$ are in the same state $w \in \mathbb{W}$ and welcome the same arrival, Φ and $\hat{\Phi}$ induce the same choice of match, if any.

Proposition 4.12. Let \hat{G} be an extended complete p -partite graph, $p \geq 2$, and \check{G} be its reduced graph.

- (i) If $p \geq 3$ or $\mathcal{V}_1 \neq \emptyset$, then for any matching policy $\hat{\Phi}$ on \hat{G} that extends a \mathcal{V}_2 -favorable policy on G , $\text{STAB}(\hat{G}, \hat{\Phi}) = \text{NCOND}(\hat{G})$.
- (ii) If $p \geq 3$, then for any measure $\hat{\mu}$ on \hat{G} whose reduced measure μ is an element of $\text{NCOND}(\check{G})$, and any matching policy $\hat{\Phi}$ on \hat{G} , the model $(\hat{G}, \hat{\Phi}, \hat{\mu})$ is stable.

The proofs of Theorem 4.7, Theorem 4.9 and Proposition 4.12 are given in section 8.

5. A few examples

In this section, we illustrate our main results by different examples.

Example 5.1. Consider the multigraph G of Figure 5.4, made of four nodes arranged in a square, with a self-loop at each node. Since all nodes have a self-loop, it follows from Remark 3.5 that any

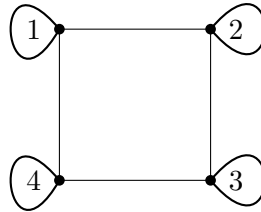


FIGURE 5.4. Multigraph G of Example 5.1.

matching model on G is necessarily stable, that is, for any admissible Φ , we have that $\text{STAB}(G, \Phi) = \mathcal{M}(\mathcal{V})$. Let us focus on the FCFM policy. The set of admissible queue details is given by $\mathbb{W} = \{\varepsilon, 1, 2, 3, 4, 13, 24, 31, 42\}$, and as a consequence of Remark 4.6, we can compute explicitly Π_W , obtaining the following values:

$$\left\{ \begin{array}{ll} \Pi_W(\varepsilon) = \alpha & \Pi_W(2) = \alpha \frac{\mu(2)}{1-\mu(4)} \\ \Pi_W(1) = \alpha \frac{\mu(1)}{1-\mu(3)} & \Pi_W(4) = \alpha \frac{\mu(4)}{1-\mu(2)} \\ \Pi_W(3) = \alpha \frac{\mu(3)}{1-\mu(1)} & \Pi_W(24) = \alpha \frac{\mu(2)}{1-\mu(4)} \mu(4) \\ \Pi_W(13) = \alpha \frac{\mu(1)}{1-\mu(3)} \mu(3) & \Pi_W(42) = \alpha \frac{\mu(4)}{1-\mu(2)} \mu(2), \\ \Pi_W(31) = \alpha \frac{\mu(3)}{1-\mu(1)} \mu(1) & \end{array} \right.$$

with

$$\alpha = \left[1 + \mu(1) \frac{1 + \mu(3)}{1 - \mu(3)} + \mu(2) \frac{1 + \mu(4)}{1 - \mu(4)} + \mu(3) \frac{1 + \mu(1)}{1 - \mu(1)} + \mu(4) \frac{1 + \mu(2)}{1 - \mu(2)} \right]^{-1},$$

using the fact that $\mathbb{I}(\check{G}) = \{\{1\}, \{2\}, \{3\}, \{4\}, \{1, 3\}, \{2, 4\}\}$.

Example 5.2. Consider the multigraph G (at the middle) of Figure 2.2. From Theorems 4.5 and 4.7, both the stability region $\text{STAB}(G, \text{FCFM})$ under First Come, First Matched, and the stability region $\text{STAB}(G, \text{MW})$ under any Max-Weight policy, coincide with the set

$$\text{NCOND}(G) = \left\{ \mu \in \mathcal{M}(\mathcal{V}) : \mu(1) < \mu(2), \mu(\{1, 3\}) \vee \mu(\{1, 4\}) < \frac{1}{2} \right\}.$$

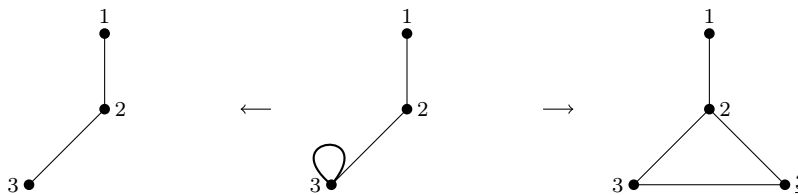


FIGURE 5.5. A multigraph on the complete 2-partite graph of size 3 (left), and its minimal blow-up graph (right).

Example 5.3. Consider now the multigraph G of Figure 5.5, whose maximal subgraph is a complete 2-partite graph of order 3 (i.e., a string of 3 nodes). We easily obtain that

$$\begin{aligned} \text{NCOND}(G) &= \left\{ \mu \in \mathcal{M}(\mathcal{V}) : \mu(1) < \mu(2) < \frac{1}{2} \right\}, \\ \text{NCOND}(\hat{G}) &= \left\{ \mu \in \mathcal{M}(\hat{\mathcal{V}}) : \mu(1) < \mu(2), \mu(2) \vee \mu(\{1, 3\}) \vee \mu(\{1, \bar{3}\}) < \frac{1}{2} \right\}. \end{aligned}$$

In view of Theorems 4.5 and 4.7, the respective stability regions $\text{STAB}(G, \text{FCFM})$ and $\text{STAB}(G, \text{MW})$ under First Come, First Matched, or any Max-Weight policy, coincide with $\text{NCOND}(G)$.

Let us first focus on the FCFM policy. The set of admissible queue details is given by

$$\mathbb{W} = \{\varepsilon\} \cup \{1^k : k \geq 1\} \cup \{2^k : k \geq 1\} \cup \{1^r 31^{k-r} : k \geq 0, 0 \leq r \leq k\}.$$

By Theorem 4.5, we have that

$$\begin{cases} \Pi_W(\varepsilon) = \alpha \\ \Pi_W(1^k) = \alpha \left(\frac{\mu(1)}{\mu(2)}\right)^k & \Pi_W(2^k) = \alpha \left(\frac{\mu(2)}{1-\mu(2)}\right)^k \\ \Pi_W(1^r 31^{k-r}) = \alpha \left(\frac{\mu(1)}{\mu(2)}\right)^r \times \frac{\mu(3)}{1-\mu(1)} \times \left(\frac{\mu(1)}{1-\mu(1)}\right)^{k-r}, \end{cases}$$

and since $\mathbb{I}(\hat{G}) = \{\{1\}, \{2\}, \{3\}, \{1, 3\}\}$, we can express α as follows,

$$\begin{aligned} \alpha = \left[1 + \frac{\mu(1)}{\mu(2) - \mu(1)} + \frac{\mu(2)}{1 - 2\mu(2)} + \frac{\mu(3)}{1 - \mu(1)} \right. \\ \left. + \frac{\mu(1)}{\mu(2) - \mu(1)} \frac{\mu(3)}{1 - 2\mu(1)} + \frac{\mu(3)}{1 - \mu(1)} \frac{\mu(1)}{1 - 2\mu(1)} \right]^{-1}. \end{aligned}$$

Second, consider a matching policy $\hat{\Phi}$ such that a 2-item always prioritizes a 1-item over a 3 or a $\bar{3}$ -item. Then $\hat{\Phi}$ extends a \mathcal{V}_2 -favorable policy Φ on \hat{G} . Thus, from Proposition 4.12(i), the stability region of the system is $\text{NCOND}(\hat{G})$, in other words $\hat{\Phi}$ is maximal on \hat{G} . We thereby generalize with a very simple proof, the result of Lemma 3 of Mairesse and Moyal (2016) to the case where $\mu(3) \neq \mu(\bar{3})$. Last, in view of Theorem 4.9(i), any \mathcal{V}_2 -favorable matching policy Φ on G (i.e., such that 2 prioritizes 1 over 3) is maximal, that is, the two sets $\text{STAB}(G, \Phi)$ and $\text{NCOND}(G)$ coincide.

Example 5.4. Last, consider the multigraph G represented in (the middle figure of) Figure 4.3. The maximal subgraph is 3-partite complete, and we readily obtain that

$$\begin{aligned} \text{NCOND}(\check{G}) &= \left\{ \mu \in \mathcal{M}(\mathcal{V}) : \mu(1) \vee \mu(\{2, 4\}) \vee \mu(\{3, 5\}) < \frac{1}{2} \right\}; \\ \text{NCOND}(G) &= \left\{ \mu \in \mathcal{M}(\mathcal{V}) : \mu(1) \vee \mu(\{2, 4\}) < \frac{1}{2}, \mu(3) < \mu(\{1, 2, 4\}) \right\}; \\ \text{NCOND}(\hat{G}) &= \left\{ \mu \in \mathcal{M}(\mathcal{V}) : \mu(1) \vee \mu(\{2, 4\}) \vee \mu(\{3, 5\}) \vee \mu(\{3, \bar{5}\}) < \frac{1}{2} \right\}. \end{aligned}$$

Then, from Theorems 4.5 and 4.7, the respective stability regions $\text{STAB}(G, \text{FCFM})$ and $\text{STAB}(G, \text{MW})$ under First Come, First Matched, or any Max-Weight policy coincide with the set $\text{NCOND}(G)$. From Theorem 4.9(i), for any policy Φ on G according to which all items prioritize 3-items over 5 items is maximal, i.e. $\text{STAB}(G, \Phi) = \text{NCOND}(G)$. From Theorem 4.9(ii), any policy Φ on G is such that $\text{NCOND}(\check{G}) \subset \text{STAB}(G, \Phi)$. Last, from Proposition 4.12, any policy $\hat{\Phi}$ on \hat{G} giving priority to 3-items over 5 and $\bar{5}$ -items is maximal, whereas for any matching policy $\hat{\Phi}$ and any measure $\hat{\mu}$ on $\hat{\mathcal{V}}$ extending a measure of $\text{NCOND}(\check{G})$, the model $(\hat{G}, \hat{\Phi}, \hat{\mu})$ is stable.

6. Proof of Proposition 4.2

The proof of the fact that $\text{NCOND}(G) = \emptyset$ whenever G is a bipartite graph was given in Theorem 1 of Mairesse and Moyal (2016). We reproduce it hereafter for easy reference: Let us assume that G is a connected bipartite graph, and let (A, B) be a bipartition of \mathcal{V} such that if $i-j$, then $(i, j) \in (A \times B) \cup (B \times A)$. Then, $A, B \in \mathbb{I}(G)$, and $\mathcal{E}(A) = B, \mathcal{E}(B) = A$. So, for any measure $\mu \in \mathcal{M}(\mathcal{V})$, we have either $\mu(A) \geq \mu(\mathcal{E}(A))$ or $\mu(B) \geq \mu(\mathcal{E}(B))$, meaning that $\text{NCOND}(G) = \emptyset$.

In order to prove the converse statement, we show that if G is a connected multigraph such that $\mu_{\text{deg}} \notin \text{NCOND}(G)$, then G is a bipartite graph.

For a subset A of \mathcal{V} , let us denote by $\mathcal{S}(A)$ the set of edges having at least one extremity in A , where we identify the edges (i, j) and (j, i) , and where we include self-loops. Formally,

$$\mathcal{S}(A) \triangleq \{ \{i, j\} \subset \mathcal{V} : i \neq j, i-j \text{ and } \{i, j\} \cap A \neq \emptyset \} \cup \{ (i, i) : i \in \mathcal{V}_1 \cap A \}.$$

Observe that we have the following properties.

- (1) For any $A \subset \mathcal{V}$, $\mathcal{S}(A) \subset \mathcal{S}(\mathcal{E}(A))$.
- (2) For any $A \subset \mathcal{V}$, $\sum_{i \in A} \deg(i) \geq \text{Card } \mathcal{S}(A)$, so that $\mu_{\text{deg}}(A) \geq \frac{1}{|\mathcal{E}|} \text{Card } \mathcal{S}(A)$, with equality if $A \in \mathbb{I}(G)$.

Let us assume that $\mu_{\text{deg}} \notin \text{NCOND}(G)$, meaning that there exists $\mathcal{I} \in \mathbb{I}(G)$ with $\mu_{\text{deg}}(\mathcal{I}) \geq \mu_{\text{deg}}(\mathcal{E}(\mathcal{I}))$. By the property (2) above, we have $\mu_{\text{deg}}(\mathcal{I}) = \frac{1}{|\mathcal{E}|} \text{Card } \mathcal{S}(\mathcal{I})$ and $\mu_{\text{deg}}(\mathcal{E}(\mathcal{I})) \geq \frac{1}{|\mathcal{E}|} \text{Card } \mathcal{S}(\mathcal{E}(\mathcal{I}))$, so that $\text{Card } \mathcal{S}(\mathcal{I}) \geq \text{Card } \mathcal{S}(\mathcal{E}(\mathcal{I}))$. But by property (1), $\mathcal{S}(\mathcal{I}) \subset \mathcal{S}(\mathcal{E}(\mathcal{I}))$, which implies that $\mathcal{S}(\mathcal{I}) = \mathcal{S}(\mathcal{E}(\mathcal{I}))$.

Let us prove that $(\mathcal{I}, \mathcal{E}(\mathcal{I}))$ is a bipartition of \mathcal{V} such that if $i-j$, then $(i, j) \in (\mathcal{I} \times \mathcal{E}(\mathcal{I})) \cup (\mathcal{E}(\mathcal{I}) \times \mathcal{I})$.

- Since $\mathcal{I} \in \mathbb{I}(G)$, $\mathcal{I} \cap \mathcal{E}(\mathcal{I}) = \emptyset$.
- Using that $\mathcal{S}(\mathcal{I}) = \mathcal{S}(\mathcal{E}(\mathcal{I}))$, we deduce that $\mathcal{E}(\mathcal{E}(\mathcal{I})) = \mathcal{I}$. So, the vertices reachable from \mathcal{I} all belong to $\mathcal{I} \cup \mathcal{E}(\mathcal{I})$. The multigraph G being connected, this implies that $\mathcal{I} \cup \mathcal{E}(\mathcal{I}) = \mathcal{V}$.
- Since $\mathcal{I} \in \mathbb{I}(G)$, there is no edge between vertices of \mathcal{I} . Furthermore, since $\mathcal{S}(\mathcal{I}) = \mathcal{S}(\mathcal{E}(\mathcal{I}))$, there is no edge between vertices of $\mathcal{E}(\mathcal{I})$.

Consequently, G is a bipartite graph, which ends the proof.

7. Proof of Theorem 4.5

Let us recall that the multigraph $G = (\mathcal{V}, \mathcal{E})$ is connected but is not a bipartite graph, with $|\mathcal{V}| \geq 2$. Then, in particular, $\text{NCOND}(G) \neq \emptyset$ (cf. Proposition 4.2). Our product form result, Theorem 4.5, follows from a reversibility scheme that generalizes to the case of multigraphs, the one constructed in Moyal et al. (2021). In fact, we propose a proof that is simpler, at some points, than the one in Moyal et al. (2021). We reproduce hereafter the main steps of this construction for easy reference, and only develop exhaustively the points that are specific to the present context, or based on different arguments.

Hereafter, we denote by \mathbb{P}_W , the transition operator of the buffer-content Markov chain, that is, for all $w, w' \in \mathbb{W}$, we write $\mathbb{P}_W(w, w') = \mathbb{P}[W_{n+1} = w' \mid W_n = w]$, for any $n \in \mathbb{N}$.

7.1. *Two auxiliary chains.* As in section 3.2 of Moyal et al. (2021), we first need to define two auxiliary Markov chains. For this, let us denote by $\bar{\mathcal{V}}$ an independent copy of \mathcal{V} , i.e. a set with the same cardinal formed with copies of elements of \mathcal{V} . We set $\mathbf{V} \triangleq \mathcal{V} \cup \bar{\mathcal{V}}$, and we define, for $\mathbf{w} \in \mathbf{V}^*$,

$$\begin{aligned} \mathcal{V}(\mathbf{w}) &\triangleq \{a \in \mathcal{V} : |\mathbf{w}|_a > 0\}, \\ \bar{\mathcal{V}}(\mathbf{w}) &\triangleq \{\bar{a} \in \bar{\mathcal{V}} : |\mathbf{w}|_{\bar{a}} > 0\}. \end{aligned}$$

For $a \in \mathbf{V}$, we will use the notation $\bar{\bar{a}} = a$.

Definition 7.1. We define the *backward detailed chain* as the process $(B_n)_{n \in \mathbb{N}}$ with values in \mathbf{V}^* given by $B_0 = \varepsilon$ and, for any $n \geq 1$,

- if $W_n = \varepsilon$ (i.e. all the items arrived up to time n are matched at time n), then $B_n = \varepsilon$,
- otherwise, let $i(n) \in \llbracket 1, n \rrbracket$ be the arrival time of the oldest item still in the buffer, then, the word B_n is the word of length $n - i(n) + 1$, defined, for any $\ell \in \llbracket 1, n - i(n) + 1 \rrbracket$, by

$$(B_n)_\ell = \begin{cases} V_{i(n)+\ell-1} & \text{if } V_{i(n)+\ell-1} \text{ has not been matched up to time } n; \\ \bar{V}_k & \text{if } V_{i(n)+\ell-1} \text{ is matched at or before time } n, \text{ with item } V_k \\ & \text{(where } 1 \leq k \leq n). \end{cases}$$

In other words, the word B_n gathers the class indexes of all unmatched items entered up to n , at the places corresponding to their arrival times, and the copies of the class indexes of the items matched before n , but after the arrival of the oldest unmatched item at n , at the place corresponding to the arrival time of their respective match.

Observe that by the construction of $(B_n)_{n \in \mathbb{N}}$, for all $n \in \mathbb{N}$, the word B_n necessarily contains all the letters of W_n . More precisely, for any $n \in \mathbb{N}$, W_n is the restriction of the word B_n to its letters in \mathcal{V} . Furthermore, $(B_n)_{n \in \mathbb{N}}$ is also a Markov chain since for any $n \geq 0$, the value of B_{n+1} can be deduced from that of B_n and from the class V_{n+1} of the item entered at time $n + 1$.

A state $\mathbf{w} \in \mathbf{V}^*$ is said to be *admissible for* $(B_n)_{n \in \mathbb{N}}$ if it can be reached by the chain $(B_n)_{n \in \mathbb{N}}$, under the FCFM policy. We set

$$\mathbb{B} \triangleq \{\mathbf{w} \in \mathbf{V}^* : \mathbf{w} \text{ is admissible for } (B_n)_{n \in \mathbb{N}}\}.$$

The following result can be proven exactly as Lemma 1 in Moyal et al. (2021).

Lemma 7.2. *Let $\mathbf{w} = \mathbf{w}_1 \dots \mathbf{w}_q \in \mathbf{V}^*$. Then, $\mathbf{w} \in \mathbb{B}$ if and only if $\mathbf{w}_1 \in \mathcal{V}$ and for $1 \leq i < j \leq q$,*

- *if $(\mathbf{w}_i, \mathbf{w}_j) \in \mathcal{V}^2$, then $\mathbf{w}_i \neq \mathbf{w}_j$,*
- *if $(\mathbf{w}_i, \mathbf{w}_j) \in \mathcal{V} \times \bar{\mathcal{V}}$, then $\mathbf{w}_i \neq \bar{\mathbf{w}}_j$.*

As a consequence of Lemma 7.2, any word $\mathbf{w} \in \mathbb{B}$ can be written as

$$\mathbf{w} = b_1 \overline{a_{11} a_{12}} \dots \overline{a_{1k_1}} b_2 \overline{a_{21} a_{22}} \dots \overline{a_{2k_2}} b_3 \dots b_q \overline{a_{q1}} \dots \overline{a_{qk_q}},$$

where $q, k_1, \dots, k_q \in \mathbb{N}$, $b_1, \dots, b_q \in \mathcal{V}$, $a_{ij} \in \mathcal{V}$ for $1 \leq i \leq q, 1 \leq j \leq k_i$, and

$$\begin{cases} \{b_1, \dots, b_q\} = \mathcal{V}(\mathbf{w}) \in \mathbb{I}(\check{G}), \\ \forall i \in \llbracket 1, q \rrbracket, b_i \in \mathcal{V}_1 \Rightarrow [\forall j \neq i, b_i \neq b_j], \\ \forall i \in \llbracket 1, q \rrbracket, \forall j \in \llbracket 1, k_i \rrbracket, a_{ij} \in \mathcal{E}(\{b_1, \dots, b_i\})^c. \end{cases}$$

The transition operator of the chain $\{B_n\}_{n \in \mathbb{N}}$ is denoted by \mathbb{P}_B , that is, for all $\mathbf{w}, \mathbf{w}' \in \mathbb{B}$, we write $\mathbb{P}_B(\mathbf{w}, \mathbf{w}') = \mathbb{P}[B_{n+1} = \mathbf{w}' \mid B_n = \mathbf{w}]$, for all $n \in \mathbb{N}$.

Definition 7.3. We define the *forward detailed chain* as the process $(F_n)_{n \in \mathbb{N}}$ with values in \mathbf{V}^* given by $F_0 = \varepsilon$ (the empty word) and, for any $n \geq 1$,

- if $W_n = \varepsilon$ (i.e. all the items arrived up to time n are matched at time n), then $F_n = \varepsilon$,
- otherwise, let \mathcal{U}_n be the set of items arrived before time n that are not matched at time n (note that \mathcal{U}_n is non-empty, since $W_n \neq \varepsilon$). Also, set

$$j(n) \triangleq \sup \{m \geq n + 1 : V_m \text{ is matched with an element of } \mathcal{U}_n\}.$$

Observe that $j(n)$ is possibly infinite. Then, if $j(n)$ is finite, F_n is the word of \mathbf{V}^* of length $j(n) - n$ (respectively of $A^{\mathbb{N}}$ of length $+\infty$, if $j(n) = +\infty$), such that for any $\ell \in \llbracket 1, j(n) - n \rrbracket$ (respectively $\ell \in \mathbb{N}_+$),

$$(F_n)_\ell = \begin{cases} V_{n+\ell} & \text{if } V_{n+\ell} \text{ is not matched with an item arrived up to } n; \\ \overline{V}_k & \text{if } V_{n+\ell} \text{ is matched with item } V_k, \text{ where } 1 \leq k \leq n. \end{cases}$$

In other words, the word F_n contains the copies of all the class indexes of the items entered up to time n and matched after n , at the place corresponding to the arrival time of their respective match, together with the class indexes of all items entered after n and before the last item matched with an item entered up to n , and not matched with an element entered before n , if any, at the place corresponding to their arrival time. Similarly to [Moyat et al. \(2021\)](#), we make the three following simple observations:

- If $F_n \in \mathbf{V}^*$ is finite, then $(F_n)_{j(n)-n} \in \overline{\mathcal{V}}$;
- $\{F_n\}_{n \in \mathbb{N}}$ is a Markov chain;
- If F_n is a.s. an element of \mathbf{V}^* for all $n \in \mathbb{N}$.

As for the backward chain, we say that a state $\mathbf{w} \in \mathbf{V}^*$ is *admissible for* $(F_n)_{n \in \mathbb{N}}$ if it can be reached by the chain $(F_n)_{n \in \mathbb{N}}$, under the FCFM policy. Then, we set

$$\mathbb{F} \triangleq \{\mathbf{w} \in \mathbf{V}^* : \mathbf{w} \text{ is admissible for } \{F_n\}_{n \in \mathbb{N}}\}$$

and we denote by \mathbb{P}_F the transition operator of the chain $\{F_n\}_{n \in \mathbb{N}}$ on \mathbb{F} . For any word $\mathbf{w} = \mathbf{w}_1 \dots \mathbf{w}_n \in \mathbf{V}^*$, let us define its reversed-copy by $\overleftarrow{\mathbf{w}} \triangleq \overline{\mathbf{w}_n} \dots \overline{\mathbf{w}_1} \in \mathbf{V}^*$. Note that the map $\Psi : \mathbf{V}^* \rightarrow \mathbf{V}^*, \mathbf{w} \mapsto \overleftarrow{\mathbf{w}}$ satisfies $\Psi \circ \Psi = Id_{\mathbf{V}^*}$. Thus, Ψ is a bijection and its inverse function is $\Psi^{-1} = \Psi$.

Lemma 7.4. *The map*

$$\Psi_{\mathbb{B}} : \begin{cases} \mathbb{B} \longrightarrow \mathbb{F} \\ \mathbf{w} \longmapsto \Psi(\mathbf{w}) = \overleftarrow{\mathbf{w}} \end{cases}$$

is well-defined and bijective.

Proof: Exactly as in Lemma 2 in [Moyat et al. \(2021\)](#), it can be proven that $\mathbf{w} \in \mathbb{F}$ if and only if $\Psi(\mathbf{w}) \in \mathbb{B}$. This guarantees that the mapping $\Psi_{\mathbb{B}}$ is well-defined and surjective. It is injective because Ψ clearly is so. \square

Let us define a measure ν on \mathbf{V}^* by $\nu(\varepsilon) \triangleq 1$ and

$$\forall \mathbf{w} \in \mathbf{V}^* \setminus \{\varepsilon\}, \nu(\mathbf{w}) \triangleq \prod_{i=1}^{|\mathcal{V}|} \mu(i)^{|\mathbf{w}|_i + |\overline{\mathbf{w}}|_i}. \tag{7.1}$$

We can use the measure ν defined above to establish the following link between the dynamics of the chains $(B_n)_{n \in \mathbb{N}}$ and $(F_n)_{n \in \mathbb{N}}$. The following result can be established exactly as Lemma 3 in [Moyal et al. \(2021\)](#),

Proposition 7.5. *For any $(\mathbf{w}, \mathbf{w}') \in \mathbb{B}^2$, we have that*

$$\nu(\mathbf{w})\mathbb{P}_B(\mathbf{w}, \mathbf{w}') = \nu\left(\overleftarrow{\mathbf{w}'}\right)\mathbb{P}_F\left(\overleftarrow{\mathbf{w}'}, \overleftarrow{\mathbf{w}}\right).$$

7.2. Positive recurrence of $(B_n)_{n \in \mathbb{N}}$ and $(F_n)_{n \in \mathbb{N}}$. We will exploit the local balance equations of Proposition 7.5 to derive stationary distributions of these two Markov chains. To this end, the following technical lemma will simplify the proofs.

Lemma 7.6. *The measure ν defined by (7.1) satisfies the following properties:*

- (1) *For any $\mathcal{A} \subset \mathbf{V} = \mathcal{V} \cup \overline{\mathcal{V}}$, we have $\nu(\mathcal{A}) = \mu(\mathcal{V}(\mathcal{A})) + \mu(\overline{\mathcal{V}(\mathcal{A})})$.*
- (2) *For any $\mathcal{A}_1, \dots, \mathcal{A}_n \subset \mathbf{V}$, $\nu(\mathcal{A}_1 \dots \mathcal{A}_n) = \nu(\mathcal{A}_1) \dots \nu(\mathcal{A}_n)$. In particular, $\nu(\mathcal{A}^k) = \nu(\mathcal{A})^k$.*
- (3) *If $\mathcal{A} \subset \mathbf{V}$ is such that $\nu(\mathcal{A}) < 1$, then $\nu(\mathcal{A}^*) = \frac{1}{1-\nu(\mathcal{A})}$.*

Proof: The first point follows from the definition of ν and the second point is a direct consequence of its multiplicative structure. Regarding the third point, observe that $\mathcal{A}^* = \cup_{k \in \mathbb{N}} \mathcal{A}^k$, so that

$$\nu(\mathcal{A}^*) = \sum_{k \in \mathbb{N}} \nu(\mathcal{A}^k) = \sum_{k \in \mathbb{N}} \nu(\mathcal{A})^k.$$

□

We can now state the following result,

Proposition 7.7. *Suppose that $\mu \in \text{NCOND}(G)$. Then, the chains $(B_n)_{n \in \mathbb{N}}$ and $(F_n)_{n \in \mathbb{N}}$ are positively recurrent and admit respectively the restrictions on \mathbb{B} and on \mathbb{F} of ν (that is, $\nu_B(\mathbf{w}) = \nu_F(\Psi_{\mathbb{B}}(\mathbf{w})) = \nu(\mathbf{w})$, for any $\mathbf{w} \in \mathbb{B}$) as unique stationary measure (up to a multiplicative constant), respectively on \mathbb{B} and \mathbb{F} .*

Proof: Let $\mu \in \text{NCOND}(G)$.

Step 1: we first prove that ν_B is a stationary measure for the chain $(B_n)_{n \in \mathbb{N}}$.

For this, let us fix $\mathbf{w}' \in \mathbb{B}$. Then we have that

$$\begin{aligned} \sum_{\mathbf{w} \in \mathbb{B}} \frac{\mathbb{P}_B(\mathbf{w}, \mathbf{w}')\nu_B(\mathbf{w})}{\nu_B(\mathbf{w}')} &= \sum_{\mathbf{w} \in \mathbb{B}} \frac{\mathbb{P}_F\left(\overleftarrow{\mathbf{w}'}, \overleftarrow{\mathbf{w}}\right)\nu_B\left(\overleftarrow{\mathbf{w}'}\right)}{\nu_B(\mathbf{w}')} \\ &= \sum_{\mathbf{w} \in \mathbb{B}} \mathbb{P}_F\left(\overleftarrow{\mathbf{w}'}, \overleftarrow{\mathbf{w}}\right) = 1, \end{aligned}$$

where the first equality follows from Proposition 7.5, the second from the fact that $\nu_B\left(\overleftarrow{\mathbf{w}'}\right) = \nu_B(\mathbf{w}')$ and the last, from Lemma 7.4. Thus, for all $\mathbf{w}' \in \mathbb{B}$, we have that

$$\nu_B(\mathbf{w}') = \sum_{\mathbf{w} \in \mathbb{B}} \mathbb{P}_B(\mathbf{w}, \mathbf{w}')\nu_B(\mathbf{w}),$$

which means exactly that ν_B is a stationary measure for the chain $(B_n)_{n \in \mathbb{N}}$.

Step 2: we now prove that $\nu_B(\mathbb{B}) < \infty$.

By Lemma 7.2, we know that $\mathbf{w} \in \mathbb{B} \setminus \{\varepsilon\}$ if and only if \mathbf{w} belongs to a set

$$b_1 \mathcal{A}_1^* b_2 \mathcal{A}_2^* \dots b_q \mathcal{A}_q^* \triangleq \{w \in \mathbf{V}^* : w = b_1 w^1 b_2 w^2 \dots b_q w^q; w^i \in \mathcal{A}_i^*, \text{ for all } i \in \llbracket 1, q \rrbracket\}, \quad q \geq 1, \quad (7.2)$$

where b_1, \dots, b_q are elements of \mathcal{V} such that $\{b_1, \dots, b_q\} \in \mathbb{I}(\check{G})$ and such that for all distinct i, j in $\llbracket 1, q \rrbracket$, $b_i \in \mathcal{V}_1$ implies that $b_i \neq b_j$, and where we denote

$$\mathcal{A}_i \triangleq \overline{\mathcal{E}(\{b_1, \dots, b_i\})^c}, \quad i \in \llbracket 1, q \rrbracket.$$

Equivalently, by highlighting only the first occurrence of each letter of \mathcal{V} appearing in \mathbf{w} and employing a similar notation to (7.2) we obtain that $\mathbf{w} \in \mathbb{B} \setminus \{\varepsilon\}$ if and only if \mathbf{w} belongs to some sets of the form

$$\mathcal{C}_{\mathcal{I}, \sigma} \triangleq e_{\sigma(1)} \mathcal{B}_{\sigma(1)}^* e_{\sigma(2)} \mathcal{B}_{\sigma(2)}^* \dots e_{\sigma(|\mathcal{I}|)} \mathcal{B}_{\sigma(|\mathcal{I}|)}^*,$$

where $\mathcal{I} = \{e_1, \dots, e_{|\mathcal{I}|}\} \in \mathbb{I}(\check{G})$, $\sigma \in \mathfrak{S}_{|\mathcal{I}|}$, and where we denote

$$\mathcal{B}_{\sigma(i)} \triangleq \overline{\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})^c} \cup (\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2), \quad i \in \llbracket 1, |\mathcal{I}| \rrbracket.$$

In view of assertion (1) of Lemma 7.6, we have that for all $i \in \llbracket 1, k \rrbracket$,

$$\begin{aligned} \nu_B(\mathcal{B}_{\sigma(i)}) &= \mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})^c) + \mu(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2) \\ &= 1 - \mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})) + \mu(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2). \end{aligned}$$

Since $\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \in \mathbb{I}(\check{G})$, we have, by definition, that $\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2 \in \mathbb{I}(G)$ and since the measure μ satisfies $\text{NCOND}(G)$, it follows that

$$\begin{aligned} \mu(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2) &< \mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2)) \\ &\leq \mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})) \end{aligned}$$

and thereby, that $\nu_B(\mathcal{B}_{\sigma(i)}) < 1$. As a conclusion, applying successively all assertions of Lemma 7.6, we obtain that for all such \mathcal{I} and σ ,

$$\nu_B(\mathcal{C}_{\mathcal{I}, \sigma}) = \prod_{i=1}^{|\mathcal{I}|} \frac{\mu(e_{\sigma(i)})}{\mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})) - \mu(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2)}.$$

The set \mathbb{B} is the disjoint union of the sets $\mathcal{C}_{\mathcal{I}, \sigma}$, for \mathcal{I} in the finite set $\mathbb{I}(\check{G})$, and σ in the finite set $\mathfrak{S}_{|\mathcal{I}|}$. It follows that $\nu_B(\mathbb{B})$ is finite and given by

$$\begin{aligned} \nu_B(\mathbb{B}) &= \nu_B(\varepsilon) + \sum_{\mathcal{I} \in \mathbb{I}(\check{G})} \sum_{\sigma \in \mathfrak{S}_{|\mathcal{I}|}} \nu_B(\mathcal{C}_{\mathcal{I}, \sigma}) \\ &= 1 + \sum_{\mathcal{I} \in \mathbb{I}(\check{G})} \sum_{\sigma \in \mathfrak{S}_{|\mathcal{I}|}} \prod_{i=1}^{|\mathcal{I}|} \frac{\mu(e_{\sigma(i)})}{\mu(\mathcal{E}(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\})) - \mu(\{e_{\sigma(1)}, \dots, e_{\sigma(i)}\} \cap \mathcal{V}_2)}. \end{aligned} \quad (7.3)$$

Step 3: we conclude with the positive recurrence of the two chains.

By the results above, the chain $(B_n)_{n \in \mathbb{N}}$ has a stationary probability distribution on \mathbb{B} , which is given by the measure ν_B normalized by $\nu_B(\mathbb{B})$.

Observe that the chain is irreducible on \mathbb{B} . To see this, let $\mathbf{w} \in \mathbb{B}$ and first observe that the empty word ε leads to \mathbf{w} with positive probability for the transitions of $\{B_n\}_{n \in \mathbb{N}}$ (this is the constructive argument proving Lemma 7.2 - see the proof of Lemma 1 in Moyat et al. (2021)). Conversely, denoting by b_1, \dots, b_q the elements of $\mathcal{V}(\mathbf{w})$, it is easy to see that the word \mathbf{w} leads to the empty word with positive probability for the transitions of $\{B_n\}_{n \in \mathbb{N}}$: indeed, by the definition of the policy FCFM, if the chain is in the state \mathbf{w} , then it will reach the empty state after exactly q steps,

by seeing the successive arrivals of q elements of respective classes in $\mathcal{E}(b_1), \mathcal{E}(b_2), \dots, \mathcal{E}(b_q)$, which concludes the proof of irreducibility.

It then follows that the chain $\{B_n\}_{n \in \mathbb{N}}$ is positively recurrent on \mathbb{B} and that its stationary probability distribution is unique. Consequently, ν_B is the unique stationary measure (up to a multiplicative constant) of the chain $(B_n)_{n \in \mathbb{N}}$.

Now, as in step 1, we obtain that for all $\mathbf{w}' \in \mathbb{B}$,

$$\nu_F(\Psi_{\mathbb{B}}(\mathbf{w}')) = \sum_{\mathbf{w} \in \mathbb{B}} \mathbb{P}_F(\Psi_{\mathbb{B}}(\mathbf{w}), \Psi_{\mathbb{B}}(\mathbf{w}')) \nu_F(\Psi_{\mathbb{B}}(\mathbf{w})).$$

Using Lemma 7.4, we deduce that ν_F is a stationary measure for the chain $(F_n)_{n \in \mathbb{N}}$. Then, step 2 shows equivalently that $\nu_F(\mathbb{F}) < \infty$. So, the chain $(F_n)_{n \in \mathbb{N}}$ has a stationary probability distribution on \mathbb{F} , which is given by the measure ν_F normalized by $\nu_F(\mathbb{F})$.

Similarly as above, we can check that the chain $\{F_n\}_{n \in \mathbb{N}}$ is irreducible on \mathbb{F} . First, the empty word leads with positive probability to any element $\mathbf{w} \in \mathbb{F}$, as can be checked using the same constructive argument as in the proof of Lemma 2. Conversely, suppose that the chain $\{F_n\}_{n \in \mathbb{N}}$ is at time n in a state

$$\mathbf{w} = a_{qk_q} \dots a_{q1} \bar{a}_q \dots \bar{a}_3 a_{2k_2} \dots a_{21} \bar{a}_2 a_{1k_1} \dots a_{11} \bar{a}_1 \in \mathbb{F}$$

and let $r \triangleq q + \sum_{i=1}^q k_i$ be the length of \mathbf{w} . Then, going forward in time, perform the FCFM-matching of the ‘unmatched’ elements of respective classes in $\mathcal{V}(\mathbf{w})$. Say there remains in the system, at time $n + r$, ℓ unmatched elements denoted c_1, c_2, \dots, c_ℓ in their order of arrivals. Then, the chain can return to the empty state in particular if the first ℓ arrivals after time $n + r$ (excluded) are of respective classes in $\mathcal{E}(c_1), \mathcal{E}(c_2), \dots, \mathcal{E}(c_\ell)$. This concludes the proof of irreducibility.

As a consequence, the chain $\{F_n\}_{n \in \mathbb{N}}$ is positively recurrent on \mathbb{F} and its stationary probability distribution is unique. Consequently, ν_F is the unique stationary measure (up to a multiplicative constant) of the chain $(F_n)_{n \in \mathbb{N}}$, which concludes the proof. \square

7.3. *Positive recurrence of $\{W_n\}_{n \in \mathbb{N}}$.* The Markov chain $(W_n)_{n \in \mathbb{N}}$ can be seen as the projection of the chain $(B_n)_{n \in \mathbb{N}}$ on \mathcal{V}^* . In order to obtain the stationary probability distribution of $(W_n)_{n \in \mathbb{N}}$ from the one of $(B_n)_{n \in \mathbb{N}}$, we will use the following lemma:

Lemma 7.8. *Let \mathbb{P}_Y and $\mathbb{P}_{Y'}$ be the transition matrices of two homogeneous Markov chains $\{Y_n\}_{n \in \mathbb{N}}$ and $\{Y'_n\}_{n \in \mathbb{N}}$ with values in some countable sets S and S' respectively, and consider a map $p : S \rightarrow S'$ satisfying*

$$\forall a', b' \in S', \forall a \in p^{-1}(\{a'\}), \mathbb{P}_Y(a, p^{-1}(\{b'\})) = \mathbb{P}_{Y'}(a', b').$$

Then, if a measure μ is invariant for \mathbb{P}_Y , the measure μ' defined by $\mu'(a') \triangleq \mu(p^{-1}(\{a'\}))$ for all $a' \in S'$, is an invariant measure for $\mathbb{P}_{Y'}$ on S' .

Proof: Let μ be an invariant measure for \mathbb{P}_Y , and let $b' \in S'$. We have

$$\begin{aligned} \sum_{a' \in S'} \mu'(a') \mathbb{P}_{Y'}(a', b') &= \sum_{a' \in S'} \left(\sum_{a \in p^{-1}(\{a'\})} \mu(a) \right) \mathbb{P}_{Y'}(a', b') \\ &= \sum_{a' \in S'} \sum_{a \in p^{-1}(\{a'\})} \mu(a) \mathbb{P}_Y(a, p^{-1}(\{b'\})) \\ &= \sum_{s \in S} \mu(s) \mathbb{P}_Y(s, p^{-1}(\{b'\})) = \mu(p^{-1}(\{b'\})) = \mu'(b'), \end{aligned}$$

meaning that μ' is invariant for $\mathbb{P}_{Y'}$. \square

For $\mu \in \text{NCOND}(G)$, let us denote by Π_B the unique stationary probability law associated to the chain $(B_n)_{n \in \mathbb{N}}$ (cf. Prop. 7.7). It is defined by

$$\forall \mathbf{w} \in \mathbb{B}, \Pi_B(\mathbf{w}) \triangleq \alpha \nu_B(\mathbf{w}),$$

where $\alpha \triangleq (\nu_B(\mathbb{B}))^{-1}$ is given by (4.3) in view of (7.3). Let us now introduce the projection

$$p : \begin{cases} \mathbb{B} & \longrightarrow \mathbb{W} \\ \mathbf{w} & \longmapsto \mathbf{w}|_{\mathcal{V}}, \end{cases}$$

which is well-defined from Lemma 7.2. We have the following result:

Proposition 7.9. *Let $\mu \in \text{NCOND}(G)$. Then, the Markov chain $(W_n)_{n \in \mathbb{N}}$ is positively recurrent, and its unique stationary probability distribution is the measure Π_W defined on \mathbb{W} by:*

$$\forall w \in \mathbb{W}, \Pi_W(w) \triangleq \Pi_B(p^{-1}(w)) = \sum_{\mathbf{w} \in \mathbb{B} : \mathbf{w}|_{\mathcal{V}}=w} \Pi_B(\mathbf{w}).$$

Proof: Let $\mu \in \text{NCOND}(G)$. We can apply Lemma 7.8 to \mathbb{P}_B and \mathbb{P}_W to prove that Π_W is a stationary distribution for $(W_n)_{n \in \mathbb{N}}$. Indeed, using the fact that for any $n \in \mathbb{N}$, W_n is the restriction of the word B_n to its letters in \mathcal{V} , we have that

$$\forall w, w' \in \mathbb{W}, \forall \mathbf{w} \in p^{-1}(\{w\}), \mathbb{P}_B(\mathbf{w}, p^{-1}(\{w'\})) = \mathbb{P}_W(w, w').$$

The measure Π_W is a probability distribution on \mathbb{W} , since $\Pi_W(\mathbb{W}) = \Pi_B(p^{-1}(\mathbb{W})) = \Pi_B(\mathbb{B}) = 1$. The chain $(W_n)_{n \in \mathbb{N}}$ being irreducible on \mathbb{W} , it follows that Π_W is its unique stationary probability distribution. \square

7.4. *Concluding the proof.* We first show that $\text{STAB}(G, \text{FCFM}) = \text{NCOND}(G)$. First, we know from Proposition 4.3 that $\text{STAB}(G, \text{FCFM}) \subset \text{NCOND}(G)$. Also, from Proposition 4.2, $\text{NCOND}(G) \neq \emptyset$, since G is not a bipartite graph. Then, for all $\mu \in \text{NCOND}(G)$, by Proposition 7.9, the chain $(W_n)_{n \in \mathbb{N}}$ is positively recurrent on \mathbb{W} . So, $\text{NCOND}(G) \subset \text{STAB}(G, \text{FCFM})$, and therefore $\text{STAB}(G, \text{FCFM}) = \text{NCOND}(G)$.

We now fix $\mu \in \text{NCOND}(G)$, and compute explicitly the unique stationary probability distribution Π_W of the chain $(W_n)_{n \in \mathbb{N}}$. First, if $w = \varepsilon$, then $p^{-1}(\{w\}) = \varepsilon$ and $\Pi_W(\varepsilon) = \alpha$, given by (4.3). Now, fix $w \neq \varepsilon$ in \mathbb{W} . By (7.2), we know that if $w = w_1 \dots w_q \in \mathbb{W}$, $q \geq 1$, then $p^{-1}(\{w\}) = w_1 \mathcal{A}_1^* w_2 \mathcal{A}_2^* \dots w_q \mathcal{A}_q^*$, with $\mathcal{A}_i = \overline{\mathcal{E}(\{w_1, \dots, w_i\})^c}$, for all $i \in \llbracket 1, q \rrbracket$. Applying Lemma 7.6 and observing that for all i , $\mu(\overline{\mathcal{A}_i}) < 1$ since $\mathcal{A}_i \subsetneq \overline{\mathcal{V}}$, it follows that

$$\begin{aligned} \Pi_W(w) &= \Pi_B(w_1 \mathcal{A}_1^* w_2 \mathcal{A}_2^* \dots w_q \mathcal{A}_q^*) \\ &= \alpha \nu_B(w_1 \mathcal{A}_1^* w_2 \mathcal{A}_2^* \dots w_q \mathcal{A}_q^*) \\ &= \alpha \prod_{i=1}^q \frac{\mu(w_i)}{1 - \mu(\overline{\mathcal{A}_i})} = \alpha \prod_{i=1}^q \frac{\mu(w_i)}{\mu(\mathcal{E}(\{w_1, \dots, w_i\}))}. \end{aligned}$$

The proof is complete.

7.5. *Observation on the sequence of copied letters.* As we will explain below, observe that under the FCFM policy, the i.i.d. sequence of arrivals induces an i.i.d. sequence for the copied letters, with the same distribution on $\overline{\mathcal{V}}$ as on \mathcal{V} . Notice that a similar result was observed for the related construction in Adan et al. (2018a).

Let $\mathbb{M} \subset \mathcal{V}^*$ represent the set of words $z \in \mathcal{V}^* \setminus \{\varepsilon\}$ such that $W^{\text{FCFM}}(z) = \varepsilon$ and $W^{\text{FCFM}}(z') \neq \varepsilon$ for any prefix z' of z . In other words, a word $z \in \mathbb{M}$ represents a sequence of arrivals leading to a first reset to zero of the buffer. The i.i.d. sequence of letters of distribution μ can be uniquely decomposed into an i.i.d. sequence of words of \mathbb{M} of distribution $\mu_{\mathbb{M}}$, where for any $w = w_1 \dots w_q \in \mathbb{M}$,

$\mu_{\mathbb{M}}(w) = \prod_{i=1}^q \mu(w_i)$. Note also that the distribution $\mu_{\mathbb{M}}$ characterizes μ . In particular, if we have an i.i.d. sequence of words of \mathbb{M} of law $\mu_{\mathbb{M}}$, then the sequence of letters out of which the words are made is an i.i.d. sequence of law μ .

Let us denote by $f : \mathbb{M} \rightarrow \mathbb{M}$ the map that, to a word $w = w_1 \dots w_q \in \mathbb{M}$, associates the word $v = v_1 \dots v_q$, where v_i is the class of the item with which w_i is matched. It follows from Prop. 3 of Moyal et al. (2021) that the map f is well-defined and bijective, its inverse function being the function $g : \mathbb{M} \rightarrow \mathbb{M}, w \mapsto \overleftarrow{f(w)}$. Furthermore, by definition of \mathbb{M} , the action of f only consists in permuting letters. The measure $\mu_{\mathbb{M}}$ having a product structure, it follows that f preserves the distribution $\mu_{\mathbb{M}}$: for any $w \in \mathbb{M}, \mu_{\mathbb{M}}(w) = \mu_{\mathbb{M}}(f^{-1}(\{w\}))$. Consequently, if $(W_i)_{i \in \mathbb{N}}$ is an i.i.d. sequence of words distributed according to $\mu_{\mathbb{M}}$, then the sequence $(f(W_i))_{i \in \mathbb{N}}$ is also an i.i.d. sequence of words distributed according to $\mu_{\mathbb{M}}$, meaning that the sequence of letters out of which the words $f(W_i)$ are made is an i.i.d. sequence of law μ .

Thus, replacing each arrival by the class of the item with which it is matched preserves the measure $\mu^{\otimes \mathbb{N}}$.

8. Remaining proofs

Throughout the section, G is a connected multigraph, \check{G} is its maximal subgraph and \hat{G} denotes its minimal blow-up graph. To simply compare a (G, Φ, μ) system with the two corresponding matching models on graphs $(\hat{G}, \hat{\Phi}, \hat{\mu})$ and $(\check{G}, \check{\Phi}, \mu)$, let us add a ‘‘hat’’ (resp. a ‘‘check’’) to all characteristics of the second (resp. the third) system: in particular, we denote, for all n , by \hat{V}_n (resp. \check{V}_n), the class of the item entering in the $(\hat{G}, \hat{\Phi}, \hat{\mu})$ (resp. $(\check{G}, \check{\Phi}, \mu)$) system at time n . The natural Markov chain of the system is then denoted by $\{\hat{W}_n\}_{n \in \mathbb{N}}$ (resp. $\{\check{W}_n\}_{n \in \mathbb{N}}$) and its state space, by $\hat{\mathbb{W}}$ (resp. $\check{\mathbb{W}}$). Specifically,

$$\begin{aligned} \hat{\mathbb{W}} &= \left\{ w \in (\mathcal{V} \cup \underline{\mathcal{V}}_1)^* : \forall i \neq j \text{ s.t. } (i, j) \in \hat{\mathcal{E}}, |w|_i |w|_j = 0 \right\}; \\ \check{\mathbb{W}} &= \left\{ w \in \mathcal{V}^* : \forall i \neq j \text{ s.t. } (i, j) \in \check{\mathcal{E}}, |w|_i |w|_j = 0 \right\}. \end{aligned}$$

Observe that we have $\mathbb{W} \subset \check{\mathbb{W}} \subset \hat{\mathbb{W}}$.

For any measurable mapping $F : \mathbb{W} \rightarrow \mathbb{R}$ (resp. $\check{\mathbb{W}} \rightarrow \mathbb{R}, \hat{\mathbb{W}} \rightarrow \mathbb{R}$) and any given $w \in \mathbb{W}$ (resp. $\hat{w} \in \hat{\mathbb{W}}, \check{w} \in \check{\mathbb{W}}$), we denote by $\Delta F_{\mu}^{\Phi}(w)$ (resp. $\hat{\Delta} F_{\hat{\mu}}^{\hat{\Phi}}(\hat{w}), \check{\Delta} F_{\mu}^{\check{\Phi}}(\check{w})$) the drift of the chain $\{W_n\}_{n \in \mathbb{N}}$ (resp. $\{\hat{W}_n\}_{n \in \mathbb{N}}, \{\check{W}_n\}_{n \in \mathbb{N}}$) starting from w (resp. \hat{w}, \check{w}) for a (G, Φ, μ) (resp. $(\hat{G}, \hat{\Phi}, \hat{\mu}), (\check{G}, \check{\Phi}, \mu)$) system. In other words, for any $n \in \mathbb{N}$ we denote

$$\begin{aligned} \Delta_{\mu}^{\Phi} F(w) &= \mathbb{E} [F(W_{n+1}) - F(W_n) \mid W_n = w]; \\ \hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} F(\hat{w}) &= \mathbb{E} [F(\hat{W}_{n+1}) - F(\hat{W}_n) \mid \hat{W}_n = \hat{w}]; \\ \check{\Delta}_{\mu}^{\check{\Phi}} F(\check{w}) &= \mathbb{E} [F(\check{W}_{n+1}) - F(\check{W}_n) \mid \check{W}_n = \check{w}]. \end{aligned}$$

8.1. *Drift inequalities.* Consider the following mappings,

$$Q : \begin{cases} \hat{\mathbb{W}} & \longrightarrow \mathbb{R}^+ \\ \hat{w} & \longmapsto \sum_{i=1}^{|\mathcal{V}|} (|\hat{w}|_i)^2 + \sum_{i=1}^{|\mathcal{V}_1|} (|\hat{w}|_{\underline{i}})^2; \end{cases} \tag{8.1}$$

$$L : \begin{cases} \hat{\mathbb{W}} & \longrightarrow \mathbb{R}^+ \\ \hat{w} & \longmapsto \sum_{i=1}^{|\mathcal{V}|} |\hat{w}|_i + \sum_{i=1}^{|\mathcal{V}_1|} |\hat{w}|_i; \end{cases} \tag{8.2}$$

where it follows from the observation above that Q and L are well defined also on \mathbb{W} and $\hat{\mathbb{W}}$.

We have the following result,

Proposition 8.1. *Let Φ be an admissible policy on G and $\mu \in \mathcal{M}(\mathcal{V})$. Let $\hat{\Phi}$ be a matching policy extending Φ on \hat{G} and $\hat{\mu}$ be a measure extending μ on $\hat{\mathcal{V}}$. Then, for all $w \in \mathbb{W}$ we have that $\Delta_\mu^\Phi Q(w) \leq \hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} Q(w)$.*

Proof: Fix $w \in \mathbb{W}$ throughout the proof. Recall that for all $i \in \mathcal{V}_1$ (if any), we have that $|w|_i \in \{0, 1\}$, and let us set

$$\begin{aligned} \mathcal{O}_w &\triangleq \{i \in \mathcal{V}_1 : |w|_i = 1\}, \\ \mathcal{Z}_w &\triangleq \{i \in \mathcal{V}_1 : |w|_i = 0 \text{ and } |w|_j = 0, \text{ for any } j \in \mathcal{E}(i)\}. \end{aligned}$$

First, for any $i \in \mathcal{V}_2$, an incoming item of class i finding a system (G, Φ, μ) in a state w finds the same possible matches (if any) as an incoming item of class i finding the system $(\hat{G}, \hat{\Phi}, \hat{\mu})$ in a state w . Likewise, if a system (G, Φ, μ) is in state w , then, for any $i \in \mathcal{V}_1 \cap (\mathcal{O}_w)^c \cap (\mathcal{Z}_w)^c$, an incoming of class i finds the same possible matches (if any) as an incoming item of class i or of class \underline{i} finding the system $(\hat{G}, \hat{\Phi}, \hat{\mu})$ in the state w . As $\hat{\Phi}$ extends Φ , in all cases the choice of the match (if any) of the incoming item is then the same, or follows the same distribution in case of a draw, in both systems. Therefore, as $\hat{\mu}$ extends μ , for all $n \in \mathbb{N}$ we get that

$$\begin{aligned} &\mathbb{E} [(Q(W_{n+1}) - Q(W_n)) \mathbb{1}_{\{V_{n+1} \in \mathcal{V}_2 \cup \mathcal{V}_1 \cap (\mathcal{O}_w)^c \cap (\mathcal{Z}_w)^c\}} | W_n = w] \\ &= \mathbb{E} \left[\left(Q(\hat{W}_{n+1}) - Q(\hat{W}_n) \right) \mathbb{1}_{\{\hat{V}_{n+1} \in \mathcal{V}_2 \cup (\mathcal{V}_1 \cap (\mathcal{O}_w)^c \cap (\mathcal{Z}_w)^c) \cup (\mathcal{V}_1 \cap (\mathcal{O}_w)^c \cap (\mathcal{Z}_w)^c)\}} | \hat{W}_n = w \right]. \end{aligned} \tag{8.3}$$

Now, if a system (G, Φ, μ) is in state w , then, for any $i \in \mathcal{Z}_w$, and incoming item of class i finds no possible match. All the same, if the system $(\hat{G}, \hat{\Phi}, \hat{\mu})$ is in the state w and the entering item is of class $i \in \mathcal{Z}_w$ or of class $\underline{i} \in \underline{\mathcal{Z}}_w$, then the entering item does not find any possible match in $(\hat{G}, \hat{\Phi}, \hat{\mu})$. In all cases, one coordinate of the Markov chain increases from zero to one, and thus for all $n \in \mathbb{N}$,

$$\begin{aligned} &\mathbb{E} [(Q(W_{n+1}) - Q(W_n)) \mathbb{1}_{\{V_{n+1} \in \mathcal{Z}_w\}} | W_n = w] \\ &= \mu(\mathcal{Z}_w) \\ &= \hat{\mu}(\mathcal{Z}_w) + \hat{\mu}(\underline{\mathcal{Z}}_w) \\ &= \mathbb{E} \left[\left(Q(\hat{W}_{n+1}) - Q(\hat{W}_n) \right) \mathbb{1}_{\{\hat{V}_{n+1} \in \mathcal{Z}_w \cup \underline{\mathcal{Z}}_w\}} | \hat{W}_n = w \right]. \end{aligned} \tag{8.4}$$

Last, if the system (G, Φ, μ) is in the state w , then, the arrival of a class i -item, for $i \in \mathcal{O}_w$, leads to the matching of two items of class i . Therefore, as $|w|_i = 1$ we obtain

$$(Q(W_{n+1}) - Q(W_n)) \mathbb{1}_{\{V_{n+1} \in \mathcal{O}_w\}} = -\mathbb{1}_{\{V_{n+1} \in \mathcal{O}_w\}}. \tag{8.5}$$

Now, suppose that the system $(\hat{G}, \hat{\Phi}, \hat{\mu})$ is in the state $\hat{W}_n = w$. Then, if an item of class $i \in \mathcal{O}_w$ enters in the system, the corresponding item is not matched and the number of i -items in the system

increases from 1 to 2. Therefore we get that

$$\left(Q\left(\hat{W}_{n+1}\right)-Q\left(\hat{W}_n\right)\right) \mathbb{1}_{\left\{\hat{V}_{n+1} \in \mathcal{O}_w\right\}}=3 \mathbb{1}_{\left\{\hat{V}_{n+1} \in \mathcal{O}_w\right\}} . \quad (8.6)$$

If on the other hand, an item of class $i \in \underline{\mathcal{O}}_w$ enters in the same system $(\hat{G}, \hat{\Phi}, \hat{\mu})$, then, the corresponding item match with the stored class i -item and so the coordinate i of the chain decreases to 0. Thus,

$$\left(Q\left(\hat{W}_{n+1}\right)-Q\left(\hat{W}_n\right)\right) \mathbb{1}_{\left\{\hat{V}_{n+1} \in \underline{\mathcal{O}}_w\right\}}=-\mathbb{1}_{\left\{\hat{V}_{n+1} \in \underline{\mathcal{O}}_w\right\}} .$$

Gathering this with (8.5) and (8.6) and then taking expectations, we obtain that

$$\begin{aligned} & \mathbb{E}\left[\left(Q\left(W_{n+1}\right)-Q\left(W_n\right)\right) \mathbb{1}_{\left\{V_{n+1} \in \mathcal{O}_w\right\}} \mid W_n=w\right] \\ & =\mathbb{E}\left[\left(Q\left(\hat{W}_{n+1}\right)-Q\left(\hat{W}_n\right)\right) \mathbb{1}_{\left\{\hat{V}_{n+1} \in \mathcal{O}_w \cup \underline{\mathcal{O}}_w\right\}} \mid \hat{W}_n=w\right]-4 \hat{\mu}\left(\mathcal{O}_w\right) . \end{aligned} \quad (8.7)$$

Finally, (8.3) together with (8.4) and (8.7) give that

$$\Delta_{\mu}^{\Phi} Q(w)=\hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} Q(w)-4 \hat{\mu}\left(\mathcal{O}_w\right), \quad (8.8)$$

which concludes the proof. \square

Definition 8.2. Let G be a connected multigraph and Φ be an admissible matching policy on G . We say that $\check{\Phi}$ reduces Φ if, for any $\mu \in \mathcal{M}(\mathcal{V})$, whenever the two systems $(\check{G}, \check{\Phi}, \mu)$ and (G, Φ, μ) are in the same state $w \in \mathbb{W}$ and welcome the same arrival, then $\check{\Phi}$ and Φ induce the same choice of match, if any.

Proposition 8.3. Let $G=(\mathcal{V}, \mathcal{E})$ be a connected multigraph and Φ be a class admissible policy on G and $\mu \in \mathcal{M}(\mathcal{V})$. Let $\hat{\Phi}$ be a matching policy extending Φ on \hat{G} , $\hat{\mu}$ a measure extending μ on $\hat{\mathcal{V}}$ and $\check{\Phi}$ be a policy that reduces Φ on \check{G} . Then the drift of the respective Markov chains are such that for all $w \in \mathbb{W}$,

$$\Delta_{\mu}^{\Phi} L(w) \leq \hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} L(w) \leq \check{\Delta}_{\check{\mu}}^{\check{\Phi}} L(w) . \quad (8.9)$$

Proof: Fix $w \in \mathbb{X}$. The only case in which the proof of the left inequality of (8.9) differs from that of Proposition 8.1 is when an item of class $i \in \mathcal{O}_w$ enters the $(\hat{G}, \hat{\Phi}, \hat{\mu})$ system in a state w . Then, we now get that for all n ,

$$\left(L\left(\hat{W}_{n+1}\right)-L\left(\hat{W}_n\right)\right) \mathbb{1}_{\left\{\hat{V}_{n+1} \in \mathcal{O}_w\right\}}=\sum_{i \in \mathcal{O}_w} \mathbb{1}_{\left\{\hat{V}_{n+1}=i\right\}},$$

which, taking expectations and reasoning as in (8.8), leads to

$$\Delta_{\mu}^{\Phi} L(w)=\hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} L(w)-2 \hat{\mu}\left(\mathcal{O}_w\right) .$$

We now turn to the proof of the right inequality of (8.9). Denote

$$\mathcal{P}_w=\left\{i \in \mathcal{V}_1:|w|_i>0\right\} .$$

Fix also $n \in \mathbb{N}$, and denote by \check{V}_n , the class of the incoming item at time n in the $(\check{G}, \check{\Phi}, \mu)$ system. First, similarly to (8.3) and (8.4) we clearly get that

$$\begin{aligned} & \mathbb{E}\left[\left(L\left(\check{W}_{n+1}\right)-L\left(\check{W}_n\right)\right) \mathbb{1}_{\left\{\check{V}_{n+1} \in \mathcal{V}_2 \cup\left(\mathcal{V}_1 \cap\left(\mathcal{P}_w\right)^c\right)\right\}} \mid \check{W}_n=w\right] \\ & =\mathbb{E}\left[\left(L\left(\hat{W}_{n+1}\right)-L\left(\hat{W}_n\right)\right) \mathbb{1}_{\left\{\hat{V}_{n+1} \in \mathcal{V}_2 \cup\left(\mathcal{V}_1 \cap\left(\mathcal{P}_w\right)^c \cup\left(\mathcal{V}_1 \cap\left(\mathcal{P}_w\right)^c\right)\right)\right\}} \mid \hat{W}_n=w\right] . \end{aligned} \quad (8.10)$$

Now, we also clearly have that

$$\begin{aligned} \mathbb{E} \left[(L(\check{W}_{n+1}) - L(\check{W}_n)) \mathbb{1}_{\{\check{V}_{n+1} \in \mathcal{P}_w\}} \mid \check{W}_n = w \right] &= \mu(\mathcal{P}_w); \\ \mathbb{E} \left[(L(\hat{W}_{n+1}) - L(\hat{W}_n)) \mathbb{1}_{\{\hat{V}_{n+1} \in \mathcal{P}_w\}} \mid \hat{W}_n = w \right] &= \hat{\mu}(\mathcal{P}_w); \\ \mathbb{E} \left[(L(\hat{W}_{n+1}) - L(\hat{W}_n)) \mathbb{1}_{\{\hat{V}_{n+1} \in \underline{\mathcal{P}}_w\}} \mid \hat{W}_n = w \right] &= -\hat{\mu}(\underline{\mathcal{P}}_w), \end{aligned}$$

which, together with (8.10), implies that

$$\hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} L(w) = \check{\Delta}_{\mu}^{\check{\Phi}} L(w) - 2\hat{\mu}(\underline{\mathcal{P}}_w).$$

□

8.2. *Proofs of the remaining main results.* We are now in position to prove Theorem 4.7, Theorem 4.9 and Proposition 4.12. Let us first observe the following result,

Lemma 8.4. *For any $\mu \in \mathcal{M}(\mathcal{V})$ we have that*

$$\mu \in \text{NCOND}(G) \iff \hat{\mu}_{1/2} \in \text{NCOND}(\hat{G}),$$

where $\hat{\mu}_{1/2}$ is the extended measure of μ such that

$$\hat{\mu}_{1/2}(i) = \hat{\mu}_{1/2}(\underline{i}) = \frac{1}{2}\mu(i) \quad \text{for all } i \in \mathcal{V}_1.$$

Proof: Let us first observe that

$$\text{For any } A \subset \mathcal{V}, \quad \mu(\mathcal{E}(A)) = \hat{\mu}_{1/2}(\hat{\mathcal{E}}(A)). \tag{8.11}$$

Indeed we have that

$$\begin{aligned} \mu(\mathcal{E}(A)) &= \mu(\mathcal{E}(A) \cap \mathcal{V}_2) + \mu(\mathcal{E}(A) \cap \mathcal{V}_1) \\ &= \hat{\mu}_{1/2}(\mathcal{E}(A) \cap \mathcal{V}_2) + \hat{\mu}_{1/2}(\mathcal{E}(A) \cap \mathcal{V}_1) + \hat{\mu}_{1/2}(\underline{\mathcal{E}(A) \cap \mathcal{V}_1}) \\ &= \hat{\mu}_{1/2} \left((\mathcal{E}(A) \cap \mathcal{V}_2) \cup (\mathcal{E}(A) \cap \mathcal{V}_1) \cup (\underline{\mathcal{E}(A) \cap \mathcal{V}_1}) \right) = \hat{\mu}_{1/2}(\hat{\mathcal{E}}(A)). \end{aligned}$$

⇐: Let $\hat{\mu}_{1/2} \in \text{NCOND}(\hat{G})$ and $\mathcal{I} \in \mathbb{I}(G)$. As $\mathcal{I} \subset \mathcal{V}_2$ and in view of (8.11), we get that

$$\mu(\mathcal{I}) = \hat{\mu}_{1/2}(\mathcal{I}) < \hat{\mu}_{1/2}(\hat{\mathcal{E}}(\mathcal{I})) = \mu(\mathcal{E}(\mathcal{I})).$$

⇒: Let us now fix $\mu \in \text{NCOND}(G)$ and $\hat{\mathcal{I}} \in \mathbb{I}(\hat{G})$. We reason by induction on the number of elements of $\hat{\mathcal{I}}$ that belong to $\mathcal{V}_1 \cup \underline{\mathcal{V}}_1$. First, observe that if $\hat{\mathcal{I}} \subset \mathcal{V}_2$, then $\hat{\mathcal{I}}$ is also an element of $\mathbb{I}(G)$. Thus, as $\mu \in \text{NCOND}(G)$ and in view of (8.11) we get that

$$\hat{\mu}_{1/2}(\hat{\mathcal{I}}) = \mu(\hat{\mathcal{I}}) < \mu(\mathcal{E}(\hat{\mathcal{I}})) = \hat{\mu}_{1/2}(\hat{\mathcal{E}}(\hat{\mathcal{I}})).$$

Second, assume that for a given $\hat{\mathcal{I}} \in \mathbb{I}(\hat{G})$, we have $\hat{\mu}_{1/2}(\hat{\mathcal{I}}) < \hat{\mu}_{1/2}(\mathcal{E}(\hat{\mathcal{I}}))$, and let $u \in \mathcal{V}_1 \cup \underline{\mathcal{V}}_1$ be such that $u \notin \hat{\mathcal{I}}$ and $\hat{\mathcal{I}} \cup \{u\} \in \mathbb{I}(\hat{G})$. Then, we have $u \notin \hat{\mathcal{E}}(\hat{\mathcal{I}})$, and thus also $\underline{u} \notin \hat{\mathcal{E}}(\hat{\mathcal{I}})$. Since $\underline{u} \in \hat{\mathcal{E}}(\hat{\mathcal{I}} \cup \{u\})$, it follows that

$$\begin{aligned} \hat{\mu}_{1/2}(\hat{\mathcal{E}}(\hat{\mathcal{I}} \cup \{u\})) &\geq \hat{\mu}_{1/2}(\hat{\mathcal{E}}(\hat{\mathcal{I}})) + \hat{\mu}_{1/2}(\underline{u}) = \hat{\mu}_{1/2}(\hat{\mathcal{E}}(\hat{\mathcal{I}})) + \hat{\mu}_{1/2}(u) \\ &> \hat{\mu}_{1/2}(\hat{\mathcal{I}}) + \hat{\mu}_{1/2}(u) = \hat{\mu}_{1/2}(\hat{\mathcal{I}} \cup \{u\}), \end{aligned}$$

and we conclude by induction. □

Proof of Theorem 4.7: Let $\mu \in \text{NCOND}(G)$. From Lemma 8.4, the measure $\hat{\mu}_{1/2}$ belongs to $\text{NCOND}(\hat{G})$. Let Φ be a matching policy of the Max-Weight class on G , with $\beta > 0$. Clearly, its extension $\hat{\Phi}$ is also of the Max-Weight class on \hat{G} . Then, we know from Theorem 3.2 in Jonckheere et al. (2020) that the model $(\hat{G}, \hat{\Phi}, \hat{\mu}_{1/2})$ is stable. In particular, we see in the proof of Theorem 3.2 in Jonckheere et al. (2020) that the Foster-Lyapunov Theorem (Brémaud, 2020, Theorem 5.1) can be applied to the chain $\{\hat{W}_n\}_{n \in \mathbb{N}}$ for the quadratic function Q . Specifically, there exist $\eta > 0$ and a finite set $\hat{\mathcal{K}} \subset \hat{\mathbb{W}}$ such that $\hat{\Delta}_{\hat{\mu}}^{\hat{\Phi}} Q(\hat{w}) < -\eta$ for all $\hat{w} \notin \hat{\mathcal{K}}$. Thus, in view of Proposition 8.1, we have that $\Delta_{\mu}^{\Phi} Q(w) < -\eta$ for any w that lies outside the finite subset $\mathcal{K} = \hat{\mathcal{K}} \cap \mathbb{W}$. We conclude by applying the Foster-Lyapunov Theorem to the mapping Q and the compact set \mathcal{K} . \square

Proof of Theorem 4.9: (i) Fix $\mu \in \text{NCOND}(G)$. First, if G is a graph ($\mathcal{V}_1 = \emptyset$) and $G = \check{G}$ is p -partite complete for $p \geq 3$, then the result follows from Theorem 2, Assertion (16) in Mairesse and Moyal (2016): specifically, we have that for some $\eta > 0$, for any $w \in \mathbb{W} \setminus \{\varepsilon\}$,

$$\Delta_{\mu}^{\Phi} L(w) < -\eta, \tag{8.12}$$

and the Foster-Lyapunov criterion applies. Now, if G is not a graph, i.e. $\mathcal{V}_1 \neq \emptyset$, then let

$$\delta = \min \{ \mu(\mathcal{E}(\mathcal{I})) - \mu(\mathcal{I}) : \mathcal{I} \in \mathbb{I}(G) \},$$

which is strictly positive since $\mu \in \text{NCOND}(G)$, and the mapping

$$L_{\delta} : \begin{cases} \mathbb{W} & \rightarrow \mathbb{R}+ \\ w & \mapsto \sum_{i \in \mathcal{V}_1} \frac{\delta}{2\mu(\mathcal{V}_1)} |w|_i + \sum_{i \in \mathcal{V}_2} |w|_i. \end{cases}$$

Then, for any $w \in \mathbb{W}$ the set $\mathcal{I}^w = \{i \in \mathcal{V} : |w|_i > 0\}$ is an independent set of \check{G} , so by the very definition of a complete p -partite graph, there exists a unique maximal independent set $\check{\mathcal{I}}$ of \check{G} such that $\mathcal{I}^w \subset \check{\mathcal{I}}$. Then, for all $w \in \mathbb{W}$ such that $\mathcal{I}^w \cap \mathcal{V}_2 \neq \emptyset$, for any n , if $\{W_n = w\}$ the Markov chain can make two types of moves upon the arrival of V_{n+1} :

- either one coordinate of W_n decreases from 1 if V_{n+1} is of a class in $\check{\mathcal{I}}^c = \check{\mathcal{E}}(\check{\mathcal{I}})$, or of a class in $\mathcal{I}^w \cap \mathcal{V}_1$;
- or one coordinate of W_n increases from 1, if V_{n+1} is of a class in $\check{\mathcal{I}} \cap ((\mathcal{I}^w)^c \cup \mathcal{V}_2)$.

Therefore, for any \mathcal{V}_2 -favorable matching policy Φ we have that

$$\begin{aligned} \Delta_{\mu}^{\Phi} L_{\delta}(w) &= -\frac{\delta}{2\mu(\mathcal{V}_1)} \mu(\mathcal{V}_1 \cap \mathcal{I}^w) \mathbb{1}_{\{\mathcal{V}_1 \cap \mathcal{I}^w \neq \emptyset\}} + \frac{\delta}{2\mu(\mathcal{V}_1)} \mu(\mathcal{V}_1 \cap \check{\mathcal{I}} \cap (\mathcal{I}^w)^c) + \mu(\check{\mathcal{I}} \cap \mathcal{V}_2) - \mu(\check{\mathcal{I}}^c). \end{aligned} \tag{8.13}$$

Observe that $\check{\mathcal{I}} \cap \mathcal{V}_2$ is an independent set of G , and that $\check{\mathcal{I}}^c = \mathcal{E}(\check{\mathcal{I}} \cap \mathcal{V}_2)$. Hence (8.13) implies that

$$\Delta_{\mu}^{\Phi} L_{\delta}(w) \leq \frac{\delta}{2\mu(\mathcal{V}_1)} \mu(\mathcal{V}_1 \cap \check{\mathcal{I}} \cap (\mathcal{I}^w)^c) + \mu(\check{\mathcal{I}} \cap \mathcal{V}_2) - \mu(\mathcal{E}(\check{\mathcal{I}} \cap \mathcal{V}_2)) \leq \frac{\delta}{2} - \delta = -\frac{\delta}{2}.$$

As this is true for any w outside the finite set $\{w \in \mathbb{W} : \mathcal{I}^w \cap \mathcal{V}_2 = \emptyset\}$, we conclude again using the Lyapunov-Foster Theorem that $\text{STAB}(G, \Phi) = \text{NCOND}(G)$.

(ii) Fix $\mu \in \text{NCOND}(\check{G})$, and an admissible matching policy Φ . Applying (8.12) to \check{G} , we obtain that for any $\check{\Phi}$ that reduces Φ , for some $\eta > 0$ we have $\check{\Delta}_{\mu}^{\check{\Phi}} L(\check{w}) < -\eta$ for all $\check{w} \in \check{\mathbb{W}} \setminus \{\varepsilon\}$. Combining this with (8.9), and recalling that $\mathbb{W} \subset \check{\mathbb{W}}$ we obtain that $\Delta_{\mu}^{\Phi} L(w) < -\eta$ for all $w \in \mathbb{W} \setminus \{\varepsilon\}$, which concludes the proof. \square

Proof of Proposition 4.12: (i) Remark that for any $\hat{w} \in \hat{\mathbb{W}}$, the set $\{i \in \mathcal{V} : |\hat{w}|_i > 0\}$ is again an independent set of \hat{G} . So we can apply, for any $\hat{\mu} \in \text{NCOND}(\hat{G})$, the exact same argument as for assertion (i) in Theorem 4.9, by replacing \mathcal{V}_1 by $\mathcal{V}_1 \cup \underline{\mathcal{V}}_1$.

(ii) Let $\hat{\mu}$ be an element of $\mathcal{M}(\hat{\mathcal{V}})$ whose reduced measure μ belongs to $\text{NCOND}(\hat{G})$. Let $\hat{\Phi}$ be an admissible policy on $\hat{\mathcal{V}}$, Φ be a policy on \mathcal{V} such that $\hat{\Phi}$ extends Φ , and $\check{\Phi}$ be a policy reducing Φ on \check{G} .

First, as in (8.12) there exists $\eta > 0$ such that $\check{\Delta}_{\mu}^{\check{\Phi}} L(w) < -\eta$ for any $w \in \mathbb{W} \setminus \{\varepsilon\}$.

Fix \hat{w} in $\hat{\mathbb{W}} \setminus \{\varepsilon\}$. Then define the permutation γ of $\hat{\mathcal{V}}$ by

$$\begin{cases} \gamma(i) = \underline{i} \text{ and } \gamma(\underline{i}) = i \text{ if } |\hat{w}|_{\underline{i}} > 0 \text{ and } |\hat{w}|_i = 0, i \in \mathcal{V}_1, \\ \gamma(j) = j \text{ else, for any } j \in \hat{\mathcal{V}}. \end{cases}$$

Let us also denote by $\gamma(\hat{w})$, the word obtained from \hat{w} by replacing the letters of \hat{w} by their image through γ , in other words for all $i \in \llbracket 1, |\hat{w}| \rrbracket$, $\gamma(\hat{w})_i = \gamma(\hat{w}_i)$. Observe that $\gamma(\hat{w})$ is clearly an element of $\mathbb{W} \setminus \{\varepsilon\}$, so in view of the above observation we have that

$$\check{\Delta}_{\mu}^{\check{\Phi}} L(\gamma(\hat{w})) < -\eta. \quad (8.14)$$

Now, as i and \underline{i} have the same connectivity in \hat{G} for any $i \in \mathcal{V}_1$, for all n the conditional distribution of \hat{W}_{n+1} given $\{\hat{W}_n = \hat{w}\}$ in the $(\hat{G}, \hat{\Phi}, \hat{\mu})$ system equals that of \hat{W}_{n+1} given $\{\hat{W}_n = \gamma(\hat{w})\}$ in the $(\hat{G}, \hat{\Phi}, \hat{\mu} \circ \gamma)$ system. In particular, we have that

$$\Delta_{\hat{\mu}}^{\hat{\Phi}}(\hat{w}) = \Delta_{\hat{\mu} \circ \gamma}^{\hat{\Phi}}(\gamma(\hat{w})). \quad (8.15)$$

On the other hand, as $\gamma(\hat{w})$ is an element of \mathbb{W} and the measure $\hat{\mu} \circ \gamma \in \mathcal{M}(\hat{\mathcal{V}})$ clearly extends the measure μ , the right inequality of (8.9) implies that

$$\hat{\Delta}_{\hat{\mu} \circ \gamma}^{\hat{\Phi}} L(\gamma(\hat{w})) \leq \check{\Delta}_{\mu}^{\check{\Phi}} L(\gamma(\hat{w})),$$

and it follows from (8.14-8.15) that $\Delta_{\hat{\mu}}^{\hat{\Phi}}(\hat{w}) < -\eta$. As this is true for any \hat{w} in $\hat{\mathbb{W}} \setminus \{\varepsilon\}$, the proof is complete. \square

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